Changes for the Better
MELSEC iQ-R Series
iQ Platform-compatible PAC

## e.fectory

## MELSEC iQ-R

## Bridging the next generation of automation

# GLOBAL IMPACT OF MITSUBISHI ELECTRIC 



Through Mitsubishi Electric's vision, "Changes for the Better" are possible for a brighter future

## Changes for the Better

We bring together the best minds to create the best technologies. At Mitsubishi Electric, we understand that technology is the driving force of change in our lives. By bringing greater comfort to daily life, maximizing the efficiency of businesses and keeping things running across society, we integrate technology and innovation to bring changes for the better.

Mitsubishi Electric is involved in many areas including the following

## Energy and Electric Systems

A wide range of power and electrical products from generators to large-scale displays.

## Electronic Devices

A wide portfolio of cutting-edge semiconductor devices for systems and products.

## Home Appliance

Dependable consumer products like air conditioners and home entertainment systems.

## Information and Communication Systems

Commercial and consumer-centric equipment, products and systems.

## Industrial Automation Systems

Maximizing productivity and efficiency with cutting-edge automation technology.

## iQ Platform for maximum return on investment

Minimize TCO, Seamless integration, Maximize productivity, Transparent communications: these are common items that highlight the benefits of the iQ Platform and e-F@ctory. The iQ Platform minimizes TCO at all phases of the automation life cycle by improving development times, enhancing productivity, reducing maintenance costs, and making information more easily accessible across the plant. Together with e-F@ctory, offering various best-in-class solutions through its e-F @ ctory alliance program, the capabilities of the manufacturing enterprise is enhanced even further realizing the next level for future intelligent manufacturing plants.

ERP (Enterprise resource planning)


## Further reduce TCO while securing your manufacturing assets

## Automation Controller

Improve productivity and product quality

1. High-speed system bus realizing improved system performance
2. On-screen multi-touch control enabling smooth GOT (HMI) operations

## Integrated Network

Best-in-class integrated network optimizing production capabilities

1. CC-Link IE supporting 1 Gbps high-speed communication
2. Seamless connectivity within all levels of manufacturing with SLMP

## Centralized Engineering

Integrated engineering environment with system level features

1. Automatic generation of system configuration
2. Share parameters across multiple engineering software via MELSOFT Navigator
3. Changes to system labels are reflected between PAC and HMI


# Revolutionary, next-generation controllers building a new era in automation MELSEC iQ-R 

## As the core for next-generation automation environment, realizing an automation controller with added value while reducing TCO*


#### Abstract

To succeed in highly competitive markets, it's important to build automation systems that ensure high productivity and consistent product quality. The MELSEC iQ-R Series has been developed from the ground up based on common problems faced by customers and rationalizing them into seven key areas: Productivity, Engineering, Maintenance, Quality, Connectivity, Security and Compatibility. Mitsubishi Electric is taking a three-point approach to solving these problems: Reducing TCO*, increasing Reliability and Reusability of existing assets.


As a bridge to the next generation in automation, the MELSEC iQ-R Series is a driving force behind revolutionary progress in the future of manufacturing.
*TCO: Total cost of ownership

## Process



High availability process control in a scalable automation solution

- Extensive visualization and data acquisition
- High availability across multiple levels
- Integrated process control software simplifies engineering


## Safety

## System design flexibility with integrated safety control

- Integrated generic and safety control
- Consolidated network topology
- Complies with international safety standards


## Productivity



## Improve productivity through

 advanced performance/ functionality- New high-speed system bus realizing shorter production cycle
- Super-high-accuracy motion control utilizing advanced multiple CPU features
- Inter-modular synchronization resulting in increased processing accuracy


## Engineering

Reducing development costs through intuitive engineering

- Intuitive engineering environment covering the product development cycle
- Simple point-and-click programming architecture
- Understanding globalization by multiple language support


## Maintenance

$\times$

## Reduce maintenance costs and downtime utilizing easier maintenance features

- Visualize entire plant data in real-time
- Extensive preventative maintenance functions embedded into modules


## Quality



## Reliable and trusted MELSEC product quality

- Robust design ideal for harsh industrial environments
- Improve and maintain actual manufacturing quality
- Conforms to main international standards

Mitsubishi Electric PAC MELSEC iQ-R "Promotion" Movie

## Intelligence

HAN.
Extensive data handling from shop
floor to business process systems
Revolutionary

Reusability

- Direct data collection and analysis
- C/C++ based programming
- Collect factory data in real-time
- Expand features using third party partner applications


## Connectivity



## Seamless network reduces system costs

- Seamless connectivity within all levels of manufacturing
- High-speed and large data bandwidth ideal for large-scale control systems
- Easy connection of third-party components utilizing device library


## Security

- Protect intellectual property
- Unauthorized access protection across distributed control


## Robust security that can be relied on

$\square$
network

## Compatibility

##  <br> Extensive compatibility with existing products

- Utilize existing assets while taking advantage of cutting-edge technology
- Compatible with most existing MELSEC-Q Series I/O


## Process <br> High-available process control in a scalable automation solution

MELSEC iQ-R Series process CPU modules are designed to cover wide-ranging process control applications, from small- to large-scale. All models provide high-speed performance coupled with the ability to handle large PID loops utilizing embedded PID control algorithms; integrating both general and process control into one module. When paired with a redundant function module, a redundant control system ideal for applications that require highly reliable control can be easily realized at a low cost.

Redundant power supply module


## Remote station

Redundant remote network head module

- Enables continuous data communications by switching




## Extensive visualization and data acquisition

## SCADA

Mitsubishi SCADA MC Works64*1 is a next generation supervisory control and data acquisition (SCADA) software providing extensive visualization with its enhanced interconnectivity with the MELSEC iQ-R Series. Advanced features such as energy management, scheduling, alarm and event management, trending, reporting, historian, and Geo-SCADA monitoring realize intuitive factory-wide control.

## Embedded PID algorithms

## PID control



The process CPU includes dedicated algorithms such as two-degree-of-freedom PID, sample PI, and auto-tuning support advanced process control.

## Extension base unit

- Supports Q Series modules(RQ extension base)


# GXWarks3 

One Software, Many Possibilities
Future Support


## Multi-level redundancy ensuring continuous control

## High availability

Highly reliable control systems can be easily realized minimizing the possibility of single-point failure at the visualization (SCADA), control, and network levels, thereby avoiding system downtime and ensuring continuous control and operation of critical systems.

MC Works64 redundant Ethernet connection will be supported in the future.
*2. Process features such as process tag and faceplate will be supported in the future.


## One package process control software

## Integrated engineering

GX Works3 ${ }^{\star 2}$, the standard integrated engineering software for the MELSEC iQ-R Series, makes programming redundant process control systems relatively easy. The program editor uses function block diagram (FBD) language for process control and simplifies system configuration with its intuitive features such as process tag label (variables) sharing, simple program structure, and easy project upload/download to the process CPU.

## 単 <br> Safety

## Integrated safety control offering a total system solution


manufacturing plants and requires stringent safety regulations. To adhere to this safety code for control systems, the MELSEC iQ-R Series is equipped with a safety CPU that is compliant with international safety standards, enabling safety devices to be connected via the CC-Link IE Field network. The entire system can be programmed using GX Works3 programming software as standard.


The Safety CPU is compliant with ISO 13849-1 PL e and IEC 61508 SIL 3 and is certified by TÜV Rheinland ${ }^{\circledR}$.


Mitsubishi Electric PAC MELSEC iQ-R "Intelligence" Movie

With ever-changing manufacturing trends, production data management, analysis, and planning are more mainstream helping to realize leaner operations, improve yield, and create a more efficient supply chain. The MELSEC iQ-R Series includes the MES Interface, C Controller and C Intelligent function, and High-speed data logger modules as part of the "Intelligence" lineup of interconnected advanced information products.


Based on the ARM ${ }^{\circledR}$ dual-core Cortex A9 processor, the real-time OS VxWorks ${ }^{\circledR} \mathrm{C}$ Controller CPU is ideal for high-end analytical requirements where raw data has to be processed, such as for in-line manufacturing quality testing. The $C$ Intelligent Function Module, based on the same processor, is a versatile programmable module that can be used for installing industryspecific communications protocols; for example, plant-wide monitoring of wind power generation farms, building automation and industrial open fieldbus networks.
 High-speed production data collection
Data logging
Enables high-speed data logging that can be synchronized with the controller scan time, as an alternative to a dedicated logging client computer. Includes features such as triggering and reporting that improve troubleshooting of the manufacturing process.

\section*{CIㅔ팝II | Direct access to IT system |
| :--- |
| database servers |
| Information connection |}

Improve production management and recipe data handling via real-time direct access to IT system database servers such as Oracle ${ }^{\circledR}$ and Microsoft ${ }^{\oplus}$ (SQL Server ${ }^{\circledR}$, Access ${ }^{\circledR}$ ). Overall system cost is also reduced as additional programming, which can increase engineering time, and gateway computers are no longer required.

## 为 <br> Productivity

## Improve productivity through advanced performance/functionality

Integrating high-performance capabilities based on the high-end iQ-R system bus, high-speed network, and an advanced motion control system; applications requiring these characteristics can be easily realized using the MELSEC iQ-R Series as the core of the automation system.


## New high-speed system bus realizes improved production cycle

The newly developed high-speed system bus is 40 -times faster compared to existing models, realizing very fast and large-capacity data processing between modules (network, I/O, multi-CPU, etc.), enabling the optimum utilization of MELSEC iQ-R Series performance and functionality.

## Multi-CPU system realizes very accurate motion control

By supporting synchronized data communications between the programmable controller CPU and motion CPU via the high-speed system bus, performance is improved by up to four times compared to existing models, easily realizing super-high motion control accuracy.

## Inter-modular synchronization realizes increased processing accuracy

## More flexible control over performance

Realizing high processing accuracy could not be any simpler when utilizing the inter-modular synchronization feature, which enables precise data synchronization between controller CPUs and various interface modules via the high-speed system bus (backplane). In addition, network level synchronization
(both CC-Link IE Field and SSCNET III/H) is now possible, realizing deterministic performance by ensuring synchronization between nodes without being influenced by varying network transmission delays.

## New controller performance architecture further reduces H/W costs

## High-speed processing of structured programs

The processing performance of the controller CPU has been substantially enhanced thanks to the newly designed CPU engine. The memory consumption for program and internal devices used in function block (FB) and structured text (ST) programs have been improved. This results in one CPU being able to do the job that used to require several CPUs in order to achieve the expected performance level and memory capacity.

## Built-in database eliminates the need for a PC-based database server

Recipe data and production results data, previously managed using a database server, can now be managed via the database in the programmable controller. Use of dedicated commands for the built-in database makes it easy to search, add and update data on the fly.
Furthermore, the import/export correlation with spreadsheet software is made easier.

Realize high-speed system performance

Approx. $\mathbf{8 X}$ faster than QCPU*3

Data management realized with built-in database


- Realizes high-speed control performance
- Inherits MELSEC-Q Series functions
- Large-capacity memory ideal for large-scale control


- Easy to switch between recipes
- Realize product batch control
- Efficiently switch between systems


[^0]
## Reducing development costs through intuitive engineering

The engineering software is sometimes considered a fundamental part of the control system in addition to the hardware components. The core of the system, it includes various steps of the product life cycle, from the design stage all the way to commissioning and maintenance of the control system. Today, intuitive, easy-to-use software suites are expected as a standard for modern manufacturing needs. GX Works3 is the latest generation of programming and maintenance software offered by Mitsubishi Electric specifically designed for the MELSEC iQ-R Series control system. It includes many new features and technologies to ensure a trouble-free engineering environment solution.

# Intuitive engineering software covering the product development cycle 

> Graphic-based configuration realizing easier programming
> Various intuitive features such as graphic-based system configuration and an extensive module library (module label/FB) provided as standard.

Integrated motion-control system configuration

From setting simple motion module parameters and positioning data setup to servo amplifier configuration, everything is packaged into an easy-to-use engineering environment.

## Simple point and click programming architecture

## System design

## Straightforward graphic based system configuration design

- Simply drag and drop from the module list to easily create system configuration
- Directly setup parameters for each module
- Automatically reflect changes in the layout to the module parameters
System design Programming Debug/maintenance
MELSOFT library enables efficient programming through
"Module Label/FB"
- Assign convenient label names to internal devices, rather than manually
entering a device name every time
- Simply drag \& drop module FBs from the MELSOFT Library directly into the
ladder program, making programming even easier


## System design Programming Debug/maintenance

## Extensive version control features

- Flexibly register program change (historical) save points
- Easily visualize and confirm program changes


## Conforms to IEC 61131-3

GX Works3 realizes structured programming such as ladder and ST, making project standardization across multiple users even easier.

## Simple motion setting tool

Easily configure the simple motion module with this convenient integrated tool.

## Tab view multiple editors

Conveniently work on multiple editors without having to switch between software screens.

## Navigation window

Easily access project components
Organize program file list.

## Module configuration

Easily parameterize each module directly from the configuration editor.

## Module list

Simply drag \& drop modules directly into the module configuration.

# MELSEC iQ-R 

Mitsubishi Electric PAC MELSEC iQ-R
"Engineering" Movie

# GXWarks 

## One Software, Many Possibilities

## Reduce engineering time by 60\%*1



## Global realization by multi-language support

To adhere to today's global production needs, GX Works3 supports multi-language features at various levels, from the multiple language software menu system to device comment language

## Reduce maintenance costs and downtime <br> utilizing easier maintenance features

A manufacturing plant is seldom stopped or taken offline and continuously produces the desired product or component. However, the control system occasionally requires maintenance; for example, at the time of a faulty product or system upgrade for manufacturing a new or updated component. At that time, thanks to the extensive maintenance functions embedded in the hardware and software, the user can trust the control system to handle transition into/out of the maintenance period for both preventive and post maintenance.



Preventive maintenance CPU module

## Visualize manufacturing data in real-time

- Monitor live manufacturing process data across the plant
- Very easy setup using the dedicated GX LogViewer monitoring tool


Real-time monitor

# MELSEC iQ-R 



Mitsubishi Electric PAC MELSEC iQ-R "Maintenance" Movie

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The MSEC IQ-R Series is a unique control system equipped with innumerable functions. It works to ensure that the "down-time" of the system is kept to a minimum, which improves productivity and helps to maintain the efficiency of the overall plant.

## Corrective

maintenance CPU module

## Efficient diagnostics with extensive event logging

- Logging of program change events, errors and when the power is turned off
- Event logging displayed in list form
- Quickly detect problems due to operating mistakes by multiple users



## Corrective maintenance <br> Quickly find network errors <br> 中 GX Works3

- Visualize error location from network system image
- Easy network error corrective measures


Corrective
maintenance
GX Works3

## Multi-language software improves global support

- Comment/label names can be registered in multiple languages
- Easy to switch between languages
- No need for multiple programs to satisfy regional requirements

$\square$ Corrective GX Works3


## Simple troubleshooting, even for novice users

- Start diagnostics screen on GX Works3 just by connecting via USB
- Display detailed error information and corrective procedures



## Quality

## Reliable and trusted

## MELSEC product quality

The MELSEC iQ-R Series is based on two fundamental aspects of quality.
"Quality of product"
"Quality for application"
These two characteristics are part of the main principle behind the MELSEC iQ-R Series. This new control system includes various features designed-in to provide a solution that not only improves the overall manufacturing productivity, but also maintains a high level of industrial quality that is ideal for the harsh and rugged environments that it is subjected to on a daily basis.


## Robust design ideal for harsh industrial environments

Synonymous with the Mitsubishi Electric name, the MELSEC
iQ-R Series is designed with high quality and reliability, which is a prerequisite for industrial applications. In addition, the overall aesthetics and usability enable easier maintenance that customers routinely expect.

## Classification according to IEC 60721-3-3 Class 3C2

For protection against aggressive atmosphere and gases, products with a conformal coating (IEC 60721-3-3 Class 3C2) are available on request ${ }^{\star 1}$

[^1] representative for further details.

1. Conforms to stringent quality evaluations and tests that are based on robust industrial environments including EMC, LSI, temperature, vibration and HALT tests.
2. High manufacturing quality control through QR code based quality management system.
3. The front face has a wide and open design with an easy-to-use front cover.
4. High-quality CPU module manufacturing with in-line high-low temperature testing.
5. The base rack design includes a dedicated earth rail to prevent noise interference in low power supply conditions and a robust structure that enables easy installation without extensive damage to bus connectors.

## Conforms to main international quality standards

The MELSEC iQ-R Series conforms to most of the main international standards that realizes applications requiring multiple global locations.

## c (1). C



## Improve and maintain actual manufacturing quality

## Maintains product quality during manufacturing

With inter-module synchronization, it is now possible to precisely synchronize interrupt programs with the network communications cycle (link scan).
6. Graph showing the signal synchronization between several modules.
7. Data required for traceability is collected on the SD memory card.
8. Collected data is analyzed using a dedicated viewer.

Any variations in data transmission response time (network transmission
delay time) between the controller and other devices on the network are eliminated, realizing high integrity between manufacturing processes that are dependent on each other, ensuring high performance and processing.

## Realizes traceability through data logging

Simple settings enable the collection of production data needed for traceability. Furthermore, collected data can be analyzed easily using a dedicated viewer. Analyzing various data on production processes provides an indicator for quality improvements and manufacturing cost reductions, thereby supporting optimization of the production system.

## Connectivity

## Seamless network reduces

## system costs

The MELSEC iQ-R Series is part of a family of products all interconnected across various levels of automation. Based on the seamless message protocol (SLMP*1), data flows transparently between the sensor level and the management level across multiple industry-standard automation networks. CC-Link IE, Asia's No. 1 industrial network, realizes fast gigabit data transmission speeds, further optimizing the manufacturing cycle. In addition, the SSCNET 3/H high-speed motion control network further enhance the factory-wide connectivity solution.


CC-Link IE embedded CPU


CC-Link IE Field Network compatible Simple Motion module

## Cost-saving integrated network CPU module

The MELSEC iQ-R Series includes a lineup of CPUs with embedded industrial network connection ports (CC-Link IE and Ethernet). System costs can be further reduced by approximately $50 \%$ using the embedded network CPU module, which realizes the same features as a generic network interface module.

## Integrate motion control into one network

The CC-Link IE Field Network compatible Simple Motion module can be used as a master station*3 on the network. System configuration cost can be reduced as only one module is required for both Motion control and network connectivity.

[^2]


## High-speed and large bandwidth ideal for large-scale control systems

The Ethernet-based open network CC-Link IE is an industry-leading 1 Gbps high-speed, large-capacity network. The division of 1 Gbps broadband into uses for distributed control and field data communications secures the reliability of control communications and realizes real-time data collection, which can be difficult with standard Ethernet.

## CC-Link IE Control (twisted-pair cable)

Utilizing a system architecture that has no constraints and enables one to choose freely such as star/line/ring topologies, adding and removing equipment is easier. Moreover, compatibility with standard twisted-pair cabling means that wiring costs can be reduced.

## Connect to two different types of networks with the same module

Ethernet and CC-Link IE network communications can be realized with the same network module. Since multiple network types can use one module, equipment costs can be further reduced.

## ? Security

## Robust security that can be relied on

As technology becomes more complex and the distribution of manufacturing systems more global, the protection of intellectual property is even more significant. When shipping a finished product overseas, the last thing an OEM needs to consider is unauthorized copying or changing of the original project data. In addition to this, unauthorized access to the control system can have very serious implications to the control system and the end user, which can compromise the overall safety of the plant.

The MELSEC iQ-R Series has a number of embedded features that help to maintain these requirements, such as hardware and software keys to protect intellectual property, and multi-level user access password hierarchy to protect the project at the design stage.


Mitsubishi Electric PAC MELSEC iQ-R "Security" Movie

## Powerful security features protecting intellectual property

## Security key authentication protecting project data

The security key authentication prevents programs from being opened on personal computers where the security key has not been registered. Furthermore, because programs cannot be executed by CPU modules where the security key has not been registered, the integrity of customer technologies and other intellectual property is not compromised. The security key can also be registered on an extended SRAM cassette. Therefore, when replacing the CPU module, there is no need to re-register the security key, making replacement very simple.


Prevent unauthorized access across the network


Device with registered IP address (access permitted)

The IP filter can be used to register the IP addresses of devices permitted to access the CPU module. As a result, access from non-registered devices can be blocked, thereby lowering the risk of program hacking and unauthorized access by a third party.
Another feature is a remote password function for password-based security. Passwords of up to 32 characters can be set to prevent unauthorized access to the CPU module via networks such as Ethernet.

