SIEMENS

Data sheet

6ES7515-2TN03-0AB0



SIMATIC S7-1500T, CPU 1515T-2 PN, central processing unit with 1.5 MB work memory for program and 4.5 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface: PROFINET RT, 6 ns bit performance, SIMATIC Memory Card required * *** approvals and certificates according to entry 109816881 at support.industry.siemens.com to be observed! ****

Figure similar

General information		
Product type designation	CPU 1515T-2 PN	
HW functional status	FS01	
Firmware version	V3.0	
Product function		
 I&M data 	Yes; I&M0 to I&M3	
• Isochronous mode	Yes; Distributed and central; with minimum OB $6x$ cycle of $375~\mu s$ (distributed) and 1 ms (central)	
Configuration control	Configuration control	
via dataset	Yes	
Display		
Screen diagonal [cm]	6.1 cm	
Control elements		
Number of keys	8	
Mode buttons	2	
Supply voltage		
Rated value (DC)	24 V	
permissible range, lower limit (DC)	19.2 V	
permissible range, upper limit (DC)	28.8 V	
Reverse polarity protection	Yes	
Mains buffering		
 Mains/voltage failure stored energy time 	5 ms	
Repeat rate, min.	1/s	
Input current		
Current consumption (rated value)	0.83 A	
Current consumption, max.	1.03 A	
Inrush current, max.	1.15 A; Rated value	
l²t	0.6 A ² ·s	
Power		
Infeed power to the backplane bus	12 W	
Power consumption from the backplane bus (balanced)	6.2 W	
Power loss		
Power loss, typ.	7.9 W	
Memory		
Number of slots for SIMATIC memory card	1	
SIMATIC memory card required	Yes	
Work memory		
integrated (for program)	1.5 Mbyte	
integrated (for data)	4.5 Mbyte	

Load memory	
 Plug-in (SIMATIC Memory Card), max. 	32 Gbyte
Backup	02 00,10
maintenance-free	Yes
CPU processing times	
	6 nc
for bit operations, typ.	6 ns 7 ns
for word operations, typ.	9 ns
for fixed point arithmetic, typ.	
for floating point arithmetic, typ.	37 ns
CPU-blocks	
Number of elements (total)	8 000; Blocks (OB, FB, FC, DB) and UDTs
Number range Size, max.	1 60 999; subdivided into: number range that can be used by the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999 4.5 Mbyte; For DBs with absolute addressing, the max. size is 64 KB
FB FB	4.5 Mbyte, For DBs with absolute addressing, the max. Size is 64 KB
Number range	0 65 535
Size, max.	1 Mbyte
FC	1 may to
Number range	0 65 535
• Size, max.	1 Mbyte
OB	,
• Size, max.	1 Mbyte
Number of free cycle OBs	100
Number of time alarm OBs	20
Number of delay alarm OBs	20
Number of delay alarm OBs Number of cyclic interrupt OBs	20; With minimum OB 3x cycle of 250 μs
Number of cyclic interrupt OBs Number of process alarm OBs	20, With Hillimitath OB 3x cycle of 230 μs
Number of DPV1 alarm OBs	3
Number of isochronous mode OBs	2
	2
Number of technology synchronous alarm OBsNumber of startup OBs	100
•	
Number of asynchronous error OBsNumber of synchronous error OBs	4
•	2
Number of diagnostic alarm OBs Nesting depth	1
Nesting depth	24
per priority class	47
Counters, timers and their retentivity	
S7 counter	0.040
• Number	2 048
Retentivity	v.
— adjustable	Yes
IEC counter	A (1 P % 11 H (1)
• Number	Any (only limited by the main memory)
Retentivity	v.
— adjustable	Yes
S7 times	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Retentivity	v.
— adjustable	Yes
Data areas and their retentivity	
Retentive data area (incl. timers, counters, flags), max.	512 kbyte; In total; available retentive memory for bit memories, timers, counters, DBs, and technology data (axes): 472 KB
Extended retentive data area (incl. timers, counters, flags), max.	4.5 Mbyte; When using PS 6 0W 24/48/60 V DC HF
Flag	
• Size, max.	16 kbyte
Number of clock memories	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	2, 2 3.500 memory and grouped into one death memory byte
Data NIOONO	

