

### DHM5 - DHK5 - DHO5

### **INCREMENTAL IO-LINK ENCODERS**

#### Introduction

Built from a solid and reliable mechanical and electrical platform, this product series was built from the ground up for reliability and robustness. Electrical protection is built in to reduce "first installation" errors. Mechanically, the high precision sealed bearings mean long life, even in harsh conditions. And the product is tested and rated to perform from -40 to +85°C. This is the best all around encoder in a 58mm package for heavy duty industrial use.



#### **Features**

- Incremental encoder with IO-link programmable parameters
- IO-Link COM3 with minimal cycle time of 1ms
- Absolute position available via IO-link
- Easy programming with standard IO-Link tool
- Simple device replacement with Data Storage capability
- Universal Electronic Circuits from 4.75 to 30 Vdc
- Robust and excellent resistance to shock and vibration
- High protection level IP65, IP67 option with a sealing flange
- Operating temperature range from -40°C to 85°C
- Standard M12 connector available

### **Applications**

- Factory automation
- Motor feedback
- Conveyors
- · Automated warehousing
- General industrial system monitoring and feedback



#### Mechanical

		DHM5	DHK5	DHO5			
Material		Cover: Zinc Alloy Body: Aluminium Shaft: Stainless Steel					
Bearings		6000 Series	6803 3	Series			
Maximum Loads  Axial		50 N 20 N					
WidXilliulli Lodus	Radial	100 N	50 N				
Shaft inertia		2,5.10 <sup>-6</sup> kg.m <sup>2</sup> (10mm)	2,9.10-6 kg.m <sup>2</sup> (14mm)	3,2.10-6 kg.m <sup>2</sup> (14mm)			
Torque		4.10 <sup>-3</sup> N.m	16.10-3 N.m	20.10 <sup>-3</sup> N.m			
Permissible Max. S	peed	12 000 min <sup>-1</sup>	6 000 min <sup>-1</sup>				
Continuous Max. Sp	eed	10 000 min <sup>-1</sup>	10 000 min <sup>-1</sup> 6 000 min <sup>-1</sup>				
Encoder Weight (Ap	prox.)	0,300 kg					
Theoretical Mechan (F <sub>axial</sub> / F <sub>radial</sub> )	nical Lifetime 10º turns	30 N / 60 N : 26	20 N / 40	) N : >36			

### Electrical

This encoder series offers an incremental encoder augmented by IO-Link configurability and diagnostics capabilities. There are two different implementations:

- Incremental encoder and IO-link on a dedicated wire (RGZ electronics)
- Incremental encoder with IO-link multiplexed on Z wire, in this case when working in a mode, the other one is disabled (RGY electronics)

١	Ver.	Mode	Output Signals	Operating Voltage	Supply current (no loads)	Current per channel pair	Short- circuit proof	Reverse polarity tolerant	Frequency Capability	Resolution	Temperature range
F	RGY RGZ	Incremental	programmable (HTL or TTL)	4,75V to 30V	< 75mA	< 40mA	Yes	Van	Up to 1MHz	programmable (1 to 10kppr)	40°C to +85°C
F		IO-Link	IO-Link	18V to 30V				Yes	IO-link COM3 (230,4 kbits/s)	programmable (1 to 16bits)	

<sup>(1)</sup> RGY outputs are multiplexed, they are in incremental mode or IO-link mode (default startup mode is incremental)

#### Environmental

Shocks (EN 60068-2-27)	$\leq$ 500 m.s $^2$ (during 6 ms)					
Vibrations (EN 60068-2-6)	≤ 200 m.s <sup>-2</sup> (102 000Hz))					
EMC	EN 61000-6-2, EN 61000-6-4					
Isolation	1 000V eff					
Operating Temperature	-40 + 85°C (encoder T°)					
Storage Temperature	-40 + 85°C					
Protection (EN 60529)	IP 65					
Humidity	98% RH non-condensing at 20 °C					

#### **IO-LINK** features

#### **Process data**

• Position : single turn 16 bits max

• Speed: calculated speed in rpm (signed)

#### **Programmable Parameters**

- Direction : clockwise or counter-clockwise, changes counting direction and speed sign.
- Set Zero Pulse command: Set the current position as the incremental zero pulse position. Set also the absolute position to zero.