## (min Compatibility

## Extensive compatibility

## with existing products

Whenever introducing a new system or technology into an existing manufacturing plant or control system, utilization of existing assets as much as feasibly possible is a mandatory requirement with today's manufacturing needs. The MELSEC iQ-R Series addresses these subtle but substantial needs with various system hardware support and engineering project compatibility to achieve an easy path to higher technology and improved performance capabilities.


Mitsubishi Electric PAC MELSEC iQ-R "Compatibility" Movie

## Utilize existing MELSEC-Q Series assets

## Current programs can be fully utilized

A simply conversion process*1 is all it takes to enable the use of MELSEC-Q Series programs with the MELSEC iQ-R Series. Customers can effectively use the program assets they have accumulated, thereby reducing the overall engineering time.
*1: For detailed information about converting to Gx Works 3 programs,
please refer to the " $G X$ Works 3 Operating Manual".


## Possible to divert external device wiring

The MELSEC iQ-R Series I/O module, analog module, and counter module pin layouts and connectors are the same as those of the MELSEC-Q Series. Accordingly, existing external device wiring (connectors, terminal blocks) can be diverted without changes and wiring costs can be reduced.


## Variety of compatible modules

By utilizing the dedicated extension base, most MELSEC-Q Series modules*2 can be re-used. This makes it possible to introduce the high-performance MELSEC iQ-R Series while controlling the cost of supplementary equipment.
*2: For further details, please refer to the "MELSEC iQ-R Module Configuration Manual".


## Lineup

| Power supply P. 23 |  |
| :---: | :---: |
| R61P.......................................... AC input |  |
| R62P............. AC input (inc. 24 V DC output) |  |
| R64P.....................AC input (large capacity) |  |
| R64RP NEW ............... AC input (Redundant) |  |
| R63P..........................................DC input |  |
| Base | P. 23 |
| Main base |  |
| R35B.............................................. 5-slot |  |
| R38B............................................... 8-slot |  |
| R310RB NEW ................ 10-slot (Redundant) |  |
| R312B........................................... 12-slot |  |
| Extended temperature range main base |  |
| R310B-HT...................................... 10-slot |  |
| R38RB-HT NEW .............. 8-slot (Redundant) |  |
| Extension base |  |
| R65B.............................................. 5-slot |  |
| R68B............................................... 8-slot |  |
| R610RB NEW ................ 10-slot (Redundant) |  |
| R612B.............................................. 12-slot |  |
| Extended temperature range extension base |  |
| R610B-HT...................................... 10-slot |  |
| R68RB-HT NEW .............. 8-slot (Redundant) |  |
| RQ extension base (MELSEC-Q Series) |  |
| RQ65B............................................ 5-slot |  |
| RQ68B............................................ 8-slot |  |
| RQ612B........................................ 12-slot |  |
| Extension cable |  |
| RC06B ........................................... 0.6 m |  |
| RC12B ............................................ 1.2 m |  |
| RC30B .............................................. 3 m |  |
| RC50B ................................................ 5 m |  |


| CPU P. 26 | I/O P. 43 |
| :---: | :---: |
| Programmable controller CPU | AC input |
| R04(EN)CPU .............................40K steps | RX10........................................... 16-point |
| R08(EN)CPU ............................. 80 K steps | DC input |
| R16(EN)CPU ........................... 160K steps | RX40C7 ....................................... 16-point |
| R32(EN)CPU .............................320K steps | RX41C4 ......................................32-point |
| R120(EN)CPU ........................ 1200K steps | RX42C4 .......................................64-point |
| RロENCPU is equipped with CC-Link IE Control/CC-Link IE Field network ports. | DC high-speed input |
| Motion CPU | RX40PC6H ..........Positive common, 16-point |
| R16MTCPU ................................... 16-axis | RX40NC6H........ Negative common, 16-point |
| R32MTCPU .................................. 32-axis | RX41C6HS ...Positive/negative common, 32-point |
| R64MTCPU ..................................64-axis | RX61C6HS ...Positive/negative common, 32-point |
| Safety CPU | DC (with diagnostic functions) input <br> RX40NC6B $\qquad$ 16-point |
| R08SFCPU-SET........................ 80 K steps | NEW |
| R16SFCPU-SET........................ 160K steps | Relay output |
| R32SFCPU-SET.......................320K steps | RY10R2 ....................................... 16-point |
| R120SFCPU-SET....................1200K steps | Transistor (sink) output |
|  | RY40NT5P................................... 16-point |
| Process CPU | RY41NT2P $\qquad$ 32-point |
| R08PCPU ................................... 80 K steps | RY42NT2P $\qquad$ 64-point |
| R16PCPU ................................ 160K steps |  |
| R32PCPU................................320K steps | High-speed transistor (sink) output |
| R120PCPU ............................ 1200K steps | RY41NT2H ...................................32-point |
|  | Transistor (source) output |
| Redundant function module | RY40PT5P $\qquad$ 16-point |
| R6RFM NEW ..................Redundant function | RY41PT1P..................................32-point |
| C Controller | RY42PT1P ...................................64-point |
| R12CCPU-V ......... Memory capacity 256 MB | High-speed transistor (source) output <br> RY41PT2H $\qquad$ 32-point |
|  | Transistor (with diagnostic functions) output <br> RY40PT5B <br> NEW $\qquad$ 16-point |
|  | I/O combined module |
|  | DC Input, transistor (sink) output |
|  | RH42C4NT2P...................32-point/32-point |



| Analog | P. 48 |
| :---: | :---: |
| Analog input |  |
| R60AD4 ..........4-channel (voltage or current) |  |
| R60ADV8...................... 8-channel (voltage) |  |
| R60ADI8.......................8-channel (current) |  |
| High-speed Analog input <br> R60ADH4 $\qquad$ 4-channel (voltage or current) |  |
|  |  |
| Analog input (channel isolated) |  |
| R60AD8-G ...... 8-channel (voltage or current) |  |
| R60AD16-G .. 16-channel (voltage or current) |  |
| Temperature input <br> R60TD8-G $\qquad$ 8-channel (thermocouple) |  |
|  |  |
| R60RD8-G......................... 8-channel (RTD) |  |
| Temperature control |  |
| R60TCTRT2TT2......... 2-channel multi-input, 2-channel thermocouple inpu |  |
| R60TCRT4..................4-channel RTD input |  |
| R60TCTRT2TT2BW ...2-channel multi-input, 2-channel thermocouple input |  |
| R60TCRT4BW.............4-channel RTD input |  |
| Analog output |  |
| R60DA4 ..........4-channel (voltage or current) |  |
| R60DAV8...................... 8-channel (voltage) |  |
| R60DAI8 | (current) |

## Analog output (channel isolated)

R60DA8-G ...... 8-channel (voltage or current) R60DA16-G .. 16-channel (voltage or current)

## Motion, Positioning, High-speed counter P. 56

Simple motion
(Compatible with CC-Link IE Field network)
RD77GF4 ........................................... 4 -axis
RD77GF8 .............................................. 8 -axis
RD77GF16........................................... 16-axis
(Compatible with SSCNET II/H)
RD77MS2 ............................................ 2 -axis
RD77MS4 .............................................. 4 -axis
RD77MS8............................................... 8 -axis
RD77MS16 .......................................... 16 -axis
Positioning
Transistor output
RD75P2 .............................................. 2-axis
RD75P4................................................. 4-axis
Differential driver output
RD75D2.............................................. 2-axis
RD75D4................................................. 4 -axis

High-speed counter
DC input/Transistor (sink) output
RD62P2 ........................................2-channel
DC input/Transistor (source) output
RD62P2E......................................2-channel
Differential input/Transistor (sink) output
RD62D2. $\qquad$ 2-channel

## Network

## P. 62

Ethernet
\(\left.\begin{array}{l}RJ71EN71 ..................... 1 G/100 M/10 Mbps <br>
Multiple network type <br>

(Ethernet/CC-Link IE)\end{array}\right\}\)| CC-Link IE Control network |
| :--- |
| RJ71GP21-SX ......................Control/Normal |
| station optical cable |

Advanced information modules
P. 69
MES Interface
RD81MES96................ Database connection

High-speed data logger
RD81DL96............................. Data collection

C Intelligent function module
RD55UP06-V........C/C++ program execution


## Flexible, interchangeable system architecture

The MELSEC iQ-R Series is a modular control system equipped with various modules such as CPUs, power supply, digital I/O, analog I/O and base unit and intelligent function modules, each having its own responsibility in the system. The core of the system is a base unit that interconnects all of the modules together and enables high-speed communications between each module. From small to large systems, scalability is simple. Up to seven extension bases can be connected and a maximum of 64 modules installed at any one time. An RQ extension base is also available, ensuring compatibility with existing MELSEC-Q Series modules.

Multiple CPU modules
Install up to four CPU modules together

- Programmable controller CPU
- CC-Link IE embedded CPU*1
- Motion CPU
- Safety CPU*2
- Process CPU
- C Controller
*1: Multi-CPU is not supported.
*2: Product package includes a safety CPU and safety function module.


- Extension base unit
- Extended temperature range extension base unit New

An extension base strictly for I/O and intelligent function modules.


- RQ extension base unit

An extension base for MELSEC-Q Series modules (further extensions requiring the MELSEC-Q Series extension base version).


Power supply module

- Power supply module


I/O \& Intelligent function modules

- Input module
- Output module
- I/O combined module
- Analog input module
- Temperature input module
- Temperature control module
- Analog output module
- Simple motion module
- Positioning module
- High-speed counter module
- Ethernet interface module
- CC-Link IE Control Network module
- CC-Link IE Field Network master/local module
- CC-Link IE Field Network remote head module NEW
- CC-Link system master/local module
- AnyWireASLINK master module NEW
- Serial communication module
- MES interface module
- High-speed data logger module
- C intelligent function module


## Integrated safety control

The MELSEC iQ-R Series safety control system consists of a safety CPU that is compliant with international safety standards, ISO 13849-1 PL e and IEC 61508 SIL 3, and can execute both safety and general logic in the same CPU. The CPU module can be installed on a standard base unit and when paired with the safety function module enables control of safety I/O, realizing easy integration into an existing or new control system. Safety I/O such as an emergency stop switch or light curtain is controlled via CC-Link IE Field network, which is connected to the safety remote I/O module.


## Highly scalable redundant control

The MELSEC iQ-R Series redundant control system is based on a dual-system architecture where all modules on a primary (control) system are duplicated onto a secondary (standby) system with a tracking cable connecting the systems together. Both systems are equipped with a process CPU module and redundant function module, with the former being able to execute standard logic and process control. Remote I/Os are controlled via the CC-Link IE Field network, and dedicated base units for supporting redundant power-supply modules are available in either standard or extended temperature models.


Power supply modules, base units*

- Redundant power supply module NEW

- Redundant power supply main base unit NEW
- Extended temperature range redundant power supply main base unit NEW

- Redundant power supply extension base unit NEw
- Extended temperature range redundant power supply extension base unit New

*Only these base units support redundant power supply modules. Can utilize standard MELSEC iQ-R Series modules.


## Highly accurate synchronization

The MELSEC iQ-R Series system provides highly accurate synchronization between modules on the control system, which is realized through inter-modular synchronization. Additionally, use of the CC-Link IE Field Network realizes network-level synchronization, providing node-level synchronization that ensures deterministic data flow void of any influence from data transmission delays. This is ideal for applications such as "cutting and folding" inside an offset printer, which requires synchronization between the printing quality sensor, high-speed rotary cutter, folding roller and conveyor.


Power supply module

| Item | R61P | R62P | R64P | R64RP | R63P |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input power supply voltage | $\begin{aligned} & 100 \ldots 240 \text { V AC } \\ & \text { (85... } 264 \text { V AC) } \end{aligned}$ | $\begin{aligned} & 100 \ldots 240 \text { V AC } \\ & \text { (85... } 264 \text { V AC) } \end{aligned}$ | $\begin{aligned} & 100 \ldots 240 \mathrm{~V} \mathrm{AC} \\ & \text { (85... } 264 \mathrm{~V} \text { AC) } \end{aligned}$ | $\begin{aligned} & 100 \ldots . .240 \mathrm{~V} \mathrm{AC} \\ & (85 \ldots . .264 \mathrm{~V} \mathrm{AC}) \end{aligned}$ | $\begin{gathered} 24 \mathrm{~V} \text { DC } \\ (15.6 \ldots 31.2 \mathrm{~A} \mathrm{DC}) \end{gathered}$ |
| Input frequency | $50 / 60 \mathrm{~Hz} \pm 5 \%$ | $50 / 60 \mathrm{~Hz} \pm 5 \%$ | $50 / 60 \mathrm{~Hz} \pm 5 \%$ | $50 / 60 \mathrm{~Hz} \pm 5 \%$ | - |
| Max. input apparent power (VA) | 130 | 120 | 160 | 160 | - |
| Max. input power (W) | - | - | - | - | 50 |
| Rated output current (5V DC) | 6.5 A | 3.5 | 9 | 9 | 6.5 A |
| Rated output current (24 V DC) | - | 0.6 | - | - | - |
| Redundant power supply | - | - | - | $\bullet$ | - |

Main base unit (Standard, Extended temperature range)

| Item | Main base unit (Standard) |  |  |  | Extended temp. range main base unit |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | R35B | R38B | R310RB | R312B | R310B-HT | R38RB-HT |
| Number of I/O modules installed | 5 | 8 | 10 | 12 | 10 | 8 |
| DIN rail mounting adapter type | R6DIN1 | R6DIN1 | R6DIN1 | R6DIN1 | R6DIN1 | R6DIN1 |
| External dimensions (HxW x D, mm) | $101 \times 245 \times 32.5$ | $101 \times 328 \times 32.5$ | $101 \times 439 \times 32.5$ | $101 \times 439 \times 32.5$ | $101 \times 439 \times 32.5$ | $101 \times 439 \times 32.5$ |

Extension base unit (Standard, Extended temperature range)

| Item | Extension base unit (Standard) |  |  |  | Extended temp. range extension base unit |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | R65B | R68B | R610RB | R612B | R610B-HT | R68RB-HT |
| Number of I/O modules installed | 5 | 8 | 10 | 12 | 10 | 8 |
| Applicable module | MELSEC iQ-R Series module |  |  |  |  |  |
| DIN rail mounting adapter type | R6DIN1 | R6DIN1 | R6DIN1 | R6DIN1 | R6DIN1 | R6DIN1 |
| External dimensions (HxW x D, mm) | $101 \times 245 \times 32.5$ | $101 \times 328 \times 32.5$ | $101 \times 439 \times 32.5$ | $101 \times 439 \times 32.5$ | $101 \times 439 \times 32.5$ | $101 \times 439 \times 32.5$ |

## RQ extension base unit

| Item | RQ extension base unit |  |  |
| :--- | :---: | :---: | :---: |
|  | RQ65B | RQ68B | RQ612B |
| Number of I/O modules installed | 5 | 8 | 12 |
| Applicable module |  | MELSEC-Q Series module |  |
| DIN rail mounting adapter type | Q6DIN2 | Q6DIN1 | Q6DIN1 |
| External dimensions $(H \times W \times D, m m)$ | $98 \times 245 \times 44.1$ | $98 \times 328 \times 44.1$ | $98 \times 439 \times 44.1$ |

## Extension cable

| Item | RC06B | RC12B | RC30B | RC50B |
| :---: | :---: | :---: | :---: | :---: |
| Cable length* $(\mathrm{m})$ | 0.6 | 1.2 | 3.0 | 5.0 |

The MELSEC iQ-R Series includes a wide range of programmable automation controllers capable of catering to diversified automation control needs, redesigned around the new MELSEC iQ-R high-speed system bus to ensure high performance and intelligent processing power. The lineup includes a high-performance, general-purpose controller (with an embedded CC-Link IE network model available) capable of variable memory capacities and a high-precision motion controller with variable controllable axes. In addition, application-specific CPUs are available; the Safety CPU (supporting functional safety standards), Process CPU (supporting high-speed PID control and hot-swap of I/O modules and when paired with a redundant function module realizes a high available control system), and the C Controller CPU, which provides C language programming ideal for converting from personal


- International standard (ISO 13849-1 PL e, IEC 61508 SIL 3) safety CPU
$>$ High-speed PID control, module replacement while online (hot-swap), supports highly reliable redundant system process CPU
$>C / C++$ programming ideal for PC/micro-controller based systems


## Improved performance

Controller performance has been improved, resulting in increased processing power and the ability to handle larger amounts of data. The multi-CPU architecture has been further improved, enabling faster data exchange across the backplane. The core instruction processing speed has also been improved tenfold, helping to reduce the production cycle time. High-speed and large process control systems can be realized, supporting up to 500 loops.

## Finely balanced control

Balancing of various different control needs can be done effectively utilizing the multi-CPU feature of the MELSEC iQ-R Series. Up to 192 servo axes can be controlled by incorporating three separate motion CPUs on the base unit, with a spare CPU slot required for
 controling the general aspects of the system.
*1: Based on a typical application example, the system benchmark test measures the CPU scan time taking into consideration the network refresh time and processing time using external devices, (compared to universal model QCPU, QnUDEHCPU).
${ }^{*} 2$ : Average number of instructions, such as basic instructions and data processing, executed in $1 \mu \mathrm{~s}$ (the larger the value, the faster the processing speed).

## Programmable Controller CPU Modules

## R04CPU

Program capacity 40K steps

## R08CPU

Program capacity 80K steps

## R16CPU

Program capacity 160K steps
R32CPU
Program capacity 320 K steps
R120CPU
Program capacity 1200 K steps

## R04ENCPU

Program capacity 40K steps, CC-Link IE embedded

## R08ENCPU

Program capacity 80K steps, CC-Link IE embedded

## R16ENCPU

Program capacity 160 K steps, CC-Link IE embedded

## R32ENCPU

Program capacity 320K steps, CC-Link IE embedded

## R120ENCPU

Program capacity 1200 K steps, CC-Link IE embedded


SD memory card slot
High-speed USB2.0 (miniB)

> Ethernet port 100BASE-TX/10BASE-T

CC-Link IE connection port 1000BASE-T/100BASE-TX/10BASE-T

At the core of the MELSEC iQ-R Series is a programmable controller CPU. This CPU is the heart of the control system and includes various features for different applications. The most common CPU is the programmable controller CPU, into which various features are embedded, enabling it to perform a wide range of control tasks. The different CPUs are highly scalable with five types available, based on program capacity needs ( 40 K to 1200 K steps). In addition, a CC-Link IE embedded CPU is available, further reducing hardware costs as a separate network module is not required.

## Built-in hardware features

Programmable controller CPUs are equipped with a built-in USB port (high-speed Ver. 2.0 Mini-B) and an Ethernet port (up to 100 Mbps ) as standard, enabling connection to a general LAN network*1 or MELSOFT software. Two memory options are included as well, an external SRAM cassette that enables device/label memory to be increased and doubling up as a hardware security key, and an SD memory card which can be used for logging data, troubleshooting device values or as a memory database for recipe storage.

[^3]
## Flexible, large-capacity data storage

The MELSEC iQ-R Series programmable controller CPU is designed to allow an external SRAM cassette to be installed directly into the CPU module. This option makes it possible to increase internal device memory to an impressive 5786K words, expanding device/label memory even further. An SD memory card can be used at the same time, expanding data logging memory and the capacity of the internal database, which is ideal for large-scale systems. In general, management of programmable controller internal data is quite flexible, making programming even easier by allowing various data area allocations to be changed within the CPU memory and SRAM cassette.


[^4]
## Data management utilizing internal database (DB)

The CPU includes an internal database that can be installed into the SD memory card. This feature allows, for example, a selection of database commands that can add/delete/change records to be utilized for simple recipe functions. It is also much easier to import/export Unicode files for use in spreadsheets. This is a very useful feature, especially for the food and beverage industry where multiple product variations are produced using the same machine process.


High-speed, event driven programs
Further improvements to CPU performance have resulted in the interval time between event driven programs (interrupt programs) reduced to 50 us. This has been realized by having multiple event driven programs able to be nested within other event driven programs and being triggered from already executing programs. This kind of performance is available with a standard input module and programmable controller CPU, without requiring a dedicated interrupt type input module, which helps to further reduce hardware costs while realizing a high-precision control system.


## CPU program management data

Operation and system historical events are automatically recorded in the CPU module, allowing quick root cause analysis of system errors or management of program changes. Actual changes to the program, parameters and system errors are viewable using GX Works3 or can be exported as a CSV file for use by other third-party software.


View operations and system events with corresponding event/error codes, data can be sorted according to various attributes.