Retentivity adjustable	Yes
Retentivity adjustable Retentivity preset	No
Local data	110
per priority class, max.	64 kbyte; max. 16 KB per block
Address area	• · · · · · · · · · · · · · · · · · · ·
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	o 102, max. number of modules / outsmodules
• Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
Number of subprocess images, max.	32
Hardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	2
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	be inserted in total
Modules per rack, max.	32; CPU + 31 modules
Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots
Time of day	
Clock	
• Type	Hardware clock
Backup time	
-	6 wk; At 40 °C ambient temperature, typically
Deviation per day, max.	6 wk; At 40 °C ambient temperature, typically 10 s; Typ.: 2 s
Deviation per day, max.	
Deviation per day, max. Operating hours counter	10 s; Typ.: 2 s
Deviation per day, max.Operating hours counterNumber	10 s; Typ.: 2 s
 Deviation per day, max. Operating hours counter Number Clock synchronization 	10 s; Typ.: 2 s
 Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave 	10 s; Typ.: 2 s 16 Yes
 Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master 	10 s; Typ.: 2 s 16 Yes Yes
 Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave 	10 s; Typ.: 2 s 16 Yes Yes Yes Yes
 Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP 	10 s; Typ.: 2 s 16 Yes Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface types	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes 2
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet)	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes 2
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet)	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes 2
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes 2
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols Ip protocol	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes: IPv4
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes; X1 2 Yes IPv4 Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes Yes; IPv4 Yes Yes Yes Yes Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes; IPv4 Yes Yes Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols IP protocol PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes Yes Ye
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols IP protocol PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes Yes; X1 2 Yes; IPv4 Yes
Deviation per day, max. Operating hours counter Number Clock synchronization supported in AS, master in AS, slave on Ethernet via NTP Interfaces Number of PROFINET interfaces 1. Interface Interface types RJ 45 (Ethernet) Number of ports integrated switch Protocols IP protocol PROFINET IO Controller PROFINET IO Device SIMATIC communication Open IE communication Web server Media redundancy	10 s; Typ.: 2 s 16 Yes Yes Yes Yes Yes Yes Yes Yes Yes; X1 2 Yes; IPv4 Yes

DO/OD : ('	V
— PG/OP communication	Yes
— Isochronous mode	Yes
 Direct data exchange 	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— PROFlenergy	Yes; per user program
 Prioritized startup 	Yes; Max. 32 PROFINET devices
 Number of connectable IO Devices, max. 	256; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
 Of which IO devices with IRT, max. 	64
 Number of connectable IO Devices for RT, 	256
max.	
— of which in line, max.	256
 Number of IO Devices that can be 	8; in total across all interfaces
simultaneously activated/deactivated, max.	
 Number of IO Devices per tool, max. 	8
— Updating times	The minimum value of the update time also depends on communication
·	share set for PROFINET IO, on the number of IO devices, and on the
	quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	$250~\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the
	minimum update time of 375 µs of the isochronous OB is decisive
— for send cycle of 500 μs	500 μs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
With IRT and parameterization of "odd" send	Update time = set "odd" send clock (any multiple of 125 μs: 375 μs, 625
cycles	μs 3 875 μs)
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 µs	500 μs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
	4 ms to 512 ms
— for send cycle of 4 ms	4 1115 10 312 1115
PROFINET IO Device	
Services	V
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	Yes
— PROFlenergy	Yes; per user program
— Shared device	Yes
 Number of IO Controllers with shared device, 	4
max.	
 activation/deactivation of I-devices 	Yes; per user program
 Asset management record 	Yes; per user program
2. Interface	
Interface types	
• RJ 45 (Ethernet)	Yes; X2
Number of ports	1
integrated switch	No
Protocols	INO
	Voc. IDv/
IP protocol PROFINET IO Controller	Yes; IPv4
PROFINET IO Controller PROFINET IO Province	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	No
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— Isochronous mode	No
 Direct data exchange 	No
— IRT	No
— PROFlenergy	Yes; per user program
	1 CO. DEL USEI DIOUIGIII
Prioritized startup	No