#### For incremental mode:

Incremental resolution: number of cycles per turn: from 1 to 10000

• Output voltage level: HTL or TTL

• Zero pulse width: 90°, 180° 270° or 360° (See figure for details)

#### Absolute parameters (in IO-Link mode):

• Resolution per turn: 1 to 16 bits

• Speed window calculation: time between each speed data update.

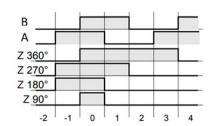
#### **Diagnostics**

• Operating Hours: number of hours since factory reset

• Temperature : event triggers when temperature exceeds specifications

· Device Status: Access to the status of the encoder

Table 1: Z pulse width definition



<sup>(2)</sup> RGZ have Incremental and IO-link outputs working simulaneously

#### **Factory settings**

Name	Index	Factory Setting	Comment
Encoder Output	70	1 : HTL	Set the incremental output voltage
Incremental	71	1024	Set the incremental resolution
Rotation direction	72	false : CW	Set the rotation direction
Z pulse width	74	0 : 90°	Set the zero pulse format (see table 1)
Enter in Factory setup mode	75	0: Encoder mode	Do not use
Speed calculation window	80	1 : 200ms	Time between each speed data update
Absolute Position Resolution	90	16	Resolution of the turn counter (in bits)
Operating-hours	110	0	Number of hours with device on



# STANDARD CONNECTIONS

## Electronics RGY: Incremental OR IO-link on Z (multiplexed)

		INC	GND	VCC	Α	В	Z	A/	B/	Z/	Ground
	Mode	IO-link	L-	L+	NC	NC	IO- link	NC	NC	NC	NC
GM	M12 8 pins		1	2	3	4	5	6	7	8	shield
BF	M12 5 pins	3	1	2	5	4	-	-	-	shield	

### Electronics RGZ: Incremental AND IO-link (simultaneous)

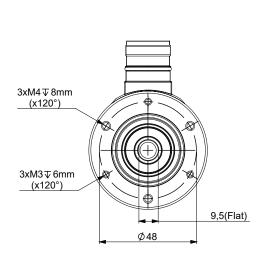
		GND (L-)	VCC (L+)	A	В	Z	A/	B/	Z/	10-link	Ground
<b>16</b>	M23 12 pins CW	1	2	3	4	5	6	7	8	9	shield

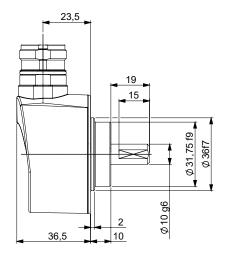


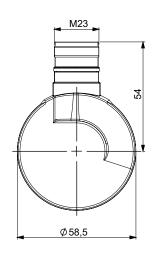
# **DIMENSIONS**

All dimensions are in millimeters.

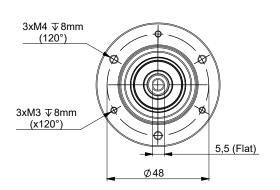
## DHM5\_10 Connection I6R (Radial M23)

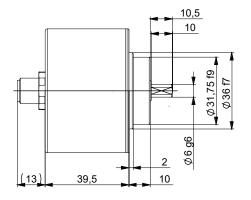


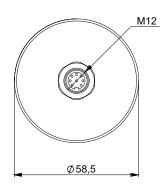




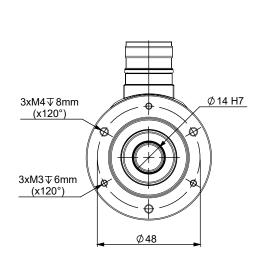
## DHM5\_06 Connection GMA (Axial M12)