## Intuitive root cause analysis

When the SD memory card is installed, device data is saved automatically to the SD memory at the time of system failure. This data is useful for investigating the cause of the failure, enabling various data collected before and during the event to be analyzed. The data can be used in a situation such as when the origin of a machine is different than where the machine was actually being used, and the data can simply be sent by e-mail (for example) as a data file for analysis.


## Easily collect manufacturing data

Utilizing the installed SD memory card or a direct live connection to the CPU module, logging data can be easily realized just by simply registering the parameters. Logged data can be utilized in a number of ways, such as using third-party spreadsheet software or as a real-time feed of data for analyzing various manufacturing processes. The real-time feature enables live feeds showing data has they happen in addition to historical trending. Logged historical trend files support the Unicode text file format, which is especially useful for Asian based applications as most languages in the region require Unicode compatibility for information to be legible.


Programmable controller CPU module specifications

| Item | R04(EN)CPU | R08(EN)CPU | R16(EN)CPU | R32(EN)CPU | R120(EN)CPU |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Control method | Stored program cyclic operation |  |  |  |  |
| I/O control mode | Refresh mode (Direct access I/O is available by specifying direct access I/O (DX, DY). ) |  |  |  |  |
| Programming language | Ladder diagram (LD), structured text (ST), function block diagram (FBD), sequential function chart (SFC) |  |  |  |  |
| Extended programming language | Function block (FB), label programming (system/local/global) |  |  |  |  |
| Program execution type | Initial, scan, fixed scan, interrupt, standby type |  |  |  |  |
| Number of I/O points [X/Y] (point) | 4096 | 4096 | 4096 | 4096 | 4096 |
| Constant scan (ms) <br> (Function for keeping regular scan time) | $0.2 \ldots 2000$ <br> (Setting available in 0.1 ms increments) |  |  |  |  |
| Memory capacity |  |  |  |  |  |
| Program capacity (step) | 40K | 80K | 160K | 320K | 1200K |
| Program memory (byte) | 160K | 320K | 640K | 1280K | 4800K |
| Device/label memory*1 (byte) | 400K | 1188K | 1720K | 2316K | 3380K |
| Data memory (byte) | 2 M | 5M | 10M | 20M | 40M |
| Instruction processing time |  |  |  |  |  |
| LD instruction (ns) | 0.98 | 0.98 | 0.98 | 0.98 | 0.98 |
| MOV instruction (ns) | 1.96 | 1.96 | 1.96 | 1.96 | 1.96 |
| $\mathrm{E}+$ instruction (floating-point addition) (ns) | 9.8 | 9.8 | 9.8 | 9.8 | 9.8 |
| Structured text IF instruction*2 (ns) | 1.96 | 1.96 | 1.96 | 1.96 | 1.96 |
| Structured text FOR instruction*2 (ns) | 1.96 | 1.96 | 1.96 | 1.96 | 1.96 |
| PC MIX value ${ }^{* 3}$ (instructions/ $/$ s) | 419 | 419 | 419 | 419 | 419 |
| Interface connection port |  |  |  |  |  |
| USB 2.0 High Speed (miniB) | $\bullet$ | $\bullet$ | - | - | - |
| Ethernet (100 BASE-TX/10 BASE-T) | - | - | - | - | - |
| CC-Link IE connection port |  |  |  |  |  |
| Ethernet <br> (1000BASE-T/100BASE-TX/10BASE-T) | $\bullet^{\star 4 * 5}$ | $0^{* 4 * 5}$ | $0^{* 4 * 5}$ | $0^{* 4 * 5}$ | $0^{* 4 * 5}$ |
| Memory interface |  |  |  |  |  |
| SD memory card | - | - | - | - | - |
| Extended SRAM cassette | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Function |  |  |  |  |  |
| Multiple interrupt | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Standard PID control | - | - | - | - | - |
| Internal database | $\bullet$ | $\bullet$ | - | $\bullet$ | - |
| Memory dump | $\bullet$ | - | - | - | - |
| Data logging | $\bullet$ | - | - | - | - |
| Real-time monitor | $\bullet$ | $\bullet$ | - | - | - |
| Security | - | - | - | - | $\bullet$ |
| Inter-modular synchronization | - | - | - | - | - |
| SLMP communication | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |

1: An extended SRAM cassette expands the device/label memory area.
2: The IF or FOR sentence of the structured text consists of several instructions, which may increase the processing time period.
: Average number of instructions such as for basic instructions and data processing executed in $1 \mu \mathrm{~s}$. The larger the value, the faster the processing speed.
: Available with RDENCPU. For details about network specifications, refer to the RJ71EN71 performance specifications on page 63 .
5: The following networks are supported, Ethernet, CC-Link IE Control (twisted pair cable), and CC-Link IE Field (two simultaneous Ethernet networks and combined CC-Link IE Field and CC-Link IE Control networks are not supported).

## SD memory card specifications

|  | Item | NZ1MEM-2GBSD | NZ1MEM-4GBSD | NZ1MEM-8GBSD |
| :--- | :---: | :---: | :---: | :---: |
| Type | SD memory card | SDHC memory card | SDHC memory card | SDHC memory card |
| Capacity (byte) | $2 G$ | $4 G$ | $8 G$ |  |

Extended SRAM cassette specifications

| Item | NZ2MC-1MBS | NZ2MC-2MBS | NZ2MC-4MBS | NZ2MC-8MBS(E)** | NZ2MC-16MBS*7 |
| :--- | :---: | :---: | :---: | :---: | :---: |
| Capacity (byte) | 1 M | 2 M | 4 M | 8M | 16M |
| ${ }^{*} 6:$ NZ2MC-8MBSE is only supported by safety CPU and process CPU. |  |  |  |  |  |

[^5]Motion CPU Modules

## R16MTCPU

Up to 16-axis control

## R32MTCPU

Up to 32-axis control
R64MTCPU
Up to 64-axis control

The motion CPU module is a dedicated high-precision control CPU module, designed solely for applications that require advanced motion control such as positioning control, synchronous control, and speed-torque control at a very high accuracy. The motion CPU is incorporated into the multiple CPU architecture of the MELSEC iQ-R Series complimenting the programmable controller CPU.

## High-speed data communication between CPUs

High-speed communication is realized between the two CPUs via a large bandwidth data buffer memory exchange. There are two types of buffer memory for data exchange: one that provides cyclic exchange at a cycle time as fast as 0.222 ms ; and one for direct data exchange of event-driven buffer memory, which is useful for large data bandwidth requirements. High-speed communications are very useful when there is a need to instantaneously transfer a large amount of information such as cam data, thereby simplifying programming even further.


[^6]
## Various different applications easily realized

Tension control can be maintained constantly enabling the unwinding of various rolled sheets, for example, with line synchronization realized via speed and advanced synchronous control.

The combination of a machine vision system and high-speed motion control enables highly accurate positional alignment.


Positional alignment

Synchronization between different print heads has been achieved by speed and advanced synchronous control.


Offset printing

## Multiple machine processes by SFC programming

The motion CPU module is programmed using the SFC (Sequential Function Chart) type language which enables programming in clearly identifiable steps. This is extremely useful where multiple machine processes have to be performed simultaneously.
■ Motion SFC Program


Motion CPU module specifications

| Item | R16MTCPU | R32MTCPU | R64MTCPU |
| :---: | :---: | :---: | :---: |
| Number of control axes | 16 axes | 32 axes (16 axes $\times 2$ lines) | 64 axes (32 axes $\times 2$ lines) |
| Operation cycle (ms) | 0.222, 0.444, 0.888, 1.777, 3.555, 7.111 | $0.222,0.444,0.888,1.777,3.555,7.111$ | 0.222, 0.444, 0.888, 1.777, 3.555, 7.111 |
| Programming language | Motion SFC, dedicated instruction | Motion SFC, dedicated instruction | Motion SFC, dedicated instruction |
| Servo program capacity (step) | 32 K | 32 K | 32K |
| Number of positioning points (point) | 6400 | 6400 | 6400 |
|  | (positioning data can be designated indirectly) | (positioning data can be designated indirectly) | (positioning data can be designated indirectly) |
| Servo amplifier network | SSCNET II/H (1 line) | SSCNET II/H (2 lines) | SSCNET II/H (2 lines) |
| Max. distance between stations ( m ) | 100 | 100 | 100 |
| Interpolation |  |  |  |
| Linear interpolation (axis) | 2, 3, 4 | 2, 3, 4 | 2, 3, 4 |
| Circular interpolation (axis) | 2 | 2 | 2 |
| Helical interpolation (axis) | 3 | 3 | 3 |
| Control mode |  |  |  |
| PTP (Point To Point) control | $\bullet$ | $\bullet$ | $\bullet$ |
| Speed-position switching control | $\bullet$ | - | $\bullet$ |
| Continuous path control | $\bullet$ | $\bullet$ | $\bullet$ |
| Position follow-up control | $\bullet$ | - | - |
| Advanced synchronous control | $\bullet$ | $\bullet$ | $\bullet$ |
| Speed-torque control | $\bullet$ | $\bullet$ | $\bullet$ |
| Acceleration/deceleration control |  |  |  |
| Trapezoidal acceleration/deceleration | $\bullet$ | $\bullet$ | $\bullet$ |
| S-curve acceleration/deceleration | $\bullet$ | $\bullet$ | $\bullet$ |
| Advanced S-curve acceleration/ deceleration | $\bullet$ | $\bullet$ | - |
| Interface |  |  |  |
| PERIPHERAL I/F | $\bullet$ | $\bullet$ | $\bullet$ |
| SD memory card | $\bullet$ | $\bullet$ | $\bullet$ |
| Function |  |  |  |
| Absolute positioning system*1 | $\bullet$ | $\bullet$ | $\bullet$ |
| Mark detection function | - | - | - |
| Security function | $\bullet$ | - | - |
| Digital oscilloscope function | $\bullet$ | $\bullet$ | $\bullet$ |
| Driver communication function | $\bullet$ | $\bullet$ | $\bullet$ |

## Process CPU Modules, Redundant Function Module R08PCPU <br> Program capacity 80K steps <br> R16PCPU <br> Program capacity 160 K steps <br> R32PCPU <br> Program capacity 320 K steps <br> R120PCPU <br> Program capacity 1200 K steps



Redundant system when process CPU is paired with the redundant function module.

The process CPU module is part of the application-specific range in the MELSEC iQ-R Series and has four CPUs available with memory sizes from 80 K to 1200 K steps. It is designed specifically for medium- to large-scale process control systems requiring high-speed performance coupled with the handling of large PID loops. When paired with a redundant function module, a highly reliable (redundant) control system can be realized with a tracking data capacity of up to 1 M words between the control and standby systems supported.

## DCS style features in a cost-efficient automation control system

The specialized CPU inherits its high performance from the MELSEC iQ-R Series when used together with the centralized programming suite GX Works3 and iQ Works. The process control system incorporates a dedicated process instruction set (such as two-degree-of-freedom PID, sample PI, and auto-tuning), realizing algorithmic PID and highly reliable features such as being able to interchange (hot-swap) I/O modules while the system is still online and large-scale process control with a maximum of 500 loops, closely bringing it in line with DCS capabilities without the financial burden.

## Redundant system remote location and high-speed switching

Optical-fiber tracking cables enable the standby system to be installed in a remote location up to 550 m from the control (primary) system. The tracking cables are immune to noise interference and support fast data transfer rates. System switching speed has also been improved to speeds of 10 ms or less, enabling high-speed switching of the control system to standby system further improving reliability.


Control panel B

## Improve reliability with reduced single-point failure

A multi-level redundant system can be realized by installing dual control systems consisting of the control (primary) and standby CPUs combined with a dual cable topology for the network cabling of the CC-Link IE Field networks, and dual remote stations minimizing the risk of singe-point failure. It is also possible to replace modules (hot-swapping) without stopping the operating control system.


## Mitsubishi MC Works64 visualization and redundant Ethernet improving information level reliability

Mitsubishi SCADA MC Works64 in combination with MELSEC iQ-R Series redundant system realizes highly reliable visualization and control system. The Ethernet module includes two communications ports which enable information level communications with MC Works 64 without switching the system even if an error occurs with one of the ports, in addition to reducing system hardware costs as only one module is required per control and standby system.


## GX Works3* easy programming and automatic memory copy

GX Works3 is the main programming and maintenance software of the MELSEC iQ-R process control system. This integrated software application is equipped with many functions that contribute to reducing engineering time and simplifying commissioning. When installed as a redundant system, the same project can be transferred to the standby system automatically during CPU module replacement without having to upload the project to the new CPU again.


[^7]
## Process CPU module specifications

| Item | R08PCPU | R16PCPU | R32PCPU | R120PCPU |
| :---: | :---: | :---: | :---: | :---: |
| Control method | Stored program cyclic operation |  |  |  |
| I/O control mode | Refresh mode (Direct access I/O is available by specifying direct access I/O (DX, DY). ) |  |  |  |
| Programming language | Ladder diagram (LD), structured text (ST), function block diagram (FBD), sequential function chart (SFC)*1 |  |  |  |
| Extended programming language | Function block (FB), label programming (system/local/global) |  |  |  |
| Program execution type | Initial, scan, fixed scan, interrupt, standby type |  |  |  |
| Number of I/O points [X/Y] (point) | 4096 | 4096 | 4096 | 4096 |
| Constant scan (ms) <br> (Function for keeping regular scan time) | $0.2 \ldots 2000$ <br> (Setting available in 0.1 ms increments) |  |  |  |
| Memory capacity |  |  |  |  |
| Program capacity (step) | 80K | 160K | 320K | 1200K |
| Program memory (byte) | 320K | 640K | 1280K | 4800K |
| Device/label memory (ECC type)*2 (byte) | 1188K | 1720K | 2316K | 3380K |
| Data memory (byte) | 5M | 10M | 20M | 40M |
| Instruction processing time |  |  |  |  |
| LD instruction (ns) | 0.98 | 0.98 | 0.98 | 0.98 |
| MOV instruction (ns) | 1.96 | 1.96 | 1.96 | 1.96 |
| $\mathrm{E}+$ instruction (floating-point addition) (ns) | 9.8 | 9.8 | 9.8 | 9.8 |
| Structured text IF instruction*3 (ns) | 1.96 | 1.96 | 1.96 | 1.96 |
| Structured text FOR instruction*3 (ns) | 1.96 | 1.96 | 1.96 | 1.96 |
| PC MIX value*4 (instructions $/ \mu \mathrm{s}$ ) | 419 | 419 | 419 | 419 |
| Interface connection port |  |  |  |  |
| USB2.0 High Speed (miniB) | $\bullet$ | - | $\bullet$ | $\bullet$ |
| Ethernet (100BASE-TX/10BASE-T) | - | $\bullet$ | - | $\bullet$ |
| Memory interface ${ }^{* 5}$ |  |  |  |  |
| SD memory card | $\bullet$ | - | $\bullet$ | $\bullet$ |
| Extended SRAM cassette | $\bullet$ | $\bullet$ | - | $\bullet$ |
| Function ${ }^{\text {6 }}$ |  |  |  |  |
| Multiple interrupt | $\bullet$ | - | $\bullet$ | $\bullet$ |
| Standard PID control | - | - | $\bullet$ | - |
| Process control | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Database | - | - | $\bullet$ | - |
| Data logging | - | $\bullet$ | $\bullet$ | - |
| Security function | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Inter-modular synchronization*7 | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| SLMP communication | - | - | - | - |
| Online module change | - | $\bullet$ | $\bullet$ | $\bullet$ |

*1: SFC programming language is not supported when used in redundant mode.
2: An extended SRAM cassette expands the device/label memory area. (NZ2MC-8MBSE expands the device/label memory area conforming to ECC type memory.)
*3: The IF or FOR sentence of the structured text consists of several instructions, which may increase the processing time period.
4: Average number of instructions such as for basic instructions and data processing executed in $1 \mu \mathrm{~s}$. The larger the value, the faster the processing speed.
*5: For more information please refer to the SD memory card and SRAM cassette specifications on page 31.
. Memory dump and real-time monitor are not supported.
7: Inter-modular synchronization is not supported when used in redundant mode.

## Redundant function module specifications

| Item | R6RFM |
| :--- | :---: | :---: |
| Communication cable | Multi-mode optical cable |
| Max. distance $(\mathrm{m})$ | 550 (when the core outer diameter is $50 \mu \mathrm{~m})$ |
| Tracking cable data capacity (word) | 1 M |

Safety CPU
R08SFCPU-SET
Program capacity 80K steps
R16SFCPU-SET
Program capacity 160 K steps
R32SFCPU-SET
Program capacity 320K steps
R120SFCPU-SET
Program capacity 1200 K steps

The safety CPU module enables control of both generic and safety programs in the same module and is easily programmed utilizing the intuitive features of GX Works3. Compliant with internationally recognized safety standards, the safety CPU enables safety devices such as safety light curtains, emergency switches, and door switches to be connected via the CC-Link IE Field network without requiring a separate dedicated network line. The safety CPU is easily programmed using GX Works3, and utilizes its intuitive features.

Generic and safety control in one CPU
The safety CPU can be installed directly on the MELSEC iQ-R Series base rack, and is easily integrated into an existing or new control system. Safety devices are connectable using the CC-Link IE Field network with safety communication integrated into the network protocol over a widely-available industrial Ethernet topology. The safety CPU is compliant with ISO 13849-1 PL e and IEC 61508 SIL 3 and is certified by TÜV Rheinland ${ }^{\circledR}$.

## Common engineering platform

In GX Works3, operation and safety programs are included in the same project folder, eliminating the need to manage multiple project folders. Various useful features of GX Works3 are also available for safety programs similar to other control programs.


## Faster response times and handling of larger programs

Utilizing the high-performance capabilities of the MELSEC iQ-R Series and CC-Link IE Field network, productivity is enhanced as response times are even faster. Additionally, safety control program capacity has been increased by up to three times, to 40 K steps, enabling the control of more complex programs.

■ Safety control response time

(Considering QS as 100.)

■ Safety program size


## Safety CPU performance specifications

| Item | R08SFCPU-SET*1 | R16SFCPU-SET** | R32SFCPU-SET*1 | R120SFCPU-SET*1 |
| :---: | :---: | :---: | :---: | :---: |
| Safety integrity level (SIL) | SIL 3 (IEC 61508) |  |  |  |
| Performance level (PL) | PL e (EN/ISO 13849-1) |  |  |  |
| Control method | Stored program cyclic operation |  |  |  |
| I/O control mode | Refresh mode (Direct access I/O is available by specifying direct access I/O (DX, DY).) |  |  |  |
| Programming language | Ladder diagram (LD), structured text (ST)*2, function block diagram (FBD)*2 |  |  |  |
| Extended programming language | Function block (FB), label programming (local/global) |  |  |  |
| Program execution type | Initial ${ }^{\star 2}$, scan*2, fixed scan, interrupt ${ }^{* 2}$, standby type*2 |  |  |  |
| Memory capacity |  |  |  |  |
| Program capacity (step) | 80K <br> (40K for safety programs) | 160K <br> (40K for safety programs) | 320K <br> (40K for safety programs) | 1200K <br> (40K for safety programs) |
| Program memory (byte) | 320K | 640K | 1280K | 4800K |
| Device/label memory*3 (byte) | 1178K | 1710K | 2306K | 3370K |
| Data memory (byte) | 5M | 10M | 20M | 40M |
| SLMP communication | - | $\bullet$ | $\bullet$ | $\bullet$ |

[^8]2: Only for executing generic control programs.
3: An extended SRAM cassette expands the device/label memory area.

## C Controller Module

## R12CCPU-V

Memory capacity 256 MB


The C Controller module is part of the application-specific range in the MELSEC iQ-R Series. The multi-core ARM ${ }^{\oplus}$-based controller pre-installed with $V \times W$ orks ${ }^{\oplus}$ Version 6.9 , realizes the simultaneous execution of programs, thereby providing a robust and deterministic alternative to computer based systems. Utilizing a fan-less hardware design, the C Controller is ideal for clean fab-based applications where dust circulation can be detrimental to the production environment. The C Controller utilizes the high-performance, flexible, and robust features of the MELSEC iQ-R Series to provide an industrial-grade automation control system.

## Easy setup using three simple tools

Setup of the C Controller couldn't be simpler as the CPU is shipped with a pre-installed real-time OS with various drivers embedded. This eliminates the need to setup and install a separate OS and develop drivers, which can substantially add to the cost of implementation. The C Controller allows C language programming by using CW Workbench programming software, easy configuration using MELSOFT CW Configurator, and VxWorks ${ }^{\circledR}$ emulation using CW-Sim.