 Number of connectable IO Devices, max. 	32; In total, up to 1 000 distributed I/O devices can be connected via
	AS-i, PROFIBUS or PROFINET
 Number of connectable IO Devices for RT, 	32
max.	32
of which in line, max. Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	o, in total across all interfaces
Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication
opading into	share set for PROFINET IO, on the number of IO devices, and on the
	quantity of configured user data
Update time for RT	
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	V.
— PG/OP communication	Yes
— Isochronous mode	No
— IRT	No
— PROFlenergy	Yes; per user program
— Prioritized startup	No
— Shared device	Yes
 Number of IO Controllers with shared device, max. 	4
activation/deactivation of I-devices	Yes; per user program
— Asset management record	
	Yes; per user program
Interface types	
RJ 45 (Ethernet)	N/
• 100 Mbps	Yes
 Autonegotiation 	Yes
Autocrossing	Yes
Industrial Ethernet status LED	Yes
Protocols	
PROFIsafe	No
Number of connections	
 Number of connections, max. 	256; via integrated interfaces of the CPU and connected CPs / CMs
 Number of connections reserved for ES/HMI/web 	10
 Number of connections via integrated interfaces 	128
Number of S7 routing paths	16
Redundancy mode	
H-Sync forwarding	Yes
Media redundancy	
— Media redundancy	only via 1st interface (X1)
— MRP	Yes; MRP Automanager according to IEC 62439-2 Edition 2.0, MRP
MPD interconnection oursetted	Manager; MRP Client
MRP interconnection, supported	Yes; as MRP ring node according to IEC 62439-2 Edition 3.0
— MRPD	Yes; Requirement: IRT
Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
Number of stations in the ring, max. SIMATIC communication	50
PG/OP communication	Yes; encryption with TLS V1.3 pre-selected
S7 routing	
€ 07 Touting	Yes
Data record routing	Yes
Data record routing S7 communication as server	Yes
 S7 communication, as server 	Yes Yes
S7 communication, as serverS7 communication, as client	Yes Yes Yes
S7 communication, as serverS7 communication, as clientUser data per job, max.	Yes Yes
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication	Yes Yes Yes Yes See online help (S7 communication, user data size)
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP 	Yes Yes Yes Yes See online help (S7 communication, user data size) Yes
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. 	Yes Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, 	Yes Yes Yes Yes See online help (S7 communication, user data size) Yes
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, supported 	Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, supported ISO-on-TCP (RFC1006) 	Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes Yes
 \$7 communication, as server \$7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, supported ISO-on-TCP (RFC1006) Data length, max. 	Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes Yes 64 kbyte
 S7 communication, as server S7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, supported ISO-on-TCP (RFC1006) Data length, max. UDP 	Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes Yes 64 kbyte Yes
 \$7 communication, as server \$7 communication, as client User data per job, max. Open IE communication TCP/IP Data length, max. several passive connections per port, supported ISO-on-TCP (RFC1006) Data length, max. 	Yes Yes Yes See online help (S7 communication, user data size) Yes 64 kbyte Yes Yes 64 kbyte

DUOD	V
• DHCP	Yes
• DNS	Yes
SNMP DCP	Yes
• LLDP	Yes Yes
• Encryption	Yes; Optional
Web server	i es, Optional
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	, , , , , , , , , , , , , , , , , , ,
Runtime license required	Yes; "Medium" license required
 OPC UA Client 	Yes; Data Access (registered Read/Write), Method Call
 Application authentication 	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15,
Lieuw and and and and	Basic256Sha256
User authentication	"anonymous" or by user name & password
Number of connections, max. Number of pades of the client interfaces.	10 2 000
 Number of nodes of the client interfaces, recommended max. 	2 000
Number of elements for one call of	300
OPC_UA_NodeGetHandleList/OPC_UA_ReadList/C	
max.	
 Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max. 	20
Number of elements for one call of	100
OPC_UA_MethodGetHandleList, max.	100
Number of simultaneous calls of the client	1
instructions for session management, per	
connection, max.	
 Number of simultaneous calls of the client instructions for data access, per connection, max. 	5
Number of registerable nodes, max.	5 000
Number of registerable method calls of	100
OPC_UA_MethodCall, max.	
 Number of inputs/outputs when calling 	20
OPC_UA_MethodCall, max.	
OPC UA Server	Yes; Data Access (Read, Write, Subscribe), Method Call, Alarms & Condition (A&C), Custom Address Space
 Application authentication 	Yes
Security policies	available security policies: None, Basic128Rsa15, Basic256Rsa15,
Cooling periods	Basic256Sha256, Aes128Sha256RsaOaep, Aes256Sha256RsaPss
 User authentication 	"anonymous" or by user name & password
 — GDS support (certificate management) 	Yes
Number of sessions, max.	48
 Number of accessible variables, max. 	100 000
 Number of registerable nodes, max. 	20 000
 Number of subscriptions per session, max. 	50
— Sampling interval, min.	100 ms
— Publishing interval, min.	100 ms
Number of server methods, max. Number of inputs (cutruits per server method)	50
 Number of inputs/outputs per server method, max. 	20
Number of monitored items, recommended	4 000; for 1 s sampling interval and 1 s send interval
max.	, •
 Number of server interfaces, max. 	10 of each "Server interfaces" / "Companion specification" type and 20
	of the type "Reference namespace"
 Number of nodes for user-defined server interfaces, max. 	30 000
Alarms and Conditions	Yes
Number of program alarms	200
Number of alarms for system diagnostics	100
Further protocols	
• MODBUS	Yes; MODBUS TCP
S7 message functions	
Number of login stations for message functions, max.	64
Program alarms	Yes
Number of configurable program messages, max.	10 000; Program messages are generated by the "Program_Alarm"
3 1 0	

