

# OAK-D

[docs.luxonis.com/projects/hardware/en/latest/pages/BW1098OAK.html](https://docs.luxonis.com/projects/hardware/en/latest/pages/BW1098OAK.html)



## Overview

The OAK-D baseboard has three on-board cameras which implement stereo and RGB vision, piped directly into the OAK SoM for depth and AI processing. The data is then output to a host via USB 3.1 Gen1 (Type-C).

## Hardware specifications

This OAK camera uses USB-C cable for communication and power. It supports both USB2 and USB3 (5Gbps / 10Gbps).

Camera Specs	Color camera	Stereo pair
Sensor	<u>IMX378</u>	<u>OV9282</u>
DFOV / HFOV / VFOV	81° / 69° / 55°	82° / 72° / 50°
Resolution	12MP (4032x3040)	1MP (1280x800)
Focus	Auto-Focus: 8cm - ∞	Fixed-Focus: 19.6cm - ∞
Max Framerate	60 FPS	120 FPS
F-number	2.0	2.2
Lens size	1/2.3 inch	1/4 inch

Camera Specs	Color camera	Stereo pair
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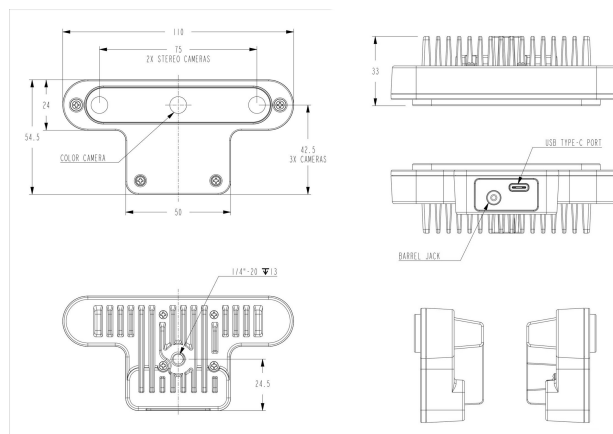
Pixel size	1.55 $\mu$ m x 1.55 $\mu$ m	3 $\mu$ m x 3 $\mu$ m
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## Myriad X inside

This OAK camera has on-board **Myriad X** VPU ([product pdf](#)). Main features:

- **4 TOPS** of processing power (1.4 TOPS for AI)
- **Run any AI model**, even custom architected/built ones - models need to be converted.
- **Encoding**: H.264, H.265, MJPEG - 4K/30FPS, 1080P/60FPS
- **Computer vision**: warp/dewarp, resize, crop via [ImageManip](#) node, edge detection, feature tracking. You can also run custom CV functions
- **Stereo depth** perception with filtering, post-processing, RGB-depth alignment, and high configurability
- **Object tracking**: 2D and 3D tracking with [ObjectTracker](#) node

## Dimensions and Weight



**Weight:** 115g total, OAK-D-PCBA 43g

## Depth perception

This OAK camera has a baseline of 7.5cm - the distance between left and right stereo camera. Minimal and maximal depth perception depends on camera FOV, resolution, and baseline - more information [here](#).

- Min perceivable distance: ~20cm (400P, extended), ~35cm (400P **OR** 800P, extended), ~70cm (800P)