## Programming without considering MPU

C Controller dedicated functions (CCPU functions) and MELSEC communication functions (MD functions) realize easy access to the C Controller, I/O, intelligent function, network, and programmable controller/motion CPU modules. Applications involving programmable controllers can be easily created using these functions.


## Parameter setup/diagnosis/monitoring with CW Configurator

CW Configurator enables parameter setup, module diagnosis and monitoring of various MELSEC iQ-R/Q Series intelligent, network and I/O modules*1 modules including the C Controller module. Using CW Configurator is as easy as using the MELSEC iQ-R engineering software GX Works3, which shares similar interfaces.
*1: For supported modules, please refer to the relevant manual of that module.


Application development in simple steps
Developing applications with the MELSEC C Controller is easy as no additional driver development is required, whilst providing a full-scale embedded development environment at a relatively low cost. CW Workbench is used as the main programming software in C/C++ with a VxWorks ${ }^{\circledR}$ emulator, CW-Sim/CW-Sim standalone, which allows debugging without requiring any hardware.

No need to generate OS or drivers. This program does it all.

Void myFuncol
/*Enter an interrupt routine for the inter-modular synchronization interruption (144) */
CCPU_Entrylnt ( 44. mylSR44) :
/* Enable the routine entered to the inter-modular synchronization interruption (144) */


Engineering tool for C Controller CW Workbench

## C Controller module specifications

| Item | R12CCPU-V |
| :---: | :---: |
| Hardware |  |
| Endian format | Little endian |
| MPU | ARM ${ }^{\text {® }}$ Cortex-A9 Dual Core |
| Working RAM | 256 MB |
| ROM | 12 MB |
| Backup RAM | 4 MB |
| Software |  |
| OS | VxWorks ${ }^{\text {® }}$ Version 6.9 |
| Programming language | C language (C/C++) |
| Programming development environment | CW Workbench/Wind River Workbench3.3 |
| C Controller module setting/monitoring tool | CW Configurator (SW1DND-RCCPU) |
| Communication interface |  |
| USB | $\bullet$ |
| Ethernet | 2CH (1000BASE-T/100BASE-TX/10BASE-T) |
| RS-232 | 1CH (9600... 115200 bps ) |
| SD memory card slot | - |

Digital I/O modules are the senses of the automation system and provide an interface of various processes to the controller. Devices such as switches, indicator lamps, and sensors can be easily connected to the control system. The high-density terminal connections (up to 64 points) results in space-saving designs within the control cabinet further reducing installation costs. In addition, input interrupt functions and output relay health diagnosis are additional features embedded in this intelligent, yet small, compact module.


## Clear and easily legible

White and red labels clearly differentiate the input and output modules from each other, further improving safety awareness. The LED signal displays also labeled with clearly visible and easy to read I/O signal numbers printed on the cover. The wiring terminals of the 16-point modules are labeled with signal names, further reducing the possibility of wiring mistakes. Up to 32 LED signals can be displayed at one time, and a toggle switch enables alternation between the first- and second-half signal displays for the high-density 64-point modules. The input and output ratings are also clearly printed on the front and the serial number is at the bottom, making it easy to confirm product model and version.

## Simple wiring and high-density I/O

I/O modules are available in a wide range of densities (16-, 32- and 64-points) depending on the I/O requirements and minimum use of space in the control cabinet. A module with a 40-pin connector is available for high-density I/O wiring. The terminal block and spring clamp terminal block are interchangeable with MELSEC-Q Series I/O terminals and can save on the cost of upgrading from existing control systems.

## Input Modules

AC input
RX10
16 points
100 to 120 V AC $(50 / 60 \mathrm{~Hz})$
DC input
RX40C7
16 points
24 V DC, 7.0 mA

## RX41C4

32 points
24 V DC, 4.0 mA
RX42C4
64 points
24 V DC, 4.0 mA

DC high-speed input
RX40PC6H
16 points 24 V DC, 6.0 mA
positive common type

## RX4ONC6H

16 points 24 V DC, 6.0 mA negative common type

## RX41C6HS INEw

32 points 24 V DC, 6.0 mA Positive/negative common shared

## RX61C6HS New

32 points 5 V DC, 6.0 mA
Positive/negative common shared

DC input
(with diagnostic functions)
RX4ONC6B NEw
16 points 24 V DC, 6.0 mA Negative common type

Digital input modules like the 24 V direct-current (DC) power supply are among the most used input signals in the control industry. The robust design of the various modules in this diversified lineup makes them ideal for industrial use.

## Multiple features integrated

A single MELSEC iQ-R input module can handle input response devices as fast as 0.1 ms , interrupt input devices and can be wired using either positive or negative (sink or source) common terminals. Since multiple modules are no longer required, a substantial reduction in overall footprint of up to $20 \%$ and a reduction in total system costs of up to $60 \%$ can be realized.


[^9]
## Reduce downtime with disconnection detection

Similar to analog modules, the MELSEC iQ-R Series input module (with diagnostic functions) includes input disconnection detection which enables detection of inputs directly on the I/O module. When an error occurs, the control system can quickly highlight the fault via a monitoring system or on GX Works3 programming software, reducing system downtime and loss of production.

Input module specifications

| Item | AC input | DC input |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | RX10 | RX40C7 | RX41C4 | RX42C4 |
| Number of input points | 16 | 16 | 32 | 64 |
| Rated input voltage, frequency | 100... $120 \mathrm{~V} \mathrm{AC}, 50 / 60 \mathrm{~Hz}$ | 24 V DC | 24 V DC | 24 V DC |
| Rated input current (mA) | $\begin{aligned} & 8.2(100 \mathrm{~V} \mathrm{AC}, 60 \mathrm{~Hz}) \\ & 6.8(100 \mathrm{~V} \mathrm{AC}, 50 \mathrm{~Hz}) \end{aligned}$ | 7.0 TYP. | 4.0 TYP. | 4.0 TYP. |
| Response time | $\leq 20 \mathrm{~ms}$ | $0.1 . .70 \mathrm{~ms}$ | $0.1 . . .70 \mathrm{~ms}$ | $0.1 . .70 \mathrm{~ms}$ |
| Common terminal arrangement (points/common) | 16 | 16 | 32 | 32 |
| Interrupt function | $\bullet$ | $\bullet$ | - | $\bullet$ |
| External interface ${ }^{* 1}$ |  |  |  |  |
| 18-point screw terminal block | $\bullet$ | - | - | - |
| 40-pin connector | - | - | - | - (2x) |


| Item | DC high-speed input |  |  |  | DC input |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | RX40PC6H | RX40NC6H | RX41C6HS | RX61C6HS | RX40NC6B |
| Number of input points | 16 | 16 | 32 | 32 | 16 |
| Rated input voltage, frequency | 24 V DC | 24 V DC | 24 V DC | 5 V DC | 24 V DC |
| Rated input current (mA) | 6.0 | 6.0 | 6.0 | 6.0 | 6.0 |
| Response time | $5 \mu \mathrm{~s} . . .70 \mathrm{~ms}$ | $5 \mu \mathrm{~s} . . .70 \mathrm{~ms}$ | $1 \mu \mathrm{~s} . . .70 \mathrm{~ms}$ | $1 \mu \mathrm{~s} . . .70 \mathrm{~ms}$ | $1 \mathrm{~ms} . . .70 \mathrm{~ms}$ |
| Common terminal arrangement (points/common) | (positive common) | (negative common) | 32 (positive/negative common) | 32 (positive/negative common) | $\begin{gathered} 16 \\ \text { (negative common) } \end{gathered}$ |
| Interrupt function | - | - | - | - | - |
| Diagnostic function*2 |  |  |  |  |  |
| Disconnection detection | - | - | - | - | - |
| External interface ${ }^{* 1}$ |  |  |  |  |  |
| 18-point screw terminal block | $\bullet$ | - | - | - | $\bullet$ |
| 40-pin connector | - | - | - | - | - |

[^10]*2: For more information about diagnostic functions, please refer to the relevant product manual.

Output Modules

Relay output

## RY10R2

16 points
24 V DC, 240 V AC
Transistor (sink) output
RY40NT5P
16 points
12 to 24 V DC, 0.5 A

## RY41NT2P

32 points
12 to 24 V DC, 0.2 A

## RY42NT2P

64 points
12 to 24 V DC, 0.2 A

Transistor (source) output
RY40PT5P
16 points
12 to 24 V DC, 0.5 A
RY41PT1P
32 points
12 to 24 V DC, 0.1 A

## RY42PT1P

64 points
12 to 24 V DC, 0.1 A

A variety of digital output modules are available including relay, transistor sink (wired as positive common) and transistor source (wired as negative common). Load voltages include 240 V AC and 12 V to 24 V DC, with various current ratings.

## Relay health diagnostics for preventive maintenance

Output modules (relay output and transistor-with diagnostic functions modules) keep track of how many times they're turned on and off. Utilizing this data, such as from embedded relay contacts in the relay output module or from relays connected externally to the transistor output module (with diagnostic functions), preventive maintenance can be carried out based on the known service of the relay.

Output module specifications

| Item | Relay output | Transistor (sink) output |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | RY10R2 | RY40NT5P | RY41NT2P | RY42NT2P | RY41NT2H |
| Number of input points (point) | 16 | 16 | 32 | 64 | 32 |
| Rated switching voltage, current | $\begin{aligned} & 24 \mathrm{~V} \mathrm{DC} / 2 \mathrm{~A} \\ & 240 \mathrm{~V} \mathrm{AC} / 2 \mathrm{~A} \end{aligned}$ | - | - | - | - |
| Rated load voltage (V DC) | - | 12... 24 | 12... 24 | 12... 24 | 5... 24 |
| Max. load current (A/point) | - | 0.5 | 0.2 | 0.2 | 0.2 |
| Response time | $\leq 12 \mathrm{~ms}$ | $\leq 1 \mathrm{~ms}$ | $\leq 1 \mathrm{~ms}$ | $\leq 1 \mathrm{~ms}$ | $\leq 2 \mu \mathrm{~s}$ |
| Common terminal arrangement (points/common) | 16 | 16 | 32 | 32 | 32 |
| Protection function (overload, overheat) | - | - | - | - | - |
| External interface ${ }^{* 1}$ |  |  |  |  |  |
| 18-point screw terminal block | - | - | - | - | - |
| 40-pin connector | - | - | - | - (2x) | - |


| Item | Transistor (source) output |  |  |  | Transistor-with diagnostic functions (source) output |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | RY40PT5P | RY41PT1P | RY42PT1P | RY41PT2H | RY40PT5B |
| Number of input points (point) | 16 | 32 | 64 | 32 | 16 |
| Rated load voltage (V DC) | 12... 24 | 12... 24 | 12... 24 | 5... 24 | 24 |
| Max. load current (A/point) | 0.5 | 0.1 | 0.1 | 0.2 | 0.5 |
| Response time | $\leq 1 \mathrm{~ms}$ | $\leq 1 \mathrm{~ms}$ | $\leq 1 \mathrm{~ms}$ | $\leq 2 \mu \mathrm{~s}$ | $\leq 1.5 \mathrm{~ms}$ |
| Common terminal arrangement (points/common) | 16 | 32 | 32 | 32 | 16 |
| Protection function (overload, overheat) | $\bullet$ | $\bullet$ | - | - | $\bullet$ |
| Diagnostic function*2 |  |  |  |  |  |
| Output disconnection detection | - | - | - | - | - |
| Output short-circuit detection | - | - | - | - | - |
| External interface ${ }^{* 1}$ |  |  |  |  |  |
| 18-point screw terminal block | - | - | - | - | $\bullet$ |
| 40-pin connector | - | - | - (2x) | - | - |

[^11]*2: For more information about diagnostic functions, please refer to the relevant product manual.

## I/O Combined Module

DC input, transistor (sink) output
RH42C4NT2P
32 points (input) 24 V DC, 4.0 mA
32 points (output) 12 to 24 V DC, 0.2 A

In addition to dedicated digital input and output modules, if only a few I/O points are required, a combined I/O module is available. This is an excellent alternative for cost-sensitive applications.

I/O combined module specifications

| Item | RH42C4NT2P |
| :---: | :---: |
| DC input |  |
| Number of input points (point) | 32 |
| Rated input voltage (V DC) | 24 |
| Rated input current (mA) | 4.0 TYP. |
| Response time (ms) | 0.1.. 70 |
| Common terminal arrangement (points/common) | 32 |
| Interrupt function | $\bullet$ |
| Transistor (sink) output |  |
| Number of output points (point) | 32 |
| Rated load voltage (V DC) | 12... 24 |
| Max. load current (A/point) | 0.2 |
| Response time (ms) | $\leq 1$ |
| Common terminal arrangement (points/common) | 32 |
| Protection function (overload, overheat) | - |
| External interface ${ }^{* 1}$ |  |
| 40-pin connector | - (2x) |

[^12]
## Focus points

$>5 \mu$ s high-speed sampling, 16 -bit high resolution $(1 / 32,000)$

- Scaling and shifting operations using parameter settings
- Ideal for high-speed precision inspection applications
$>$ Filtering of high-frequency noise
- Event driven performance asynchronous from main scan
- Generate or import pre-defined wave data
- Galvanic channel isolation
- Synchronization of multiple channels


Similar to the digital I/O modules, analog modules are the main interface between the control process and the MELSEC iQ-R Series automation system. The main differences are that they have been designed to interface with sensors that process varying voltage and current signals instead of digital binary signals, and convert those signals into binary data that the control system can use. The MELSEC iQ-R Series range of analog modules includes features such as high-speed sampling $(5 \mu \mathrm{~s} / 4 \mathrm{CH})$ coupled with 16 bit high-resolution $(1 / 32,000)$ digital output signals, simultaneous multi-channel conversion (no. of channels increased with inter-modular synchronization), galvanic channel isolation and disconnection detection, thereby enabling highly precise and stable analog signal processing.

## Save on downtime cost with 'channel disconnection detection'

Channel input or output error threshold values are easily settable within GX Works3 ensuring the detection of disconnected channel(s), reducing downtime and saving on maintenance costs.


Time

High signal integrity using galvanic isolation
The "-G" suffix modules include internal galvanic channel isolation that can improve noise interference capabilities without requiring an additional signal converter as well as protecting the internal module components from a short circuit.


Electric disturbances such as current and noise can be isolated.


## Analog Input Modules

R60AD4
4-channel (voltage or current)

## R60ADV8

8-channel (voltage)

## R60ADI8

8-channel (current)

R60AD8-G
8 -channel (voltage or current), channel isolated

## R60AD16-G

16-channel (voltage or current), channel isolated

## R60TD8-G

8 -channel, temperature input (thermocouple) channel isolated

## R60RD8-G

8-channel, temperature input (RTD) channel isolated

R60ADH4 NEw
4-channel (voltage or current)

MELSEC iQ-R Series analog modules are ideal as the interface between external analog signals and the control system. Various modules are available to cover a wide range of requirements, such as galvanic isolation, thermocouple sensors, resistance temperature detectors (RTD), current, voltage and mixed channel applications.

## High-frequency noise filtering

The analog modules include a first-order delay filter that eliminates high-frequency noise interference and improves the accuracy of input analog signals. This feature can be easily setup using the module's dedicated parameters, thereby improving the processing time as an additional setup program (ladder) is not required.


## In-line level monitor



## Enhanced alarm and warning features

Preventive maintenance procedures are simplified with the enhanced alarm and warning capabilities. Regardless of the program scan time, when an event such as the change rate of an analog signal exceeding the preset limit occurs, corrective interrupt procedures can be triggered or an alarm generated to notify responsible personnel or initiate proper countermeasures.


## Data logging faster than scan time

Analog modules are equipped with a data logging feature that's useful when a large amount of data (up to 10k points) is required within a specified period of time. Coupled with the high-speed analog-to-digital conversion time, event-driven triggers enable continuous logging even after an event occurrence and fast data logging sampling that is asynchronous to the control scan time. Data logging can be used in applications such as a motor inspection line, where motor performance can be logged at high speed and certain values such as voltage, current, torque and rotational speed analyzed through comparisons with different test patterns.


## Scaling and shifting digital values without any programs

Scaling and shifting can be easily setup from only using the parameters. There is no need for additional programming, thereby realizing reductions in engineering costs and overall program size.



Upper and lower limits of scaling can range from -32000 to 32000.

Analog input module specifications

| Item | R60AD4 | R60ADV8 | R60ADI8 | R60AD8-G | R60AD16-G |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Number of analog input points (ch) | 4 | 8 | 8 | 8 | 16 |
| Accuracy |  |  |  |  |  |
| Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ |
| Ambient temperature $0 . . .55^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ | $\pm 0.3 \%$ | $\pm 0.3 \%$ | - | - |
| Temperature coefficient | - | - | - | $\pm 35 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ | $\pm 35 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| Common |  |  |  |  |  |
| Conversion speed (ch) | $80 \mu \mathrm{~s}$ | $80 \mu \mathrm{~s}$ | $80 \mu \mathrm{~s}$ | 10 ms | 10 ms |
| Channel isolation | - | - | - | Transformer isolation | Transformer isolation |
| Absolute max. input | $\pm 15 \mathrm{~V}, 30 \mathrm{~mA}$ | $\pm 15 \mathrm{~V}$ | 30 mA | $\pm 15 \mathrm{~V}, 30 \mathrm{~mA}$ | $\pm 15 \mathrm{~V}, 30 \mathrm{~mA}$ |
| Voltage input |  |  |  |  |  |
| Analog input voltage (V DC) | -10... 10 | -10... 10 | - | -10... 10 | -10... 10 |
| Digital output value | -32000... 32000 | -32000... 32000 | - | -32000...32000 | -32000... 32000 |
| Current input |  |  |  |  |  |
| Analog input current (mA DC) | 0... 20 | - | 0... 20 | 0... 20 | 0... 20 |
| Digital output value | 0... 32000 | - | 0... 32000 | 0... 32000 | 0... 32000 |
| External interface ${ }^{* 1}$ |  |  |  |  |  |
| 18-point screw terminal block | - | - | - | - | - |
| 40-pin connector | - | - | - | $\bullet$ | - (2x) |

High-speed analog input module specifications

| Item $\quad$ R60ADH4 |  |
| :---: | :---: |
| Number of analog input points (ch) | 4 |
| Accuracy |  |
| Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ | $\pm 0.1 \%$ |
| Ambient temperature $0 \ldots . .55^{\circ} \mathrm{C}$ | $\pm 0.2 \%$ |
| Input specifications |  |
| Operation mode (sampling cycle) | Normal mode (medium speed: $10 \mu \mathrm{~s} / \mathrm{CH}$ ) |
|  | Normal mode (low speed: $20 \mu \mathrm{~s} / \mathrm{CH}$ ) |
|  | Simultaneous conversion mode ( $5 \mu \mathrm{~s} / 4 \mathrm{CH}$ ) |
| Absolute max. input | $\pm 15 \mathrm{~V}, 30 \mathrm{~mA}$ |
| Voltage input |  |
| Analog input voltage (V DC) | -10... 10 |
| Digital output value | -32000... 32000 |
| Current input |  |
| Analog input current (mA DC) | 0... 20 |
| Digital output value | 0... 32000 |
| External interface ${ }^{* 1}$ |  |
| 18-point screw terminal block | - |

Temperature input module specifications

| Item | R60TD8-G | R60RD8-G |
| :---: | :---: | :---: |
| Number of analog input points (ch) | 8 | 8 |
| Cold junction temperature compensation accuracy | $\pm 1.0^{\circ} \mathrm{C}$ | - |
| Usable thermocouple | B, R, S, K, E, J, T, N | - |
| Usable RTD | - | Pt100, JPt100, Ni100, Pt50 |
| Resolution | $\begin{aligned} & \mathrm{B}, \mathrm{R}, \mathrm{~S}, \mathrm{~N}: 0.3^{\circ} \mathrm{C} \\ & \mathrm{~K}, \mathrm{E}, \mathrm{~J}, \mathrm{~T}: 0.1^{\circ} \mathrm{C} \end{aligned}$ | $0.1{ }^{\circ} \mathrm{C}$ |
| Conversion speed (ch) | 30 ms | 10 ms |
| Channel isolation | Transformer isolation | Transformer isolation |
| Wire break detection | - | - |
| Output |  |  |
| Measured temperature value (16-bit signed binary data) | -2700... 18200 | -2000... 8500 |
| Scaling value (16-bit signed binary data) | - | - |
| External interface ${ }^{* 1}$ |  |  |
| 40-pin connector | - | $\bullet$ |

[^13]
## Analog Output Modules R60DA4 <br> 4-channel (voltage or current) <br> R60DAV8 <br> 8 -channel (voltage) <br> R60DAI8 <br> 8-channel (current) <br> R60DA8-G <br> 8 -channel (voltage or current), channel isolated <br> R60DA16-G <br> 16 -channel (voltage or current), channel isolated

MELSEC iQ-R Series analog output modules reliably deliver accurate analog values to points where
high-resolution digital inputs are required. A variety of modules (voltage, current, or mixed) are available to cover a wide range of application requirements, such as high-speed drive control or variable-speed control of the pressure applied to materials being fed into some kind of forming mechanism.