Number of loadable program messages in RUN, max. Number of simultaneously active program alarms Number of program alarms Number of alarms for system diagnostics Number of alarms for motion technology objects Test commissioning functions Joint commission (Team Engineering) Status block Single step	block, ProDiag or GRAPH 5 000 1 000 200 160 Yes; Parallel online access possible for up to 8 engineering systems Yes; Up to 8 simultaneously (in total across all ES clients) No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
 Number of variables, max. 	
of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
• Forcing	Yes
• Forcing, variables	Peripheral inputs/outputs
Number of variables, max.	200
Diagnostic buffer	V
• present	Yes
Number of entries, max.	3 200
— of which powerfail-proof	500
Traces	A. Un to E40 VD of data mantanas are assailais
Number of configurable Traces	4; Up to 512 KB of data per trace are possible
Interrupts/diagnostics/status information	
Diagnostics indication LED	
RUN/STOP LED	Yes
• ERROR LED	Yes
MAINT LED	Yes
 STOP ACTIVE LED 	Yes
Connection display LINK TX/RX	Yes
Connection display LINK TX/RX Supported technology objects	
Supported technology objects	Yes; Note: The number of technology objects affects the cycle time of
Supported technology objects Motion Control Number of available Motion Control resources for	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects Motion Control Number of available Motion Control resources for technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool
Supported technology objects Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400
Supported technology objects Motion Control • Number of available Motion Control resources for technology objects • Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40
Supported technology objects Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — for each set of kinematics	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources per speed-controlled axis per positioning axis per synchronous axis per external encoder per output cam per cam track per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources per cam (1 000 points and 50 segments) per each set of kinematics Per leading axis proxy	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cach set of kinematics — Per leading axis proxy Positioning axis — Number of positioning axes at motion control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — for each set of kinematics — Per leading axis proxy Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — for each set of kinematics — Per leading axis proxy Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value)	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — for each set of kinematics — Per leading axis proxy Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120 2 20 30 30 3 11
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — per leading axis proxy Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120 2 20 30 30 3 11 20 Yes; Universal PID controller with integrated optimization
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — per leading axis proxy Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) Controller PID_Compact PID_Compact PID_Step	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120 2 20 30 30 3 11 20 Yes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves
Motion Control Number of available Motion Control resources for technology objects Required Motion Control resources — per speed-controlled axis — per positioning axis — per synchronous axis — per external encoder — per output cam — per cam track — per probe Number of available Extended Motion Control resources for technology objects Required Extended Motion Control resources — per cam (1 000 points and 50 segments) — per cam (10 000 points and 50 segments) — per leading axis proxy Positioning axis — Number of positioning axes at motion control cycle of 4 ms (typical value) — Number of positioning axes at motion control cycle of 8 ms (typical value) Controller PID_Compact	Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool 2 400 40 80 160 80 20 160 40 120 2 20 30 30 3 11 20 Yes; Universal PID controller with integrated optimization

High-speed counter	Yes
Ambient conditions	
Ambient temperature during operation	
horizontal installation, min.	-30 °C; No condensation
 horizontal installation, max. 	60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off
 vertical installation, min. 	-30 °C; No condensation
vertical installation, max.	40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off
Ambient temperature during storage/transportation	
• min.	-40 °C
• max.	70 °C
Altitude during operation relating to sea level	
 Installation altitude above sea level, max. 	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual
configuration / header	
configuration / programming / header	
Programming language	
— LAD	Yes
— FBD	Yes
— STL	Yes
— SCL	Yes
— GRAPH	Yes
Know-how protection	
 User program protection/password protection 	Yes
 Copy protection 	Yes
Block protection	Yes
Access protection	
 protection of confidential configuration data 	Yes
 Password for display 	Yes
 Protection level: Write protection 	Yes
 Protection level: Read/write protection 	Yes
 Protection level: Write protection for Failsafe 	No
Protection level: Complete protection	Yes
programming / cycle time monitoring / header	
 lower limit 	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	70 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	535 g
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4/2/2023

last modified: