

# OAK-1 MAX — DepthAI Hardware Documentation 1.0.0 documentation

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## OAK-1 MAX

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### Overview

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**OAK-1 MAX** supports up to 32MP color camera resolution ([IMX582](#)) on a tiny, yet performant, device.

OAK-1 Max isn't a standard USB camera. It's a 4-trillion-operations-per-second AI powerhouse that performs your AI models on-board, so that your host is free to do whatever you need it to do.

### Hardware specifications

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#### Camera module specifications

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Camera Specs	Color camera
Sensor	<a href="#">IMX582</a> (PY080)
DFOV / HFOV / VFOV	71° / 45° / 55°
Resolution	32MP (5312x6000)
Focus	Auto-Focus: 20cm - ∞

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Camera Specs	Color camera
Max Framerate	42 FPS
F-number	1.79±5%
Lens size	1/2 inch
Effective Focal Length	4.74mm
Distortion	< 1.5%
Pixel size	0.8µm x 0.8µm

## RVC2 inside

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This OAK device is built on top of the [RVC2](#). Main features:

- **4 TOPS** of processing power (1.4 TOPS for AI - [RVC2 NN Performance](#))
- **Run any AI model**, even custom architected/built ones - models need to be [converted](#).
- **Encoding**: H.264, H.265, MJPEG - 4K/30FPS, 1080P/60FPS
- **Computer vision**: warp/dewarp, resize, crop via [ImageManip](#) node, [edge detection](#), [feature tracking](#). You can also [run custom CV functions](#)
- **Object tracking**: 2D tracking with [ObjectTracker](#) node

## IMX582 RAM consumption

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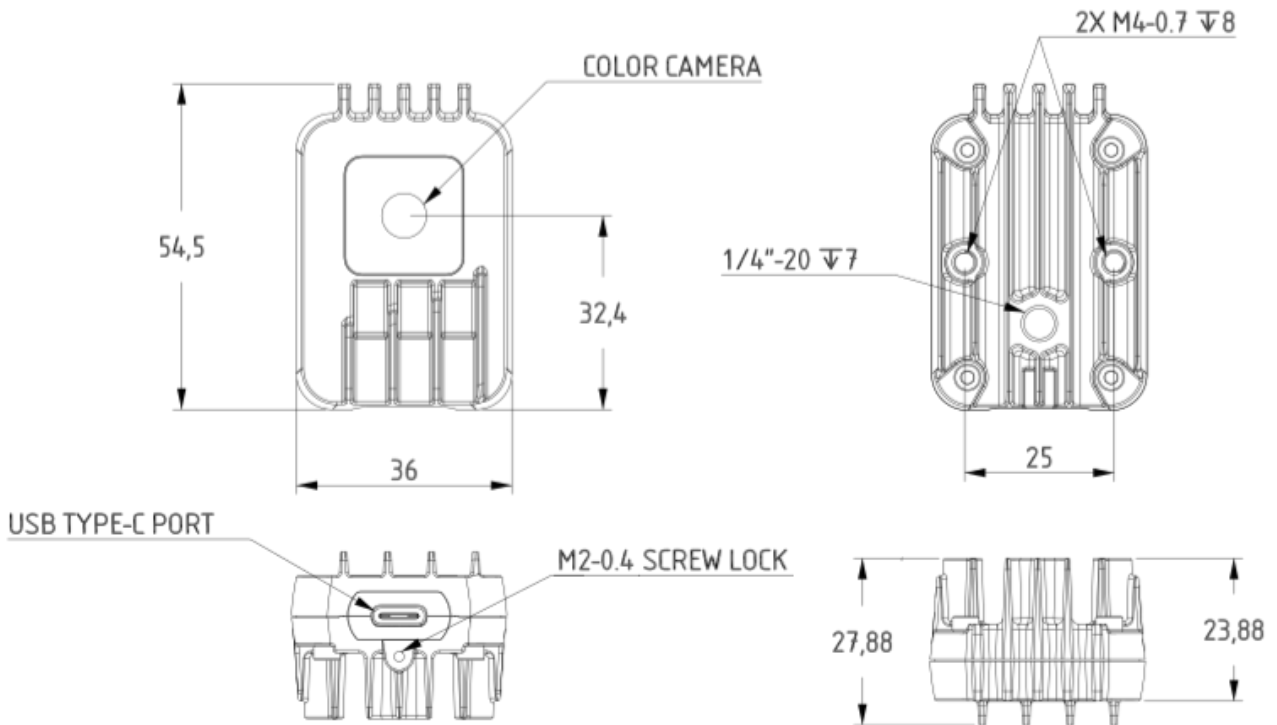
At highest resolution, the IMX582 image sensor produces 32MP frames, which can consume *a lot* of RAM. As OAK cameras are embedded devices, they don't have a lot of RAM to begin with. In most pipelines, even just the [ColorCamera](#) node with default pool sizes will be too large, so you need to be very cautious when it comes to RAM and we suggest reading the [RAM usage documentation](#). For ColorCamera node, you'd likely need to change pool sizes, example here:

```
cam = pipeline.create(dai.node.ColorCamera)
cam.setResolution(dai.ColorCameraProperties.SensorResolution.THE_5312X6000) # 32MP
# Decrease pool sizes for all outputs (raw, isp, preview, video, still):
cam.setNumFramesPool(2,2,1,1,1)
```

## Dimensions and Weight

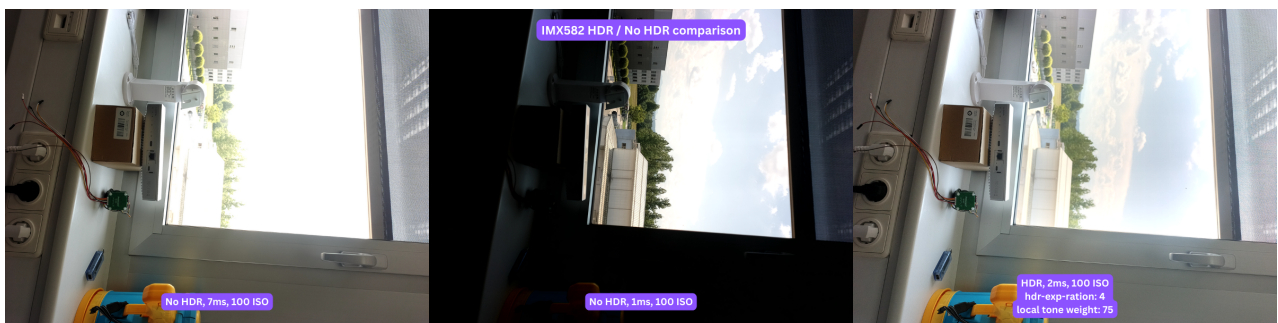
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- Width: 36 mm
- Height: 54.5 mm
- Length: 27.8 mm
- Weight: 53.1 grams



## IMX582 HDR

IMX582 sensor supports on-sensor HDR, so it can be leveraged by the [Robotics Vision Core 2](#) as well. In the comparison image below we are using [OAK-1 MAX](#). HDR support is currently on branch [camera\\_controls\\_misc](#) and will be merged to main soon.



IMX582 HDR comparison. Click on this image for full resolution images on [Google Drive](#). We suggest downloading images, as they are large.

For the HDR image above we used the following argument for [cam\\_test.py](#):

```
python3 cam_test.py -cams rgb,c -rs -cres 12mp -fps 10 -misc hdr-exposure-ratio=4
hdr-local-tone-weight=75
```