## Faster, smoother predefined wave signal output

The analog output module enables pre-registration of waveforms easily using MELSOFT GX Works3, realizing a smoother continuous output that closely matches the precision required for the application, such as torque control for a press or injection molding machine. Registering the waveform in the module is simple and easy, and does not require a dedicated analog output program, such as for continuous line control, further reducing programming time.

GX Works3 wave output data setup


Shift operation and scaling without programs
Shift operation and scaling can be used without creating programs; they can be simply set on parameters. This simple setting minimizes program development cost as well as the program size.

## Analog output module specifications

| Item | R60DA4 | R60DAV8 | R60DA18 | R60DA8-G | R60DA16-G |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Number of analog output points (ch) | 4 | 8 | 8 | 8 | 16 |
| Accuracy |  |  |  |  |  |
| Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ | $\pm 0.1 \%$ |
| Ambient temperature $0 \ldots . .55^{\circ} \mathrm{C}$ | $\pm 0.3 \%$ | $\pm 0.3 \%$ | $\pm 0.3 \%$ | - | - |
| Temperature coefficient | - | - | - | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ | $\pm 50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ |
| Conversion speed (ch) | $80 \mu \mathrm{~s}$ | $80 \mu \mathrm{~s}$ | $80 \mu \mathrm{~s}$ | 1 ms | 1 ms |
| Channel isolation | - | - | - | Transformer isolation | Transformer isolation |
| Output short-circuit protection | - | $\bullet$ | $\bullet$ | - | - |
| External supply power (V DC) | 24 | 24 | 24 | - | - |
| Voltage output |  |  |  |  |  |
| Digital input value | -32000... 32000 | -32000... 32000 | - | -32000... 32000 | -32000... 32000 |
| Analog output voltage (V DC) | -10... 10 | -10... 10 | - | -12... 12 | -12... 12 |
| Current output |  |  |  |  |  |
| Digital input value | 0... 32000 | - | 0... 32000 | 0... 32000 | 0... 32000 |
| Analog output current (mA DC) | 0... 20 | - | 0... 20 | 0... 20 | 0... 20 |
| External interface ${ }^{* 1}$ |  |  |  |  |  |
| 18-point screw terminal block | - | - | - | - | - |
| 40-pin connector | - | - | - | $\bullet$ | - (2x) |

[^14]
## Temperature Control Modules R60TCTRT2TT2 <br> 2-channel (multiple input) +2 -channel (thermocouple input)

## R60TCRT4

4-channel (RTD input)

## R60TCTRT2TT2BW

2-channel (multiple input) + 2-channel (thermocouple input) With heater disconnection detection

## R60TCRT4BW

4-channel (RTD input)
With heater disconnection detection

MELSEC iQ-R Series temperature control modules are ideal for applications requiring highly stable and responsive temperature control. The series comes with thermocouple and RTD input module types and are available with or without heater disconnection detection.

## Controlled heating minimizes distortion in heating profile

Temperature fluctuations are attenuated at high speed through the external disturbance suppression function. This enables the preset temperature value to be maintained, ensuring a uniform heating profile not influenced by heating variations in the work. Due to its high-speed response capabilities, this function can be used in applications such as packaging machine sealing, injection molding, and for wafer plates in semiconductor manufacturing machines.


■ External disturbance suppression


## Coordination between multiple temperature control modules

Temperature control modules are equipped with features that enable coordination of up to 64 modules in one control system. The features that support this are as follows:

- Inter-module simultaneous temperature rise
- Inter-module peak current suppression


Inter-module simultaneous temperature rise
Temperature uniformity is realized by aligning the timing of multiple loops when reaching the set value, thereby bringing the temperature profile closer, ensuring a reduction in energy used controlled over multiple zones.


Inter-module peak current suppression
Peak current is reduced by spreading out the control output timing of transistors, thereby ensuring an energy-efficient power consumption cycle. High and low power usage periods are grouped together, realizing a lower peak current overall with up to five groups possible.



Temperature trace realizing real-time temperature waveform monitoring
Setting parameters has been simplified when using the temperature trace feature of GX Works3. This simple-to-use feature enables tracing of various temperature values in real-time, helping to visualize the control performance while adjusting the parameters. Temperature values can also be exported as a CSV file.


Temperature control module performance specifications

| Item | R60TCTRT2TT2 | R60TCRT4 | R60TCTRT2TT2BW | R60TCRT4BW |
| :---: | :---: | :---: | :---: | :---: |
| Number of analog input channels (ch) | 4 | 4 | 4 | 4 |
| Usable thermocouple | B, R, S, K, E, J, T, N, U, L, PLII, W5Re/W26Re | - | B, R, S, K, E, J, T, N, U, L, PL II, W5Re/W26Re | - |
| Usable RTD | Pt100, JPt100 | Pt100, JPt100 | Pt100, JPt100 | Pt100, JPt100 |
| Sampling cycle (4 ch, ms) | 250/500 | 250/500 | 250/500 | 250/500 |
| Control output cycle (s) | 0.5... 100.0 | 0.5...100.0 | 0.5...100.0 | 0.5...100.0 |
| Input impedance (M) | 1 | 1 | 1 | 1 |
| Input filter (0: Input filter OFF) | $0 . . .100 \mathrm{~s}$ | $0 . .100 \mathrm{~s}$ | $0 . . .100 \mathrm{~s}$ | $0 . . .100 \mathrm{~s}$ |
| Sensor correction value setting | (-(full scale of input range)) to full scale of input range |  |  |  |
| Operation at a sensor input disconnection | Upscale processing |  |  |  |
| Temperature control method | PID ON/OFF pulse or two-position control |  |  |  |
| Heater disconnection detection | - | - | - | - |
| Indication accuracy ${ }^{\text {+1 }}$ |  |  |  |  |
| Ambient temperature $25 \pm 5^{\circ} \mathrm{C}$ | $\leq \pm 0.3 \%$ | $\leq \pm 0.3 \%$ | $\leq \pm 0.3 \%$ | $\leq \pm 0.3 \%$ |
| Ambient temperature $0 \ldots . .55^{\circ} \mathrm{C}$ | $\leq \pm 0.7 \%$ | $\leq \pm 0.7 \%$ | $\leq \pm 0.7 \%$ | $\leq \pm 0.7 \%$ |
| PID constants range |  |  |  |  |
| PID constants setting | Setting by auto tuning is available. |  |  |  |
| Proportional band (P) | - When the input range unit is ${ }^{\circ} \mathrm{C}$ or ${ }^{\circ} \mathrm{F}: 0(0.0)$...full scale of input range (depending on the decimal point position) <br> - When the input range is another analog input unit: 0.0...1000.0\% |  |  |  |
| Integral time (I) | $0 . .3600 \mathrm{~s}$ (Set 0 for P control and PD control.) |  |  |  |
| Derivative time (D) | $0 . .3600 \mathrm{~s}$ (Set 0 for P control and PI control.) |  |  |  |
| Transistor output |  |  |  |  |
| Output signal | ON/OFF pulse | ON/OFF pulse | ON/OFF pulse | ON/OFF pulse |
| Rated load voltage (V DC) | 10.. 30 | 10.. 30 | 10.. 30 | 10.. 30 |
| Maximum load current (A) | 0.1/point, 0.4/common | 0.1/point, 0.4/common | 0.1/point, 0.4/common | 0.1/point, 0.4/common |
| Maximum inrush current | $0.4 \mathrm{~A}, 10 \mathrm{~ms}$ | $0.4 \mathrm{~A}, 10 \mathrm{~ms}$ | $0.4 \mathrm{~A}, 10 \mathrm{~ms}$ | $0.4 \mathrm{~A}, 10 \mathrm{~ms}$ |
| External interface*2 |  |  |  |  |
| 18-point screw terminal block | - | - | - (2x) | - (2x) |

[^15]

## Focus points

$>$ Wide range of modules for best-fit motion control needs
$\checkmark$ Motion control programming simplified
$>$ Software-based gear, shaft, transmission, and cam control
$>3$-axis helical interpolation for large-diameter thread milling
$>$ Normal, fast or multi-axis startup
$>$ High-accuracy pulse measurement

MELSEC iQ-R Series simple motion, positioning, and high-speed counter modules are a distinct set of high-accuracy and fast control response intelligent modules that are ideal for applications requiring high-speed and precision.

## Simple motion module

Simple motion modules are easy to setup similar to positional modules and offer high-precision motion controller performance. This is an easy-to-use module specifically designed for highly precise motion control applications, available with connection to either high-speed servo control network (SSCNET II/H) or CC-Link IE Field network depending on the model.


## Positioning module

Capable of high-speed transmission (5M pulses/s $\mathrm{s}^{\star 1}$ ), the positioning module can control up to four axes. This versatile module supports connection to a wide range of motion devices, such as pulse-train input servo amplifiers or stepping motor with a transistor (open collector), or differential driver input interface.
*1: Differential driver output


High-speed counter module
Capable of measurements at up to 8 M pulses $/ \mathrm{s}^{\star 2}$, the high-speed counter module is an ideal low-cost position control solution that provides precise positional tracking when used in combination with an incremental encoder.
*2: Differential input


- Pulse measurement by an encoder
(conveyor control, etc.)
- PWM (pulse-width modulation) system drive control


## Simple Motion Modules

Compatible with
CC-Link IE Field network

## RD77GF4

Up to 4-axis control

## RD77GF8

Up to 8-axis contro

## RD77GF16

Up to 16-axis control

Compatible with
SSCNET III/H

## RD77MS2

Up to 2-axis control

## RD77MS4

Up to 4-axis control
RD77MS8
Up to 8-axis contro

## RD77MS16

Up to 16-axis control

Similar to positioning modules, simple motion modules are capable of a wide range of high-precision control such as positional control, advanced synchronous control, cam control, and speed-torque control. The module line-up includes $2-, 4-$ - 8 -, and 16 -axis models, with setup being done easily by parameters and programming.

## Advanced synchronous control

Software-based synchronous control can be used as an alternative to mechanical control, such as gear, shaft, transmission and cam. In addition, cam control is even easier with cam auto-generation. Synchronous control can be simply operated (start/stop) for each axis, allowing synchronous and positional control axes within the same program.

Synchronous control
All axes are synchronized using a synchronous encoder or servo input axes. Up to 16 control axes can be synchronized when using the synchronous encoder, such as that used for packaging machines, for example.


■ Cam auto-generation
Cam data for a rotary cutter can be generated automatically simply by registering the sheet length, synchronization width, rotary cutter axis dimensions, etc.


## Mark detection

The actual position of the servo motor can be obtained based on the registration mark printed on the high-speed moving film. Compensation of the cutter axis position, based on the registration marks, keeps the constant cutting position.


Speed-torque control (press-fit control)
The motor can be switched to torque control (press-fit mode) without stopping it during positioning. The current position is controlled during the speed/torque control. Therefore the positioning can be done smoothly even after switching back to position control.


Simple motion module specifications

| Item | RD77GF4 | RD77GF8 | RD77GF16 | RD77MS2 | RD77MS4 | RD77MS8 | RD77MS16 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Number of control axes (axis) | 4 | 8 | 16 | 2 | 4 | 8 | 16 |
| Operation cycle (ms) | 0.5, 1.0, 2.0, 4.0 | 0.5, 1.0, 2.0, 4.0 | 0.5, 1.0, 2.0, 4.0 | $\begin{gathered} 0.444,0.888 \\ 1.777,3.555 \end{gathered}$ | $\begin{gathered} 0.444,0.888 \\ 1.777,3.555 \end{gathered}$ | $\begin{gathered} 0.444,0.888 \\ 1.777,3.555 \end{gathered}$ | $\begin{gathered} 0.444,0.888 \\ 1.777,3.555 \end{gathered}$ |
| Control unit | mm , inch, degree, pulse | mm , inch, degree, pulse | mm , inch, degree, pulse | mm, inch, degree, pulse | mm, inch, degree, pulse | mm , inch, degree, pulse | mm , inch, degree, pulse |
| Positioning data (data/axis) | 600 | 600 | 600 | 600 | 600 | 600 | 600 |
| Servo amplifier | MR-J4-GF | MR-J4-GF | MR-J4-GF | MR-J4-B | MR-J4-B | MR-J4-B | MR-J4-B |
| Max. distance between stations (m) | 100 | 100 | 100 | 100 | 100 | 100 | 100 |
| Servo amplifier connection system |  |  |  |  |  |  |  |
| CC-Link IE Field | - | - | - | - | - | - | - |
| SSCNET III/H | - | - | - | - | - | - | - |
| External interface ${ }^{* 1}$ |  |  |  |  |  |  |  |
| 40-pin connector | - | - | - | $\bullet$ | - (2x) | - (2x) | - (2x) |
| Interpolation function |  |  |  |  |  |  |  |
| Linear interpolation (axis) | 2, 3, 4 | 2, 3, 4 | 2, 3, 4 | 2 | 2, 3, 4 | 2, 3, 4 | 2, 3, 4 |
| Circular interpolation (axis) | 2 | 2 | 2 | 2 | 2 | 2 | 2 |
| Control system |  |  |  |  |  |  |  |
| PTP (Point To Point) control | - | $\bullet$ | $\bullet$ | - | - | $\bullet$ | $\bullet$ |
| Trajectory control (linear, arc) | $\bullet$ | - | - | - | - | $\bullet$ | - |
| Speed control | $\bullet$ | - | $\bullet$ | - | $\bullet$ | $\bullet$ | $\bullet$ |
| Speed-position switching control | $\bullet$ | - | - | - | - | - | - |
| Speed-torque control | $\bullet$ | - | - | - | $\bullet$ | $\bullet$ | - |
| Pressure control | - | - | - | - | - | - | - |
| Advanced synchronous control | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Acceleration/deceleration process |  |  |  |  |  |  |  |
| Trapezoidal acceleration/deceleration | $\bullet$ | $\bullet$ | $\bullet$ | - | $\bullet$ | $\bullet$ | $\bullet$ |
| S-curve acceleration/deceleration | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Function |  |  |  |  |  |  |  |
| Absolute positioning system*2 | $\bullet$ | - | $\bullet$ | - | - | - | - |
| Mark detection function | $\bullet$ | - | $\bullet$ | - | $\bullet$ | $\bullet$ | $\bullet$ |

[^16]
## Positioning Modules

Transistor output
200k pulse/s
RD75P2
Up to 2-axis (linear/circular interpolation)
RD75P4
Up to 4-axis (linear/circular/helical interpolation)

Differential driver output
5M pulse/s

## RD75D2

Up to 2-axis (linear/circular interpolation)
RD75D4
Up to 4-axis (linear/circular/helical interpolation)

The MELSEC iQ-R Series offers a choice of two positioning modules, transistor output or differential drive output, depending on the connected amplifier. The modules are capable of transmission speeds up to $5 \mathrm{M} \mathrm{pulses} / \mathrm{s}$, and the differential driver output module supports wiring up to a distance of 10 m . It can be used in positional control or speed control, and features include linear, circular, and helical interpolation, which is a complex control required for deep-thread milling applications.

## Various positional control

Various different positional control is performed by the module, from manual control, advanced control, to zero return control where it is required for the process position to return to its starting point. Automated sealing and gluing applicators tend to require extensive positional control as the interpolation may require a profile consisting of linear and circular paths that need to be followed accurately, such as in the automotive industry when glues are applied to the sealing portions of the doors.


## Multiple startup options

Positioning modules are capable of multiple different position-start options such as normal startup where the starting trigger command is activated from the command pulse; fast-start, where an event-driven trigger is asynchronous to the execution program data analysis; and multi-axis startup, where multiple axes can be executed simultaneously from an output pulse. In addition, block-start is where multiple sequential positioning data are executed by a single start trigger, which is used in control that follows the same repetitive path.


4 path profiles (P1...P4) being drawn in sequence.


## Realize helical interpolation

For applications that require the boring of deep, large holes, usually multiple interpolation control of three axes ( X , $Y$ and $Z$ ) or more must be taken into consideration. In such cases, the actual milling is done in a circle, with the $X$ and $Y$ axes synchronized to achieve the pre-set size. The depth of the hole is simultaneously controlled along the Z axis, ensuring minimal deviation in the cutting bit position. This type of positioning is usually quite difficult as the interpolation of the three axes can introduce some deviation when not utilizing a full-scale numerical control system.


Positioning module specifications

| Item | Transistor output |  | Differential driver output |  |
| :---: | :---: | :---: | :---: | :---: |
|  | RD75P2 | RD75P4 | RD75D2 | RD75D4 |
| Number of control axes (axis) | 2 | 4 | 2 | 4 |
| Control unit | mm , inch, degree, pulse | mm , inch, degree, pulse | mm , inch, degree, pulse | mm , inch, degree, pulse |
| Positioning data (data/axis) | 600 | 600 | 600 | 600 |
| Module backup function | Positioning data, and block start data can be saved on flash ROM (battery-less backup) |  |  |  |
| Starting time (1 axis linear control) (ms) | 0.3 | 0.3 | 0.3 | 0.3 |
| Max. output pulse (pulse/s) | 200,000 | 200,000 | 5,000,000 | 5,000,000 |
| Max. connection distance between servos (m) | 2 | 2 | 10 | 10 |
| Interpolation |  |  |  |  |
| Linear interpolation (axis) | 2 | 2, 3, 4 | 2 | 2, 3, 4 |
| Circular interpolation (axis) | 2 | 2 | 2 | 2 |
| Helical interpolation (axis) | - | 3 | - | 3 |
| Control system |  |  |  |  |
| PTP (Point To Point) control | $\bullet$ | - | - | - |
| Path control (linear, arc, helical) | - | - | - | - |
| Speed control | $\bullet$ | $\bullet$ | $\bullet$ | $\bullet$ |
| Speed-position switching control | $\bullet$ | - | - | - |
| Position-speed switching control | $\bullet$ | - | - | - |
| Acceleration/deceleration process |  |  |  |  |
| Trapezoidal acceleration/deceleration | $\bullet$ | $\bullet$ | - | $\bullet$ |
| S-curve acceleration/deceleration | $\bullet$ | $\bullet$ | - | $\bullet$ |
| Fast-start function |  |  |  |  |
| Positioning start signal ( $\mu \mathrm{s}$ ) | 8 | 8 | 8 | 8 |
| External command signal ( $\mu \mathrm{s}$ ) | 20 | 20 | 20 | 20 |
| External interface ${ }^{* 1}$ |  |  |  |  |
| 40-pin connector | - | - (2x) | - (2x) | - (2x) |

*1: For more information about external interface (for applicable options, please refer to the relevant product manual), refer to the option lists on page 90 .

## High-Speed Counter Modules

DC input,<br>transistor (sink) output<br>RD62P2<br>2-channel

DC input, transistor (source) output

RD62P2E
2-channel

Differential input, transistor (sink) output

## RD62D2

2-channel

The MELSEC iQ-R Series counter modules are capable of 200k pulse/s for the DC input type, and 8M pulse/s for differential input. When used with a high-accuracy incremental encoder, positional tracking can also be realized. It also features a PWM output, which is ideal for applications requiring a measurement of pulse cycles.

## Pulse measurement

The pulse measurement feature enables measuring of the pulse cycle, which is ideal for various applications such as in the food and beverage industry where proximity sensors are used to control flask position on the conveyor, or the renewable energy industry where the wind vane angle is controlled on a wind turbine.


## High-speed PWM output

The PWM output frequency can support up to 200 kHz with a minimum 100 ns pulse width (proportion to 'on' time) during the required duty cycle. The set values can be changed during operation without having to stop the system, such as in industrial-scale fan control.