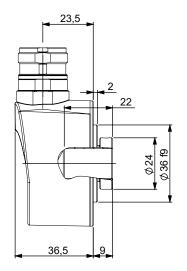


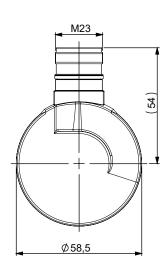




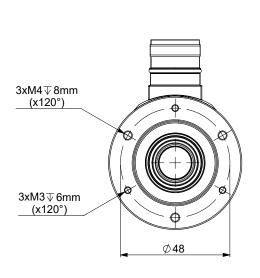
DHK5\_14 Connection I6R (Radial M23)

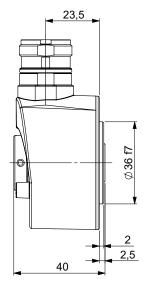


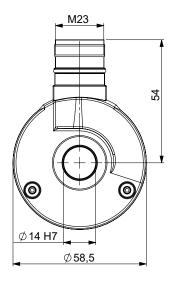




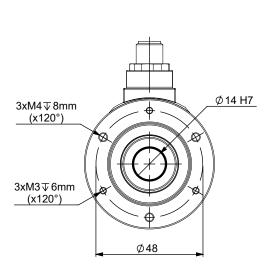
DH05\_14 Standard clamping, Connection I6R (Radial M23)

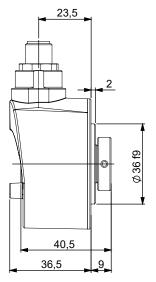


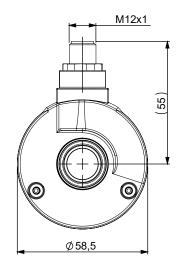




# DH05S14/0M/ Flange side clamping, Connection GMR (Radial M12)

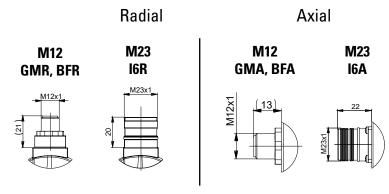








### **CONNECTION DIMENSIONS**

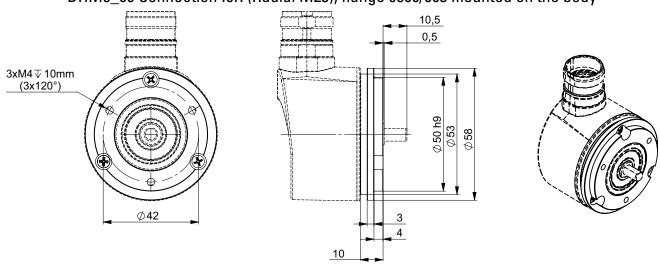




### FLANGE AND COUPLING INTERFACES

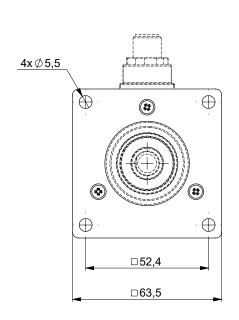
All flange or coupling kits shall be ordered separately (see accessories section).

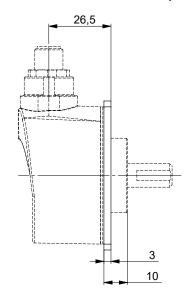
### DHM5\_06 Connection I6R (Radial M23), flange 9500/003 mounted on the body