High-speed counter module specifications

| Item | RD62P2 | RD62P2E | RD62D2 |
| :---: | :---: | :---: | :---: |
| Number of channels (ch) | 2 | 2 | 2 |
| Count input signal |  |  |  |
| 1-phase input (1 multiple/2 multiples) | $\bullet$ | - | $\bullet$ |
| 2-phase input (1 multiple/2 multiples/4 multiples) | - | - | - |
| CW/CCW input | - | - | - |
| Signal level ( $\phi \mathrm{A}, \phi \mathrm{B}$ ) | 2... 5 mA at $5 / 12 / 24 \mathrm{~V}$ DC | $2 . .5 \mathrm{~mA}$ at $5 / 12 / 24 \mathrm{~V}$ DC | EIA Standard RS-422-A Differential line driver level |
| Counter |  |  |  |
| Counting speed (pulse/s) | 10k...200k | 10k...200k | 10k...8M |
| Counting range (32-bit signed binary) | -2147483648...2147483647 | -2147483648...2147483647 | -2147483648...2147483647 |
| External input |  |  |  |
| Preset, function start | 7... 10 mA at 5/12/24 V DC | 7... 10 mA at $5 / 12 / 24 \mathrm{~V}$ DC | 7... 10 mA at 5/12/24 V DC |
| Digital filter (ms) | 0, 0.1, 1, 10 | 0, 0.1, 1, 10 | 0, 0.1, 1, 10 |
| Pulse measurement |  |  |  |
| Resolution*1 (ns) | 100 | 100 | 100 |
| Number of points per channel | 1 | 1 | 1 |
| External output |  |  |  |
| Coincidence output (2 points/channel) | Transistor (sink type) output, 12/24 V DC, 0.5 A/point | Transistor (source type) output, 12/24 V DC, 0.1 A/point | Transistor (sink type) output, 12/24 V DC, 0.5 A/point |
| PWM output |  |  |  |
| Output frequency range (kHz) | 0... 200 | 0... 200 | 0... 200 |
| Duty ratio | Multiples of $0.1 \mu \mathrm{~s}$ | Multiples of $0.1 \mu \mathrm{~s}$ | Multiples of $0.1 \mu \mathrm{~s}$ |
| Number of output points per channel | 2 | 2 | 2 |
| Setting change during operation | - | - | - |
| External interface*2 |  |  |  |
| 40-pin connector | - | - | - |

*1: Pulse measurement can be performed in the range of 2000 to 2147483647 ( 0.2 ms to approx. 214 s ).

The network and interface modules of the MELSEC iQ-R Series ensure a vast selection of interconnectivity possibilities with various protocols and network topologies providing the best-fit solution for various applications. At the core of the Series is the CC-Link IE network family which is a high-speed 1 Gbps control level and field level Ethernet topology industrial open network.

## Seamless message protocol (SLMP*1) network communications

With SLMP, it is possible to seamlessly access production management systems, programmable controllers and other devices using the same method, eliminating concerns about network hierarchies and boundaries. Tasks such as machine monitoring, data collection and maintenance can be performed from virtually anywhere on the network. Used together with the Ethernet module, SLMP-ready Ethernet devices such as a machine vision sensor or RFID controller can be interfaced to the CC-Link IE Field Network without further adding another network.


[^17]Ethernet Interface Module

## RJ71EN71

1 Gbps, 100/10 Mbps multiple network type

## CC-Línk IE

The MELSEC iQ-R Series Ethernet module is equipped with two ports that can be used as either a generic Ethernet, CC-Link IE Field or Control Network module. The module design incorporates an easy-to-read display and a dot-matrix LED providing a quick way to assess network conditions using the module.

## Dual gigabit Ethernet ports

The number of connectable ports on the Ethernet module has been doubled and the number of connections per channel increased. By increasing the number of ports the module can be used effectively as a gateway, simultaneously connecting a generic Ethernet network to one port and using the second port for the CC-Link IE Field or Control network. Additionally, the number of connections per channel has been increased from 64 to 128, doubling the bandwidth for even more connectable devices.


Select network combination from within GX Works3.

- Network combination ${ }^{* 1}$


C : CC-Link IE Control Network
F: CC-Link IE Field Network
E:Ethernet
*1: The CC-Link IE Field and CC-Link IE Control networks cannot be used together.

## Ethernet interface module specifications

| Item | RJ71EN71*2 |
| :---: | :---: |
| Transmission specifications |  |
| Data transmission speed | $1 \mathrm{Gbps} / 100 \mathrm{Mbps} / 10 \mathrm{Mbps}$ |
| Interface | RJ45 connector (Auto MDI/MDI-X) |
| Max. frame size (byte) | 1518/9022 (when jumbo frames are used) |
| IP version | Compatible with IPv4 |
| Sending/receiving data storage memory |  |
| Number of simultaneous open connections | 128 |
| Fixed buffer | 5 K words x 16 |
| Socket communications | - 5 K words x 48 (when only P1 is used) <br> - 5 K words $\times 112$ (when only P1/P2 is used) |
| Random access buffer | 6 K words x 1 |
| CC-Link IE Field/Control cable specifications |  |
| Communication cable | Ethernet cable (Category 5e or higher, double shielded/STP) |

## CC-Link IE Control Network Module <br> RJ71GP21-SX <br> 1 Gbps optical cable, control/normal station

## CC-Línk IE Control

CC-Link IE Control is a high-reliability distributed control network designed to handle very large data communications (128K word) over a high-speed
(1 Gbps) dual-loop optical cable topology.


## Continuous communications even when cable or stations are faulty

Utilizing a high-speed, noise resistant fiber-optic topology, the CC-Link IE Control Network supports a loop-back function that guarantees continuous communications even when a cable is disconnected or a station falls into a fault status. The dual-loop topology of the cable ensures that the data will find another route along the network without affecting overall network communications.


## Extensive real-time network monitoring

The network status can be easily monitored directly from GX Works3 software enabling intuitive troubleshooting of network errors or viewing the operation of the network while in communications. This makes it possible to see the actual fault occurring in the network, thereby helping to reduce the overall downtime. In addition, error messages related to the faulty network module station can be viewed for further network diagnosis. All stations within the network can be monitored regardless of which station the software is connected too.


CC-Link IE Control Network module specifications

| Item | RJ71GP21-SX |
| :---: | :---: |
| Communication speed | 1 Gbps |
| Transmission path | Duplex loop |
| Communication cable | Optical fiber cable which satisfies 1000 BASE-SX standard: Multi-mode optical fiber (GI) |
| Max. station-to-station distance (m) | 550 (when the core outer diameter is $50 \mu \mathrm{~m}$ ) 275 (when the core outer diameter is $62.5 \mu \mathrm{~m}$ ) |
| Overall cable distance (m) | 66,000 (when 120 stations are connected and the core outer diameter is $50 \mu \mathrm{~m}$ ) 33,000 (when 120 stations are connected and the core outer diameter is $62.5 \mu \mathrm{~m}$ ) |
| Max. number of connectable stations | 120 (control station: 1, normal station: 119) |
| Max. number of link points per network |  |
| Link relay (LB) | 32 K points ( 32768 points, 4K bytes) |
| Link register (LW) | 128 K points ( 131072 points, 256K bytes) |
| Link input (LX), link output (LY) | 8 K points (8192 points, 1K bytes) |

## CC-Link IE Field Network Module

## RJ71GF11-T2

1 Gbps, master/local station

## CC-Línk IE Field

CC-Link IE Field is a versatile gigabit Ethernet-based network integrating controller, I/O control, safety control, and motion control in a flexible wiring topology supporting star, ring, and line configurations.


## Multiple topology variations

Star topology
Devices are connected via a switching hub allowing local stations to be added easily.

- Line topology

Continuous connection of devices along the Ethernet line.


## Synchronized network communications

The control cycle of local stations on the network can be synchronized with the master station.


CC-Link IE Field Network module specifications

| Item | RJ71GF11-T2 |
| :---: | :---: |
| Transmission speed | 1 Gbps |
| Network topology | Line topology, star topology (both types can be on the same line), and ring topology |
| Communication cable | Ethernet cable (Category 5e or higher, double shielded/STP) |
| Max. station-to-station distance (m) | 100 |
| Overall cable distance (m) | Line topology: 12,000 (when 121 stations are connected) <br> Star topology: Depends on the system configuration Ring topology: 12,100 (when 121 stations are connected) |
| Max. number of connectable stations | 121 (master station: 1, slave station: 120) |
| Max. number of link points per network |  |
| Remote input (RX), remote output (RY) | 16K points (16384 points, 2 K bytes) |
| Remote register (RWw, RWr) | 8 K points (8192 points, 16K bytes) |

## CC-Link IE Field Network

## Remote Head Module

## RJ72GF15-T2 NEw

1 Gbps, remote station

## CC-Línk IE Field

The CC-Link IE Field head module can control the I/O and intelligent function modules directly when installed on the same base unit, and can operate as a network remote station. Installing two remote head modules improves network reliability by having redundant network lines, and supports online module replacement (hot-swap) when a module needs to be changed while the system is still in operation.


## Remote station with redundant head modules and network

Network system reliability can be improved by installing redundant head modules and redundant network cables; even if an error occurs in one of the head modules, the network standby module can take over without disrupting network communications and initiates the control system to switch to the standby system. In addition, if one of the head modules is replaced, the settings and parameters are automatically transferred to the standby module and re-initialized.


CC-Link IE Field Network remote head module specifications

| Item | RJ72GF15-T2 |
| :---: | :---: |
| Transmission speed | 1 Gbps |
| Network topology | Line topology, star topology (both types can be on the same line), and ring topology |
| Communication cable | Ethernet cable (Category 5e or higher, double shielded/STP) |
| Max. station-to-station distance (m) | 100 |
| Overall cable distance (m) | Line topology: 12,000 (when 121 stations are connected) <br> Star topology: Depends on the system configuration Ring topology: 12,100 (when 121 stations are connected) |
| Max. number of connectable stations | 121 (master station: 1, slave station: 120) |
| Max. number of link points per network |  |
| Remote input (RX), remote output (RY) | 16K points (16384 points, 2K bytes) |
| Remote register (RWw, RWr) | 8 K points (8192 points, 16K bytes) |

## AnyWireASLINK Master Module

## RJ51AW12AL New

DigitalLinkSensor AnyWireASLINK system compatible

## AnyWireASLINK

AnyWireASLINK is a sensor-level network that realizes a smaller installation space and reduces wiring owing to its easy wiring topology. The ability to monitor the network system from a centralized location reduces commissioning time and improves productivity.


Preventive maintenance by monitoring of sensor status
Using the AnyWireASLINK system, parameter settings

■ AnyWireASLINK
Prevent intermittent stops

- Analyze the amount of incoming light
- Sensitivity threshold can be adjusted to keep operation up to the maintenance cycle



## Various devices connected with less wiring

Overall wiring of various sensors can be reduced using the AnyWireASLINK connection system.

- ASLINKER (2-wire general-purpose I/O device)
- ASLINKTERMINAL (general-purpose I/O terminal for 4/8/16 points)
- ASLINKSENSOR (sensor directly connected to AnyWireASLINK)
- ASLINKAMP (sensor amplifier connecting a general-purpose sensor head)



## AnyWireASLINK master module specifications

| Item |  |
| :--- | :---: |
| Max. number of I/O points | 512 points (256 input points/256 output points) |
| Max. number of connectable modules | 128 (varies according to each slave module's current consumption) |
| Overall cable distance ${ }^{\star 1}(\mathrm{~m})$ | $200 \mathrm{~m}^{\star 2}$ |
| Topology | Bus (multi-drop, T-branch, tree branch) |
| Communication clock | 27.0 kHz |
| Max. communication cable supply current ${ }^{\star 1}(\mathrm{~A})$ | 2 (when using $1.25 \mathrm{~mm}^{2}$ cable) |

[^18]
## CC-Link System Module

## RJ61BT11

Max. 10 Mbps, master/local station (CC-Link Ver.2)

## CC-Link[V]

CC-Link is a high-speed and highly reliable deterministic I/O control network that realizes reduced wiring while offering multi-vendor compatible products.


## Multiple connectivity of field devices

CC-Link incorporates many different field devices that can be configured into a wire-saving communications network. Using the remote device net mode, it is possible to connect up to 64 remote devices, such as analog I/O modules.


| Item | RJ61BT11 |
| :--- | :---: |
| Transmission speed (bps) | $156 \mathrm{k} / 625 \mathrm{k} / 2.5 \mathrm{M} / 5 \mathrm{M} / 10 \mathrm{M}$ |
| Network topology | Bus (RS-485) |
| Communication cable | Ver.1.10-compatible CC-Link dedicated cable |
| Overall distance (m) | 100 (10 Mbps)...1200 (156 kbps) |
| Max. number of connected modules | 65 stations (master station: 1, slave station: 64) |
| Max. number of link points per system (CC-Link Ver.2) |  |
| Remote I/O (RX, RY) | 8192 points |
| Remote register (RWw, RWr) | 2048 points |

## Serial Communication Modules

## RJ71C24

Max. 230.4 kbps, RS-232 (1 channel), RS-422/485 (1 channel)

## RJ71C24-R2

Max. 230.4 kbps, RS-232 (2 channels)

## RJ71C24-R4

Max. 230.4 kbps, RS-422/485 (2 channels)


The serial communication module enables serial devices with up to 230.4 kbps transmission speeds to be connected per channel. Communications protocols such as MODBUS® ${ }^{\circledR}$ are supported via the pre-defined protocol feature.


| Item | RJ71C24 | RJ71C24-R2 | RJ71C24-R4 |
| :---: | :---: | :---: | :---: |
| Transmission speed (bps) | $1.2 \mathrm{k} / 2.4 \mathrm{k} / 4.8 \mathrm{k} / 9.6 \mathrm{k} / 14.4 \mathrm{k} / 19.2 \mathrm{k} / 28.8 \mathrm{k} / 38.4 \mathrm{k} / 57.6 \mathrm{k} / 115.2 \mathrm{k} / 230.4 \mathrm{k}$ |  |  |
| Interface |  |  |  |
| CH1 | RS-232 | RS-232 | RS-422/485 |
| CH2 | RS-422/485 | RS-232 | RS-422/485 |
| Overall transmission distance |  |  |  |
| RS-232 (m) | 15 | 15 | - |
| RS-422/485 (m) | 1,200 | - | 1,200 |

> Direct access to II system database

- C/C++ based programming
- Installation of various communications protocols
- High-speed collection of shop floor data in real-time
> Utilize third-party partner applications
e.F@ctory
e-F@ctory is a solution from Mitsubishi Electric helping to optimize production systems through its direct connectivity between an IT system and the shop floor reducing cost over the entire product life cycle. Production data management, analysis and planning utilizing loT* can be realized, improving productivity through preventive maintenance, operations management, traceability, and energy management. The MELSEC iQ-R Series includes a range of products that fulfill these various needs as part of the "Intelligence" lineup of interconnected e-F@ctory advanced information products.
* Internet of Things


## Direct access to IT system database

Realize improved production management and reduce overall system costs through real-time direct access to IT system database servers without requiring additional programming and gateway computers.

C/C++ based programming
Provides a robust and cost-efficient alternative from computer-based analytical and testing systems, enabling custom applications to be executed directly on the control system. In addition, various communications protocols can be installed directly.

## High-speed data logging simplifies troubleshooting

Managing production line data, accurate identification of failures and keeping daily/monthly records can be realized at a low cost.

Note: For information about the C Controller, please refer to page 40

## MES Interface module RD81MES96 <br> Database connection

Along with ever-changing manufacturing trends, improving machine productivity and maintaining manufacturing quality through meticulous traceability have become a fundamental part of manufacturing. MES Interface modules address these requirements by providing direct database connectivity for IT systems and facilitating automatic SQL*1 text generation using intuitive configuration setup software. Modules allow production data from the shop floor to be inserted into database records directly; for example, providing real-time production status that enables quicker response to production-related problems.

*1: Structured Query Language is a programming language designed for managing data in a relational database. computers, the MES Interface saves on maintenance costs typical of computers.


MES Interface module specifications

| Item | RD81MES96 |
| :---: | :---: |
| Database connection |  |
| Supported database*3 | Oracle ${ }^{\oplus}$ Database, Microsoft ${ }^{\oplus}$ SQL Server, Microsoft ${ }^{\oplus}$ Access |
| SQL text | SELECT, INSERT, UPDATE, DELETE, Multi-SELECT, STORED PROCEDURE |
| Database communication action field | 65,536 |
| Accessible CPU module ${ }^{* 3}$ | iQ-R Series (Direct, Remote), Q Series (Remote), L Series (Remote) |
| Data sampling interval |  |
| High speed data sampling (ms) | Sequence scan time synchronization, 1... 900 |
| General data sampling (s) | 0.1...0.9, 1... 3600 |
| Function |  |
| DB record read/write | Reads/writes data in the database of the host information system |
| Device memory read/write | Reads/writes device memory data of the CPU module |
| Trigger condition monitoring | Monitors values of the time or device tag components etc., and starts jobs when a trigger condition changes from false to true (the condition is satisfied) |
| Data operation and processing | Performs four arithmetic operations, obtains remainder, performs character string operation, etc. |
| Program execution | Executes a program on the server through a MES Interface module |
| DB buffering | Buffers the data sent to the database, and resend it after recovery, when the data cannot be linked due to the disconnection of the network between MES Interface module and the database or failure of the database etc. |

[^19]
# High-speed Data Logger Module RD81DL96 <br> Data collection 

The production process data acquisition feature of this high-speed data logger module contributes to improving production quality and efficiency, thereby realizing optimal production processes. The module enables logging of various data such as Unicode, CSV, and BIN text formats, which can be utilized for spreadsheet reporting owing to the automatic report generation feature: BIN text format data can be ported directly to Microsoft ${ }^{\circledR}$ Windows ${ }^{\circledR}$ Excel ${ }^{\circledR}$. Logging files can also be automatically sent to a FTP server or directly into a Microsoft ${ }^{\circledR}$ Windows ${ }^{\circledR}$ share folder.


## Data logging synchronized with control system scan time

Acquired data can be synchronized with the control system scan time and achieve sampling rates up to 0.5 ms , realizing a higher resolution that enables changes in control data to be captured.

High-speed data sampling function: 0.5 ms (max.)


## Easier root cause analysis

Event-driven data can be acquired right before and after the trigger occurrence, improving the recovery time of the control system.


## Utilize data for various analysis and maintenance processes

Various data, such as the frequency and duration of a specific operation that has been satisfied, can be utilized for preventative maintenance and machine operation/trend analysis.

High-speed data logger module specifications

| Item | RD81DL96 |
| :---: | :---: |
| Accessible CPU modules | iQ-R Series (Direct, Remote), Q Series (Remote), L Series (Remote) |
| Data sampling interval |  |
| High-speed data sampling (ms) | - Sequence scan time synchronization <br> - 0.5...0.9, 1... 32767 (for trigger logging) <br> - 2... 32767 (for continuous logging) |
| General data sampling (s) | - 0.1...0.9, 1... 32767 <br> - Time interval specification (specify hour/minute/second) |
| Amount of sampled data |  |
| High-speed data sampling | - Overall amount of data: 32768 (per setting: 1024) <br> - Overall number of device points: 32768 (per setting: 4096) |
| General data sampling | - Overall amount of data: 65536 (per setting: 1024) <br> - Overall amount of data: 262144 (per setting: 4096) |
| Function |  |
| Data logging | Logs CPU module device values at specified data sampling intervals. |
| Event logging | Monitors sampled device values from the CPU module, and logs events that occur. |
| Report | Outputs the data sampled by the high speed data logger module as an Excel ${ }^{\oplus}$ file. |
| Recipe | Executes the following operations using recipe files stored in the SD memory card: <br> - Transfer device values written on the recipe files to devices in the CPU module. <br> - Transfer device values in the CPU module to the recipe files. |

## C Intelligent Function Module RD55UP06-V <br> C/C++ program execution

The C Intelligent function module is available with a multi-core ARM ${ }^{\circledR}$-based controller pre-installed with VxWorks $^{\circledR}$ Version 6.9, which realizes simultaneous execution of programs, thereby providing a robust and deterministic alternative to computer-based systems. Utilizing a fan-less hardware design, the C Intelligent function module is ideal for clean fab-based environments, where dust circulation can be detrimental to the production environment, and can be used for applications such as in-line production quality testing or as a gateway for various industry-specific communications protocols.


## Realize complex arithmetic equations in C/C++

The C Intelligent Function module enables the execution of C/C++ programs when paired with a standard MELSEC iQ-R Series Programmable Controller CPU, emulating the same features as a standalone C Controller. Representing complex arithmetic and string equations in $\mathrm{C} / \mathrm{C}++$ programs is much easier than implementing in ladder form, thereby reducing overall development time and program size. Additionally, Intellectual property is simplified as the result of separating it from the ladder program.

Controller or Programmable Controller CPU plus C Intelligent Function module

C/C++ program

## Application development in simple steps

CW Workbench*1 is used as the main programming software in C/C++ with a VxWorks ${ }^{\circledR}$ emulator, CW-Sim/ CW-Sim standalone, which allows debugging without requiring any hardware.
*1: For more information, please refer to page 42.
C intelligent function module specifications

| Item | RD55UP06-V |
| :---: | :---: |
| Hardware |  |
| Endian format | Little endian |
| MPU | ARM ${ }^{\text {® }}$ Cortex-A9 Dual Core |
| Working RAM | 128 MB |
| ROM | 12 MB |
| Software |  |
| OS | VxWorks ${ }^{\circledR}$ Version 6.9 |
| Programming language | C/C++ |
| Programming development environment | CW Workbench/Wind River Workbench3.3 |
| Setting/monitoring tool | GX Works3 (SW1DND-GXW3-E)*2 |
| Communication interface |  |
| Ethernet (1000BASE-T/100BASE-TX/10BASE-T) | 1 CH |
| SD memory card slot | $\bullet$ |

${ }^{*}$ 2. Setting and monitoring of the module is integrated within the GX Works3 engineering software.

## Software

## FA Integrated Engineering Software MELSOFT iQ Works

MELSOFT iQ Works is an integrated software suite consisting of GX Works3, MT Works2, GT Works3, RT ToolBox2 mini and FR Configurator2, which are programming software for each respective product. Integration is further enhanced with MELSOFT Navigator as the central system configuration incorporating an easy-to-use, graphical user interface with additional project-sharing features such as system labels and parameters. The advantages of this powerful integrated software suite are that system design is made much easier with a substantial reduction in repetitious tasks, cutting down on errors while helping to reduce the overall TCO.


## System management software

melsoft Navigator
System level graphic-based configuration tool that simplifies the system design by providing a visual representation of the system. System management features such as system-wide parameterization, labels and block reading of project data are also included.

## Programmable controller engineering software melsoft GX Works3

GX Works3 is the latest generation of programming and maintenance software offered by Mitsubishi Electric specifically designed for the MELSEC iQ-R Series control system. It includes many new features such as graphic-based system configuration, integrated motion control setup, multiple language support, providing an intuitive engineering environment solution.

## HMI/GOT screen design software melsoft GT Works3

This graphic operation terminal (GOT) screen creation software is designed with three main features-simplicity, graphics design and operation ease-that help to create graphic screens in fewer steps.

Motion controller engineering software
melsoft MT Works2

This motion control design and maintenance software includes intuitive graphic-based programming together with a digital oscilloscope simulator.

## Robot engineering software

 melsoft RT ToolBox2 miniThis robot setup software supports various steps from programming, to commissioning, evaluation, and maintenance. In addition, improved preventative maintenance is realized through the use of an integrated 3D robot simulator.

## Inverter setup software mELsor FR Configurator2

This software simplifies the setup and maintenance of AC Inverters. Parameters can be registered easily and distributed to multiple inverters when replacing, and activation of the PLC function all from one setup screen.

## Total system centralized configuration

The correlation between the system configuration feature of MELSOFT Navigator and GX Works3, MT Works2 has been further improved. The system design console works in a bidirectional method, enabling the system configuration to be shared across all three software including network level integration without having to re-design the configuration from within the product level programming software(s).


## Effective parameter registration

Registration of module parameters within the system has been further enhanced with parameters being shared bidirectionally between MELSOFT Navigator and GX Works3, MT Works2. Upward registration of parameters to MELSOFT Navigator is also possible as changes are reflected from within the system configuration.


## Unified system label database

The unified label database allows centralized management of global labels across both GX Works3 and GT Works3. The dynamic labeling structure enables system label sharing, which ensures that labels can be used without being conscious of the device associated with that label. The structure is also responsive to system configuration changes without having to modify the labels within the product programming tools.


# GXWarks 



Mitsubishi Electric MELSOFT GX Works3 Promotion Movie

One Software, Many Possibilities

GX Works3 consists of various different components that help to simplify project creation and maintenance tasks. A system design console that enables projects to be created at the system overview stage has been added. Additionally, the main programming languages are supported and their labels (variables) are shared, further simplifying programming. Various debug and maintenance features are also included.


## Project lifecycle engineering

Various features have been consolidated into an integrated engineering environment that enables easier project creation throughout the engineering process, ensuring consistency through every step.

- System-wide design
- Easy system configuration with parts library
- Direct module parameter registration
- Integrated simple motion module setup

■ Multiple programming languages

- Conforms to IEC 61131-3
- Supports main programming languages
- Consistency between different programming tabs

■ Simple to debug

- Various online monitoring
- Hardware simulator (emulator)
- Data logging
- Straightforward maintenance

- System monitoring
- Module and network diagnostics
- Multi-language commenting



## System Design

## System design with a convenient parts library

Most projects start from system design, so having a software application that caters to this initial stage is important. GX Works3 incorporates a system design feature that enables system components to be assembled directly in the programming software. It includes a parts library consisting of MELSEC iQ-R Series modules that can be used to simplify system creation.


Register module parameters on the fly
Another useful feature is the ability to register parameters automatically. Simply double-click on the desired module and the corresponding parameters will be registered in the project. A window with an easy-to-use parameter settings screen opens, enabling module parameters to be modified as needed.


Integrated motion setup tool
GX Works3 is equipped with a special motion setup tool that makes it easy to change simple motion module settings such as module parameters, positioning data and servo parameters. Also, debugging is simplified using the fine-tuning cam data generation feature.



## Programming

## Central parts library

GX Works3 comes with an updated object library pre-installed in the software consisting of a module library with current modules at time of software release although this can be added to as newer modules become available. A variety of other objects are available such as third-party partner function blocks. The library can be fully shared across multiple projects.


## Reduce repetitive program tasks

Global and local variables (labels) are supported providing an easy way to share device names across multiple projects, other MELSOFT software and third party SCADA. The variables can be registered into either the current program, function block as a local variable or within the project as a global variable to share across multiple programs within the same project. Variables specific to a particular module are also available, and can be used immediately, further reducing engineering time and cost.


Main programming languages supported
The main IEC languages are supported by GX Works3. Various different programming languages can be used within the same project simultaneously and can be viewed easily via the menu tab. The variables and devices used in each program can be shared across multiple platforms, with user defined function blocks supported.



## Debug

## Easy version management

Being able to visually see and manage different versions of the same project can help to reduce debugging processes. Even with a number of engineers are working on the same project, changes made are easily recognized directly from the program or as an automatically generated verification results list. This feature is available for locally stored projects on the computer, and between the program stored in the programmable controller CPU.

Online data operation


Verification results


Graphical representation of differences


## Hardware simulation

GX Works3 features an integrated simulator which helps to visualize the operation of the program during the debugging process. Motion control CPU hardware can be simulated as well.

Offline debugging without a control CPU required




## Simplified troubleshooting reduces downtime even further

GX Works3 incorporates various maintenance features helping to reduce downtime and keep productivity high． Various levels of maintenance are possible，from system－wide monitoring of errors and module status to monitoring at the network level；for example，detailed operations that show where programs or parameters have been changed in the CPU and the monitoring of system events，which also includes a useful historical function that can be exported as a CSV file．


## Multi－language menu，ideal for global support

The menu system can be switched between various languages，enabling different locations to work on the same project with the same programming software version．In addition，device comments within the project can be switched between various languages without having to create multiple copies of the same project to support the comments in different languages．


Language version of comments being switched

| COMMENT［Device Comment］ |  |  |
| :---: | :---: | :---: |
| Device Name | X0 | Conditions |
| Device Name | Japanese／日本語 | English（Display Target） |
| X0 | 運較スイイ少チ | Start operation |
| $\times 1$ | センサ | Sensor |
| Y0 |  | Start nnavatimn（avt moniva umr） |
| X3 | センサ（㙏設ココバア） | Sensor（ext conve yor） |

# Extensive global support coverage providing expert help whenever needed 

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## Factory Automation Global website

Mitsubishi Electric Factory Automation provides a mix of services to support its customers worldwide. A consolidated global website is the main portal, offering a selection of support tools and a window to its local Mitsubishi Electric sales and support network.

■ From here you can find:

- Overview of available factory automation products
- Library of downloadable literature
- Support tools such as online e-learning courses, terminology dictionary, etc.
- Global sales and service network portal
- Latest news related to Mitsubishi Electric factory automation

Mitsubishi Electric Factory Automation
Global website:
www.MitsubishiElectric.com/fa


## Online e-learning

An extensive library of e-learning courses covering the factory automation product range has been prepared. Courses from beginner to advanced levels of difficulty are available in various languages.


[^20]
## Innovative next-generation, e-Manual

The e-Manual viewer is a next-generation digital manual offered by Mitsubishi Electric that consolidates all manuals into an easy-to-use package with various useful features integrated into the viewer. The e-Manual is modeled around a centralized database allowing multiple manuals to be cross-searched at once, further reducing the time for reading individual product manuals when setting up a control system.


Key features include

- Included with GX Works3 engineering software
- Also available in tablet version
- Easily download manuals all at once
- Automatic update of manual versions
- Search information across multiple manuals
- Visual navigation from hardware diagram showing various specifications
- Customizable by adding user notes and bookmarks
- Directly port sample programs within manuals to GX Works3

MITSUBISHI ELECTRIC FA e-Manual (tablet version)


The e-Manual application is available on iOS and Android ${ }^{\text {TM }}$ tablets.
e-Manual files are provided as in-app downloads.


■ Supported versions

| OS | OS version | Model |
| :---: | :---: | :---: |
| iOS | iOS 8.1 or later | Apple iPad 2, iPad (3rd generation), iPad (4th generation), iPad Air, iPad Air 2, iPad mini, iPad mini 2, iPad mini 3 |
| Android ${ }^{\text {™ }}$ | Android ${ }^{\text {TM }}$ 4.3/4.4/5.0 | ASUS Nexus7 ${ }^{\text {TM }}$ (2013) ${ }^{\text {*1 }}$ |

[^21]
## CC-Link Partner Association (CLPA) - Actively promoting worldwide adoption of CC-Link networks

## Proactively supporting CC-Link, from promotion to specification development

The CC-Link Partner Association (CLPA) was established to promote the worldwide adoption of the CC-Link open-field network. By conducting promotional activities such as organizing trade shows and seminars, conducting conformance tests, and providing catalogs, brochures and website information, CLPA activities are successfully increasing the number of CC-Link partner manufacturers and CC-Link-compatible products. As such, CLPA is playing a major role in the globalization of CC-Link.


Visit the CLPA website for the latest CC-Link information.
URL:www.cc-link.org


## Global influence of CC-Link continues to spread

CC-Link is supported globally by CLPA. With offices throughout the world, support for partner companies can be found locally. Each regional CLPA office undertakes various support and promotional activities to further the influence of CC-Link/CC-Link IE in that part of the world. For companies looking to increase their presence in their local area, CLPA is well placed to assist these efforts through offices in all major regions.


■ General specifications

| Item | Specification |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Operating ambient temperature | 0...55 ${ }^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Storage ambient temperature | $-25 . . .75^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Operating ambient humidity | $5 . . .95 \% \mathrm{RH}$, non-condensing |  |  |  |  |  |
| Storage ambient humidity | 5...95\% RH, non-condensing |  |  |  |  |  |
| Vibration resistance | Compliant with JIS B 3502 and IEC 61131-2 | - | Frequency | Constant acceleration | Half amplitude | Sweep count |
|  |  | Under intermittent | 5 ... 8.4 Hz | - | 3.5 mm | 10 times each in |
|  |  | vibration | 8.4... 150 Hz | $9.8 \mathrm{~m} / \mathrm{s}^{2}$ | - | $\mathrm{X}, \mathrm{Y}, \mathrm{Z}$ directions |
|  |  | Under continuous | 5 ... 8.4 Hz | - | 1.75 mm |  |
|  |  | vibration | $8.4 . . .150 \mathrm{~Hz}$ | $4.9 \mathrm{~m} / \mathrm{s}^{2}$ | - |  |
| Shock resistance | Compliant with JIS B 3502 and IEC $61131-2\left(147 \mathrm{~m} / \mathrm{s}^{2}, 3\right.$ times each in directions X, Y, Z) |  |  |  |  |  |
| Operating atmosphere | No corrosive gases ${ }^{* 4}$, no flammable gases, no excessive conductive dust |  |  |  |  |  |
| Operating altitude*1 | 0... $2000 \mathrm{~m}^{* 5}$ |  |  |  |  |  |
| Installation location | Inside a control panel |  |  |  |  |  |
| Overvoltage category*2 | $\leq$ II |  |  |  |  |  |
| Pollution degree ${ }^{* 3}$ | $\leq 2$ |  |  |  |  |  |
| Equipment class | Class $2^{* 6}$ |  |  |  |  |  |

${ }^{*}$ : Do not use or store the programmable controller under pressure higher than the atmospheric pressure of altitude 0 m . Doing so may cause malfunction. When using the programmable controller under pressure, please consult your local Mitsubishi Electric representative.
*2: This indicates the section of the power supply to which the equipment is assumed to be connected between the public electrical power distribution network and the machinery within premises. Category $\mathbb{I}$ applies to equipment for which electrical power is supplied from fixed facilities. The surge voltage withstand level for up to the rated voltage of 300 V is 2500 V .
*3: This index indicates the degree to which conductive material is generated in terms of the environment in which the equipment is used
Pollution level 2 is when only non-conductive pollution occurs. A temporary conductivity caused by condensing must be expected occasionally
*4: The special coated product, which meets the regulation (JIS C 60721-3-3/IEC 60721-3-3 3C2) related to corrosive gas, is available for the use in a corrosive gas environment. For more details on the special coated product, please consult your local Mitsubishi Electric representative.
*5: When used at an altitude higher than 2000 m , the upper limits of the permissible voltage and the operating ambient temperature become lower. Please consult your local Mitsubishi Electric representative
*6: Class 1 when the RQ extension base unit is used.

## ■ Software operating environment

| Item | MELSOFT GX Works3, CW Configurator | CW Workbench, CW-Sim, CW-Sim Standalone |
| :---: | :---: | :---: |
| Personal computer | Windows ${ }^{\text {® }}$ supported personal computer |  |
| CPU | Intel ${ }^{\text {® }}$ Core ${ }^{\text {TM }} 2$ Duo Processor 2 GHz or more |  |
| Available hard disk capacity | 5 GB | 4 GB or more |
| Display resolution | $1024 \times 768$ pixels or higher |  |
| Required memory |  |  |
| 64-bit edition | 2 GB or more recommended | 2 GB or more |
| 32-bit edition | 1 GB or more recommended | $\begin{gathered} 1 \mathrm{~GB} \text { or more } \\ (2 \mathrm{~GB} \text { or more recommended) } \end{gathered}$ |
| OS (English version) |  |  |
| Microsoft ${ }^{\text {W }}$ Windows ${ }^{\circledR} 8.1$ Operating System | $\bullet$ | - *7 |
| Microsoff ${ }^{\text {W }}$ Windows ${ }^{\text {® }}$ 8.1 Pro Operating System | - | - *7 |
| Microsoft ${ }^{\text {W }}$ Windows ${ }^{\circledR}$ 8.1 Enterprise Operating System | $\bullet$ | - ${ }^{*}$ |
| Microsoft ${ }^{\oplus}$ Windows ${ }^{\circledR} 8$ Operating System | - | - *7 |
| Microsoft ${ }^{\text {W }}$ Windows ${ }^{\ominus} 8$ Pro Operating System | $\bullet$ | - ${ }^{* 7}$ |
| Microsoft ${ }^{\ominus}$ Windows ${ }^{\ominus} 8$ Enterprise Operating System | - | - *7 |
| Microsoft ${ }^{\ominus}$ Windows ${ }^{\ominus} 7$ Starter Operating System | $\bullet$ | - |
| Microsoft ${ }^{\text {W }}$ Windows ${ }^{\oplus} 7$ Home Premium Operating System | $\bullet$ | - |
| Microsoff ${ }^{\text {W }}$ Windows ${ }^{\oplus} 7$ Professional Operating System | $\bullet$ | ** |
| Microsoff ${ }^{\text {® }}$ Windows ${ }^{\oplus} 7$ Ultimate Operating System | $\bullet$ | ${ }^{+8}$ |
| Microsoff ${ }^{\ominus}$ Windows ${ }^{\oplus} 7$ Enterprise Operating System | $\bullet$ | ** |
| Microsoft ${ }^{\text {® }}$ Windows Vista ${ }^{\oplus}$ Home Basic Operating System | -* | - |
| Microsoft ${ }^{\text {® }}$ Windows Vista ${ }^{\oplus}$ Home Premium Operating System | -* | - |
| Microsofte Windows Vista ${ }^{\ominus}$ Business Operating System | - ${ }^{+}$ | - |
| Microsoft ${ }^{\ominus}$ Windows Vista® ${ }^{\text {® }}$ Ultimate Operating System | -* | - |
| Microsoft ${ }^{\text {® }}$ Windows Vista ${ }^{\text {® }}$ Enterprise Operating System | - ${ }^{+}$ | - |
| Microsoft ${ }^{\text {W }}$ Windows ${ }^{\text {® }}$ XP Professional Operating System SP3 | - ${ }^{\text {a }}$ | ** |
| Microsoft ${ }^{\text {W }}$ Windows ${ }^{\oplus}$ XP Home Edition Operating System SP3 | - *9 | - |
| 7: Windows Touch is not supported. | ${ }^{9} 9$ : The 64 -bit edition is not supported. |  |

*8: Windows ${ }^{\star}$ XP Mode is not supported.

MELSOFT GX Works3-supported CPU modules

| Item | Model |  |
| :--- | :--- | :--- |
| Programmable controller | R04(EN)CPU | R32(EN)CPU |
| CPU | R08(EN)CPU | R120(EN)CPU |
|  | R16(EN)CPU |  |
| Safety CPU | R08SFCPU | R32SFCPU |
|  | R16SFCPU | R120SFCPU |
| Process CPU | R08PCPU | R32PCPU |
|  | R16PCPU | R120PCPU |

## MELSOFT CW Configurator-supported CPU modules

| Item | Model |
| :--- | :---: |
| C Controller | R12CCPU-V |

## Product List

■ CPU modules

| Type | Model | Outline |
| :---: | :---: | :---: |
| Programmable controller CPU | R04CPU | Program capacity, 40K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R08CPU | Program capacity, 80 K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R16CPU | Program capacity, 160K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R32CPU | Program capacity, 320K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R120CPU | Program capacity, 1200K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R04ENCPU | CC-Link IE embedded; program capacity, 40K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R08ENCPU | CC-Link IE embedded; program capacity, 80K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R16ENCPU | CC-Link IE embedded; program capacity, 160K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R32ENCPU | CC-Link IE embedded; program capacity, 320K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R120ENCPU | CC-Link IE embedded; program capacity, 1200K steps; basic operation processing speed (LD instruction), 0.98 ns |
| Motion CPU | R16MTCPU | Up to 16-axis control; operation cycle, $\leq 0.222 \mathrm{~ms}$; SSCNET II/H connectivity |
|  | R32MTCPU | Up to 32 -axis control; operation cycle, $\leq 0.222 \mathrm{~ms}$; SSCNET II/H connectivity |
|  | R64MTCPU | Up to 64-axis control; operation cycle, $\leq 0.222 \mathrm{~ms}$; SSCNET II/H connectivity |
| Safety CPU | R08SFCPU-SET | Program capacity, 80 K steps ( 40 K steps for safety programs); basic operation processing speed (LD instruction), 0.98 ns |
|  | R16SFCPU-SET | Program capacity, 160 K steps ( 40 K steps for safety programs); basic operation processing speed (LD instruction), 0.98 ns |
|  | R32SFCPU-SET | Program capacity, 320 K steps ( 40 K steps for safety programs); basic operation processing speed (LD instruction), 0.98 ns |
|  | R120SFCPU-SET | Program capacity, 1200K steps ( 40 K steps for safety programs); basic operation processing speed (LD instruction), 0.98 ns |
| Process CPU | R08PCPU | Program capacity, 80 K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R16PCPU | Program capacity, 160K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R32PCPU | Program capacity, 320K steps; basic operation processing speed (LD instruction), 0.98 ns |
|  | R120PCPU | Program capacity, 1200K steps; basic operation processing speed (LD instruction), 0.98 ns |
| Redundant function module | R6RFM NEw | By combining with a process CPU a redundant control system can be realized. |
| C Controller | R12CCPU-V | Endian format, little endian; OS, VxWorks ${ }^{\ominus}$ Version 6.9 |
| SD memory card* ${ }^{* 1}$ | NZ1MEM-2GBSD | SD memory card, 2G bytes |
|  | NZ1MEM-4GBSD | SDHC memory card, 4G bytes |
|  | NZ1MEM-8GBSD | SDHC memory card, 8G bytes |
|  | NZ1MEM-16GBSD | SDHC memory card, 16G bytes |
| Extended SRAM cassette | NZ2MC-1MBS | 1M bytes |
|  | NZ2MC-2MBS | 2M bytes |
|  | NZ2MC-4MBS | 4M bytes |
|  | NZ2MC-8MBS | 8M bytes |
|  | NZ2MC-8MBSE*2 | 8M bytes |
|  | NZ2MC-16MBS | 16M bytes |
| Battery | Q6BAT | Replacement battery |
|  | Q7BAT | Replacement large-capacity battery |
|  | Q7BAT-SET | Large-capacity battery with holder for mounting CPU |