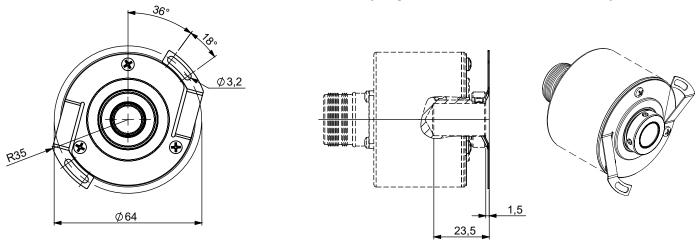
BEISENSORS

DHM5\_10 Connection GMR (Radial M12), flange 9500/005 mounted on the body

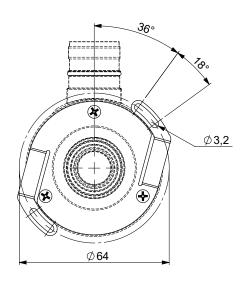


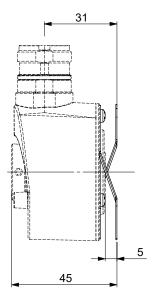


DHK5\_14 Connection I6A (Axial M23), coupling 9445/016 mounted on the body

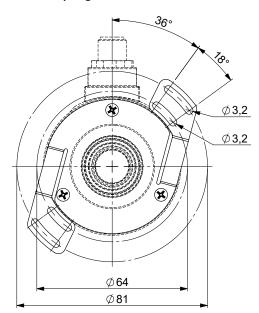


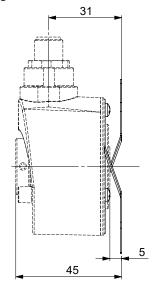
DHO5\_14 Standard clamping, Connection I6R (Radial M23), coupling 9445/012 mounted on the body



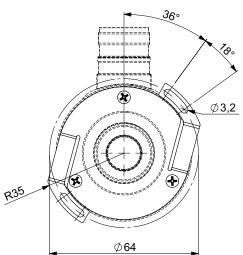


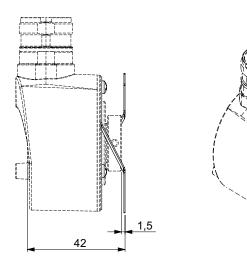
DH05\_14 Standard clamping, Connection GMR (Radial M12), coupling 9445/015 mounted on the body





DH05S14/OM/ Flange side clamping, Connection IPR (Radial M23)", coupling 9445/016 mounted on the body







For an optimized installation meeting industrial standards, refer to the Instructions Manual.

The Instructions Manual provides the technical information (drawings, electrical data, etc...) for a proper integration.



CE UK WOHS O IO-Link



DHM5	06	RGZ	X	/ EPRO	i // I	6
Family		$\top$				
<b>DHM5:</b> Solid Shaft Encoder <b>DHK5:</b> Blind Shaft Encoder <b>DH05:</b> Hollow Shaft Encoder						
Shaft Size	_					
<b>DHM5 06</b> : 6 mm <b>10</b> : 10 mm <b>DHK5 or DH05</b> : <b>14</b> : 14 mm						
Voltage Output						
RGY: 4,75-30V IO-link multiple: (only with M12 connector) RGZ: 4,75-30V programmable of (only with M23 connector)			ut HTL/T			
Channels						
X: programmable outputs						
Cycles / Turn						
EPROG: Full programmable 1-1	Okppr with p	orogramming too	I (IO-Link master)			
Output Termination						
<b>GM</b> : M12 8 Pins (only RGY) <b>BF</b> : M12 5 pins (only RGY) <b>I6</b> : M23 12 Pins CW (only RGZ)						
Output orientation						
R: Radial (All configurations) A: Axial (DHM5 and DHK5 only)						