1: Mitsubishi Electric shall not guarantee the operation of any third party products.
*2: ECC type for safety CPU and process CPU modules.
■ Base unit

| Type | Model | Outline |
| :---: | :---: | :---: |
| Main base | R35B | 5 slots, for MELSEC iQ-R Series modules |
|  | R38B | 8 slots, for MELSEC iQ-R Series modules |
|  | R312B | 12 slots, for MELSEC iQ-R Series modules |
| Redundant power supply main base | R310RB ${ }^{\text {NEW }}$ | 10 slots, for MELSEC iQ-R Series modules |
| Extended temperature range main base | R310B-HT | 10 slots, for MELSEC iQ-R Series modules |
| Extended temperature range redundant power supply main base | R38RB-HT NEW | 8 slots, for MELSEC iQ-R Series modules |
| Extension base | R65B | 5 slots, for MELSEC iQ-R Series modules |
|  | R68B | 8 slots, for MELSEC iQ-R Series modules |
|  | R612B | 12 slots, for MELSEC iQ-R Series modules |
| Redundant power supply extension base | R610RB NEW | 10 slots, for MELSEC iQ-R Series modules |
| Extended temperature range extension base | R610B-HT | 10 slots, for MELSEC iQ-R Series modules |
| Extended temperature range redundant power supply extension base | R68RB-HT NEW | 8 slots, for MELSEC iQ-R Series modules |
| RQ extension base | RQ65B | 5 slots, for MELSEC-Q Series modules |
|  | RQ68B | 8 slots, for MELSEC-Q Series modules |
|  | RQ612B | 12 slots, for MELSEC-Q Series modules |
| Extension cable | RC06B | 0.6 m cable for extension and RQ extension base units |
|  | RC12B | 1.2 m cable for extension and RQ extension base units |
|  | RC30B | 3 m cable for extension and RQ extension base units |
|  | RC50B | 5 m cable for extension and RQ extension base units |
| DIN rail mounting adapter | R6DIN1 | For main and extension base units |
|  | Q6DIN1 | For RQ68B/RQ612B |
|  | Q6DIN2 | For RQ65B |
|  | Q6DIN1A | For RQ extension base units (with vibration-proofing bracket sets) |
| Blank cover | RG60 | For I/O slots of main and extension base units |
|  | QG60 | For I/O slots of RQ extension base units |

## ■ Power supply module

| Type | Model | Outline |
| :---: | :---: | :---: |
| Power supply | R61P | AC power supply; input, 100 to 240 V AC; output, $5 \mathrm{~V} \mathrm{DC} / 6.5 \mathrm{~A}$ |
|  | R62P | AC power supply; input, 100 to 240 V AC ; output, $5 \mathrm{~V} \mathrm{DC/3.5} \mathrm{A}$,24 V DC/0.6 A |
|  | R64P | AC power supply; input, 100 to 240 V AC ; output, 5 V DC/9 A |
|  | R63P | DC power supply; input, 24 V DC; output, 5 V DC/6.5 A |
|  | R64RP NEW | AC power supply; input, 100 to 240 V AC; output, 5 V DC/9 A, Redundant power supply function support |

■ I/O modules

| Type | Model | Outline |
| :---: | :---: | :---: |
| Input | RX10 | AC input, 16 points; 100...120 V AC ( $50 / 60 \mathrm{~Hz}$ ) |
|  | RX40C7 | DC input, 16 points; 24 V DC, 7.0 mA |
|  | RX41C4 | DC input, 32 points; 24 V DC, 4.0 mA |
|  | RX42C4 | DC input, 64 points; 24 V DC, 4.0 mA |
| High-speed input | RX40PC6H | Positive common type DC input, 16 points; $24 \mathrm{~V} \mathrm{DC}, 6.0 \mathrm{~mA}$; minimum response time $5 \mu \mathrm{~s}$ |
|  | RX40NC6H | Negative common type DC input, 16 points; 24 V DC, 6.0 mA ; minimum response time $5 \mu \mathrm{~s}$ |
|  | RX41C6HS NEW | Positive/negative common type DC input, 32 points; 24 V DC, 6.0 mA ; minimum response time $1 \mu \mathrm{~s}$ |
|  | RX61C6HS NEW | Positive/negative common type DC input, 32 points; 5 V DC, 6.0 mA ; minimum response time $1 \mu \mathrm{~s}$ |
| Input <br> (with diagnostic functions) | RX40NC6B NEW | Negative common type DC input, 16 points; 24 V DC, 6.0 mA |
| Output | RY10R2 | Relay output, 16 points; 24 V DC/2 A, $240 \mathrm{~V} \mathrm{AC/2} \mathrm{~A}$ |
|  | RY40NT5P | Transistor (sink) output, 16 points; 12 to 24 V DC, 0.5 A |
|  | RY41NT2P | Transistor (sink) output, 32 points; 12 to 24 V DC, 0.2 A |
|  | RY42NT2P | Transistor (sink) output, 64 points; 12 to 24 V DC, 0.2 A |
|  | RY40PT5P | Transistor (source) output, 16 points; 12 to 24 V DC, 0.5 A |
|  | RY41PT1P | Transistor (source) output, 32 points; 12 to 24 V DC, 0.1 A |
|  | RY42PT1P | Transistor (source) output, 64 points; 12 to 24 V DC, 0.1 A |
| High-speed output | RY41NT2H | Transistor (sink) output, 32 points; 5 to 24 V DC, 0.2 A ; minimum response time $2 \mu \mathrm{~s}$ |
|  | RY41PT2H | Transistor (source) output, 32 points; 5 to 24 V DC, 0.2 A ; minimum response time $2 \mu \mathrm{~s}$ |
| Output <br> (with diagnostic functions) | RY40PT5B NEW | Transistor (source) output, 16 points; $24 \mathrm{VDC}, 0.5 \mathrm{~A}$ |
| I/O combined | RH42C4NT2P | DC input, 32 points; 24 V DC, 4.0 mA <br> Transistor (sink) output, 32 points; 12 to 24 V DC, 0.2 A |

■ Analog modules

| Type | Model | Outline |
| :---: | :---: | :---: |
| Analog input | R60AD4 | 4 channels for voltage/current inputs $-10 \ldots 10 \text { V DC, }-32000 \ldots . .32000 ; 0 \ldots 20 \mathrm{~mA} \text { DC, } 0 . . .32000 ; 80 \mu \mathrm{~s} / \mathrm{CH}$ |
|  | R60ADH4 | 4 channels for voltage/current inputs $-10 \ldots 10 \text { V DC, }-32000 \ldots 32000 ; 0 \ldots 20 \mathrm{~mA} \mathrm{DC}, 0 \ldots 32000 ; 5 \mu \mathrm{~s} / 4 \mathrm{CH}$ |
|  | R60ADV8 | 8 channels for voltage inputs $-10 \ldots 10 \text { V DC, }-32000 \ldots 32000 ; 80 \mu \mathrm{~s} / \mathrm{CH}$ |
|  | R60ADI8 | 8 channels for current inputs 0... 20 mA DC/0... $32000 ; 80 \mu \mathrm{~s} / \mathrm{CH}$ |
|  | R60AD8-G | 8 channels for voltage/current input, channel isolated $-10 \ldots 10 \mathrm{~V}$ DC/-32000... $32000,0 . . .20 \mathrm{~mA} \mathrm{DC/0...32000} 10 \mathrm{~ms} /$, |
|  | R60AD16-G | 16 channels for voltage/current input, channel isolated $-10 \ldots 10 \mathrm{~V}$ DC/-32000... $32000,0 . .20 \mathrm{~mA} \mathrm{DC} / 0 . . .32000,10 \mathrm{~ms} / \mathrm{CH}$ |
| Temperature input | R60TD8-G | Thermocouple (B, R, S, K, E, J, T, N), 8 channels for input, channel isolated, $30 \mathrm{~ms} / \mathrm{CH}$ |
|  | R60RD8-G | RTD (Pt100, JPt100, Ni100, Pt50), 8 channels for input, channel isolated, $10 \mathrm{~ms} / \mathrm{CH}$ |
| Temperature control | R60TCTRT2TT2 | Thermocouple (B, R, S, K, E, J, T, N, U, L, PL II, W5Re/W26Re), 4 channels for input (2 channels can also be used for RTD input) |
|  | R60TCRT4 | RTD (Pt100, JPt100), 4 channels for input |
|  | R60TCTRT2TT2BW | Thermocouple (B, R, S, K, E, J, T, N, U, L, PL II , W5Re/W26Re), 4 channels for input ( 2 channels can also be used for RTD input), heater disconnection detection |
|  | R60TCRT4BW | RTD (Pt100, JPt100), 4 channels for input, heater disconnection detection |
| Analog output | R60DA4 | 4 channels for voltage/current outputs $-32000 \ldots 32000,-10 \ldots 10 \mathrm{~V} \text { DC; } 0 . . .32000,0 . . .20 \mathrm{~mA} \mathrm{DC} ; 80 \mu \mathrm{~s} / \mathrm{CH}$ |
|  | R60DAV8 | 8 channels for voltage outputs -32000...32000, -10... 10 V DC; $80 \mu \mathrm{~s} / \mathrm{CH}$ |
|  | R60DAI8 | 8 channels for current outputs 0... $32000,0 . . .20 \mathrm{~mA}$ DC; $80 \mu \mathrm{~s} / \mathrm{CH}$ |
|  | R60DA8-G | 8 channels for voltage/current output, channel isolated -32000...32000/-12... 12 V DC, 0... $32000 / 0 \ldots 20 \mathrm{~mA}$ DC, $1 \mathrm{~ms} / \mathrm{CH}$ |
|  | R60DA16-G | 16 channels for voltage/current output, channel isolated -32000...32000/-12... 12 V DC, 0...32000/0... $20 \mathrm{~mA} \mathrm{DC} 1 \mathrm{~ms} /$, |

■ Motion/Positioning/High-speed counter modules

| Type | Model | Outline |
| :---: | :---: | :---: |
| Simple motion | RD77GF4 | 4 axes, linear/circular interpolation, advanced synchronous control, CC-Link IE Field network compatible |
|  | RD77GF8 | 8 axes, linear/circular interpolation, advanced synchronous control, CC-Link IE Field network compatible |
|  | RD77GF16 | 16 axes, linear/circular interpolation, advanced synchronous control, CC-Link IE Field network compatible |
|  | RD77MS2 | 2 axes, linear/circular interpolation, advanced synchronous control, SSCNETII/H compatible |
|  | RD77MS4 | 4 axes, linear/circular interpolation, advanced synchronous control, SSCNET II/H compatible |
|  | RD77MS8 | 8 axes, linear/circular interpolation, advanced synchronous control, SSCNETII/H compatible |
|  | RD77MS16 | 16 axes, linear/circular interpolation, advanced synchronous control, SSCNETIII/H compatible |
| Positioning | RD75P2 | Transistor output, 2 axes; max. output, 200k pulse/s; linear/circular interpolation |
|  | RD75P4 | Transistor output, 4 axes; max. output, 200k pulse/s; linear/circular/helical interpolation |
|  | RD75D2 | Differential driver output, 2 axes; max. output, 5M pulse/s; linear/circular interpolation |
|  | RD75D4 | Differential driver output, 4 axes; max. output, 5M pulse/s; linear/circular/helical interpolation |
| High-speed counter | RD62P2 | 5/12/24 V DC input, 2 channels; counting speed, max. 200k pulse/s; external output, transistor (sink type) |
|  | RD62P2E | 5/12/24 V DC input, 2 channels; counting speed, max. 200k pulse/s; external output, transistor (source type) |
|  | RD62D2 | Differential input, 2 channels; max. counting speed, 8M pulse/s; external output, transistor (sink type) |

■ Network modules

| Type | Model | Outline |
| :---: | :---: | :---: |
| Ethernet (built-in CC-Link IE) | RJ71EN71 | 1 Gbps/100 Mbps/10 Mbps, 2 ports Multi-network connectivity (Ethernet/CC-Link IE) |
| CC-Link IE Control | RJ71GP21-SX | 1 Gbps , fiber-optic cable, control/normal station |
| CC-Link IE Field | RJ71GF11-T2 | 1 Gbps , master/local station |
| CC-Link IE Field Network remote head | RJ72GF15-T2 NEW | 1 Gbps, remote station |
| CC-Link | RJ61BT11 | Max. 10 Mbps , master/local station, CC-Link Ver. 2 supported |
| AnyWireASLINK | RJ51AW12AL NEW | DigitalLinkSensor AnyWireASLINK system compatible, master station |
| Serial communication | RJ71C24 | Max. 230.4 kbps; RS-232, 1 channel; RS-422/485, 1 channel |
|  | RJ71C24-R2 | Max. 230.4 kbps; RS-232, 2 channels |
|  | RJ71C24-R4 | Max. 230.4 kbps; RS-422/485, 2 channels |

Advanced information modules

| Type | Model | Outline |
| :--- | :--- | :--- |
| MES Interface | RD81MES96 | Database connection (MX MESInterface-R is required) |
| High-speed data logger | RD81DL96 | Data collection (High-speed data logger module tool "SW1DNN-RDLUTL-E"is required)*1 |
| C intelligent function module | RD55UP06-V | C/C++ program execution (Setting and monitoring tool is integrated within GX Works3) |

*1: For information on how to obtain the software, please contact your local Mitsubishi Electric sales office or representative.
■ Software

| Type |  | Model |
| :---: | :---: | :--- |

*2: For detailed information about supported modules, refer to the manuals of the relevant software package.
*3: The MELSOFT GX Works3 menu is switchable between Japanese, English, and simplified Chinese. (Traditional Chinese and Korean will be supported soon.)

| Type | Model |  |
| :--- | :--- | :--- |
| CW Workbench | SW1DND-CWWR-E | Engineering tool for C Controller module |
|  | SW1DND-CWWR-EZ | Additional license for R12CCPU-V, RD55UP06-V |
|  | SW1DND-CWWR-EVZ | Update license for R12CCPU-V, RD55UP06-V |
| CW-Sim | SW1DND-CWSIMR-EZ | VxWorks $^{\oplus}$ simulation environment for CW Workbench, additional license |
| CW-Sim Standalone | SW1DNC-CWSIMSAR-E | VxWorks $^{\oplus}$ simulation environment for CW Workbench, standalone type |
| MELSOFT CW Configurator | SW1DND-RCCPU-E | Setting and monitoring tool for C Controller |
| MX MESInterface-R | SW1DND-RMESIF-E | MES Interface function configuration tool |

■ Option

| Type | Model | Outline |
| :---: | :---: | :---: |
| Connector | A6CON1 | 32 -point connector soldering type (40-pin connector) |
|  | A6CON2 | 32 -point connector crimp-contact type (40-pin connector) |
|  | A6CON3 | 32 -point connector pressure-displacement (flat cable) type (40-pin connector) |
|  | A6CON4 | 32 -point connector soldering type (40-pin connector, cable connectable in bidirectional) |
| Spring clamp terminal block | Q6TE-18SN | For 16-point I/O modules, $0.3 \ldots 1.5 \mathrm{~mm}^{2}(22 . .16$ AWG) |
| Connector/terminal block conversion module | A6TBXY36 | For positive common input modules and sink output modules (standard type) |
|  | A6TBXY54 | For positive common input modules and sink output modules (2-wire type) |
|  | A6TBX70 | For positive common input modules (3-wire type) |
| Connector/terminal block conversion module cable | AC05TB | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 0.5 m |
|  | AC10TB | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 1 m |
|  | AC20TB | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 2 m |
|  | АСЗ0тв | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 3 m |
|  | AC50TB | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 5 m |
|  | AC80тB | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 8 m * |
|  | AC100TB | For A6TBXY36, A6TBXY54, and A6TBX70 (positive common/sink type), 10 m* |
| Relay terminal module | A6TE2-16SRN | For 40-pin connector 24 V DC transistor output modules (sink type) |
| Relay terminal module cable | AC06TE | For A6TE2-16SRN, 0.6 m |
|  | AC10TE | For A6TE2-16SRN, 1 m |
|  | AC30TE | For A6TE2-16SRN, 3 m |
|  | AC50TE | For A6TE2-16SRN, 5 m |
|  | AC100TE | For A6TE2-16SRN, 10 m |

* Common current 0.5 A or lower

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[^0]:    3: Based on a typical application example, the system benchmark test measures the CPU scan time, taking into consideration the network refresh time and monitoring processing time with external devices as compared to Universal model QCPU (QnUDEHCPU).
    *4: Average number of instructions such as for basic instructions and data processing executed in $1 \mu \mathrm{~s}$ (the larger the value, the faster the processing speed),

[^1]:    *1: Please contact your local Mitsubishi Electric office or

[^2]:    1. Seamless Message Protocol (SLMP): A simple client-server common protocol that enables communication between Ethernet products and CC-Link IE-compatible machines.
    Cost comparison of using the MELSEC iQ-R Series R04CPU + RJ71EN71 modules.
    The sub-master and safety communication functions are not supported.
[^3]:    *1: General LAN connection supported by the Ethernet port only.

[^4]:    *1: Based on R120CPU.
    *2: Based on NZ2MC-8MBS (8 MB).

[^5]:    6: NZ2MC-8MBSE is only supported by safety CPU and process CPU.
    7: Safety CPU is not supported.

[^6]:    *1: As compared to current Mitsubishi Electric products.

[^7]:    *Process features such as process tag and faceplate will be supported in the future.

[^8]:    1: Product package includes a safety CPU(R■SFCPU) and safety function module (R6SFM)

[^9]:    The RX42C4 module can be configured to use both sink and source wiring (between the left and right sides of 32 point terminal).
    *2: Based on a comparison with the MELSEC-Q Series

[^10]:    1: For more information about external interface (for applicable options, please refer to the relevant product manual), please refer to the options list on page 90 .

[^11]:    1: For more information about external interface (for applicable options, please refer to the relevant product manual), please refer to the options list on page 90 .

[^12]:    1: For more information about external interface (for applicable options, please refer to the relevant product manual), refer to the options list on page 90

[^13]:    *1: For more information about external interface (for applicable options, please refer to the relevant product manual), refer to the options list on page 90

[^14]:    *1: For more information about external interface (for applicable options, please refer to the relevant product manual), please refer to the options list on page 90 .

[^15]:    1: The accuracy is calculated in the following method. For details, please refer to the manual. (Only when it is not affected by noise.)
    Accuracy $\left({ }^{\circ} \mathrm{C}\right)=($ full-scale $) \times$ (indication accuracy) + cold junction temperature compensation accuracy
    ${ }^{*} 2$ : For more information about external interface (for applicable options, please refer to the relevant product manual), refer to the options list on page 90.

[^16]:    *1: For more information about external interface (for applicable options, please refer to the relevant product manual), refer to the options list on page 90.
    *2: A battery needs to be installed in the servo amplifier for home position backup.

[^17]:    *1: SLMP (Seamless Message Protocol): Is a client/server protocol that enables communications between Ethernet-ready and CC-Link IE compatible devices.

[^18]:    *1: The allowable value varies depending on the transmission cable supply current, total distance, or transmission cable (DP, DN) wire diameter. For details, please refer to the user's manual.
    ${ }^{* 2}$ : With the slave module having an integrated transmission cable (DP, DN) and module, the length of the transmission cable (DP, DN) is included in the overall length.

[^19]:    *3: For details, please refer to the relevant manual.

[^20]:    ■ Beginner level
    Designed for newcomers to Mitsubishi Electric Factory Automation products gaining a background of the fundamentals and an overview of various products related to the course.

    ## $\square$ Basic to Advanced levels

    These courses are designed to provide education at all levels. Various different features are explained with application examples providing an easy and informative resource for in-house company training.

[^21]:    *1: When using a tablet not listed above, 7 -inch (resolution of $1920 \times 1200$ dots (WUXGA)) or better is recommended.

[^22]:    * Not all products are available in all countries.