BEISENSORS



Description		Part Number								
Synchro flange kit Hardware included	<b>₹</b>	M9500/003 Other synchro flanges dimensions available on request								
Square flange kit Hardware included		M9500/005 Other square flanges dimensions available on request								
Mounting bracket Hardware included	>	M9202 (Compatible with all models)								
Reduction sleeve	Insulated (PEEK) DH05 9431/106 9431/108 9431/110 9431/112	DH05 DH05 DHK5 9431/I06 9431/A06 9431/K06 9431/I08 9431/A08 9431/K08 9431/I10 9431/A10 9431/K10								
Stator coupling kit Hardware included	P/N M9445/012 M9445/015 M9445/016	Recommended use/Compatibility DH05 DHK5 & DH05 DHK5 & DH05 DHK5 & DH05 with /OM/ option her stator coupling configurations available	Fixing points 2 4 2							
Tether arm kit Hardware included		M9445/047 (Compatible with DHK5 and DH05 mod								
Bellows coupling	ys coupling  y = 06 to 12 (side 1 bore diameter in mm) y = 06 to 12 (side 2 bore diameter in mm) + Imperial sizes available: 6.35, 9.52, 12.7 (mm) Installation: Refer to Instruction Manual									
Standard Mating Connector 2m, 5m, 10m Mating Cable Assembly	Extension cords compatible with I6 connection option:  RAL-020-001 = M23, PVC cable, 2m  RAL-050-001 = M23, PVC cable, 5m  RAL-100-001 = M23, PVC cable, 10m	connection option:  RAL-020-001 = M23, PVC cable, 2m								
Standard programing cable (only for GMR) IO-Link USB master	·									

Made in France Page 9

Sensata Technologies, Inc. ("Sensata") data sheets are solely intended to assist designers ("Buyers") who are developing systems that incorporate Sensata products (also referred to herein as "components"). Buyer understands and agrees that Buyer remains responsible for using its independent analysis, valuation, and judgment in designing Buyer's systems and products. Sensata data sheets have been created using standard laboratory conditions and engineering practices. Sensata has not conducted any testing other than that specifically described in the published documentation for a particular data sheet. Sensata may make corrections, enhancements, improvements, and other changes to its data sheets or components without notice.

Buyers are authorized to use Sensata data sheets with the Sensata component(s) identified in each particular data sheet. HOWEVER, NO OTHER LICENSE, EXPRESS OR IMPLIED, BY ESTOPPEL OTHERWISE TO ANY OTHER SENSATA INTELLECTUAL PROPERTY RIGHT, AND NO LICENSE TO ANY THIRD PARTY TECHNOLOGY OR INTELLECTUAL PROPERTY RIGHT, IS GRANTED HEREIN. SENSATA DATA SHEETS ARE PROVIDED "AS IS." SENSATA MAKES NO WARRANTIES OR REPRESENTATIONS WITH REGARD TO THE DATA SHEETS OR USE OF THE DATA SHEETS, EXPRESS, IMPLIED, OR STATUTORY, INCLUDING ACCURACY OR COMPLETENESS. SENSATA DISCLAIMS ANY WARRANTY OF TITLE AND ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE, QUIET ENJOYMENT, QUIET POSSESSION, AND NON-INFRINGEMENT OF ANY THIRD PARTY INTELLECTUAL PROPERTY RIGHTS WITH REGARD TO SENSATA DATA SHEETS OR USE THEREOF.

All products are sold subject to Sensata's terms and conditions of sale supplied at www.sensata.com SENSATA ASSUMES NO LIABILITY FOR APPLICATIONS ASSISTANCE OR THE DESIGN OF BUYERS' PRODUCTS. BUYER ACKNOWLEDGES AND AGREES THAT IT IS SOLELY RESPONSIBLE FOR COMPLIANCE WITH ALL LEGAL, REGULATORY, AND SAFETY-RELATED REQUIREMENTS CONCERNING ITS PRODUCTS, AND ANY USE OF SENSATA COMPONENTS IN ITS APPLICATIONS, NOTWITHSTANDING ANY APPLICATIONS-RELATED INFORMATION OR SUPPORT THAT MAY BE PROVIDED BY SENSATA.

Mailing Address: Sensata Technologies, Inc., 529 Pleasant Street, Attleboro, MA 02703, USA

#### **CONTACT US**

#### **Americas**

+1 (800) 350 2727 sensors@sensata.com Europe, Middle East & Africa +33 (3) 88 20 8080 position-info.eu@sensata.com

Asia Pacific

sales.isasia@list.sensata.com China +86 (21) 2306 1500 Japan +81 (45) 277 7117 Korea +82 (31) 601 2004 India +91 (80) 67920890 Rest of Asia +886 (2) 27602006 ext 2808