### **Enabling the** Electronics Revolution

### HRPM Hall-Effect Rotary Position Sensor with integrated connector



### **KEY FEATURES**

2
Touchless Sensor

### True touchless operation

Without any internal or external gears or linkages the sensor is easily assembled and calibrated and free from wear and tear over lifetime.



### 360 degree absolute position feedback

Endless mechanical rotational angle without dead band, keeps the position on power loss with configurable electrical angles from 50 to 360 degrees.



### Made for harsh environments

The rugged package protects the sensor from dust, moisture, vibration and extreme temperatures for usage in the most demanding environments.



### Unlimited mechanical life

The separation of electronics and magnet module allows for a virtually unlimited lifetime independent of unlimited life number of revolutions.

### DESCRIPTION

The HRPM Series of Hall-effect Rotary Position Sensors is a cost-effective, non-contacting position sensing solution for applications in harsh environments such as transportation, industrial and marine.

This compact sensor with integrated AMP superseal connector is based on a touchless concept with separate housings for electronics and magnet. The magnet is mounted on the actuated axis and without wear and tear due to radial forces, the reliability and lifetime are increased significantly.

Fully sealed and flanged mounted for easy positioning, the sensor is versatile with configurable angular ranges from 50 to 360 degrees, option for a bare or housed magnet, different pin-outs and support for low and high-voltage power supply.

### **APPLICATIONS**

### Industrial

- ► Autonomous warehouse robotics
- Robotics and automation feedback
- ▶ Robot arm position
- Valve monitoring
- Conveyor operation

#### **Transportation**

- ► Steering wheel angle
- ▶ Pedal Position
- Suspension/height detection
- Fork height and mast tilt
- Bucket position
- Hitch position
- Transmission gear shift

#### Marine

- Steering and shifter sensor
- Home and Building Automation
- ► HVAC systems

# **HRPM**

### Hall-Effect Rotary Position Sensor with integrated connector

MECHANICAL SPECIFICATIONS			
	НКРМ		
Rotational life	Virtually unlimited		
Mechanical range	360° (endless rotation)		
Mating connector	AMP Superseal 282087-1		
Air Gap	3mm ±1mm		
Mounting screw sizes			
Sensor to mounting surface	non-magnetic, stainless steel M4 X 0.7 screws and 8 mm 0D washers		
Housed magnet to actuator mounting shaft	non-magnetic, stainless steel M3 X 0.5 plain cup point set screws		
ELECTRICAL SPECIFICATIONS			
	LIDDM		

	НКРМ			
Supply voltage	5V ±10%	7V to 32V		
Supply current	12 mA	14 mA		
Overvoltage protection	+10V	+36V		
Reverse voltage protection	-10V	-30V		
Output standard inverted	10% to 90% Vdc (CW) 90% to 10% Vdc (CCW)			
Absolute linearity / Accuracy error <sup>1</sup>	± 1% (0,5% on request)			
Resolution	Up to 12 bit			
Self-diagnostic features	yes			
<sup>1</sup> Ferromagnetic materials close to the sensor life, shaft, mounting surface) may affect the sensor's linearity				

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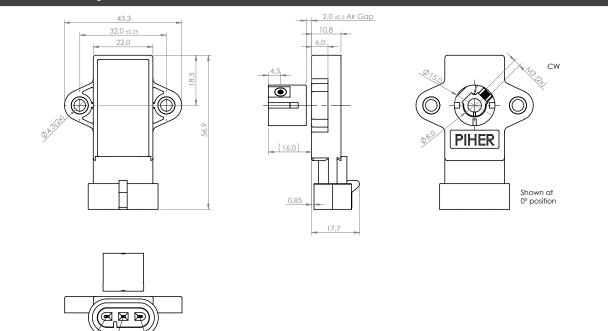
ENVIRONMENTAL SPECIFICATIONS			
HRPM			
Operating temperature	-40° to +125°C		
Shock	50g		
Vibration	5-2000 Hz; 20g; Amax 0,75 mm		
Sealing	ІР69К		

## **HRPM**

Hall-Effect Rotary Position Sensor with integrated connector

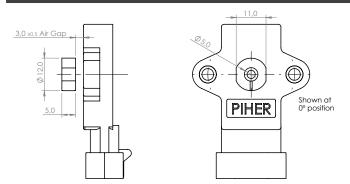
### DIMENSIONS (MM)

### HRPM-A (housed magnet)



### HRPM-M (bare magnet)

Pin <sup>1</sup>



Pin 3

Pin 2

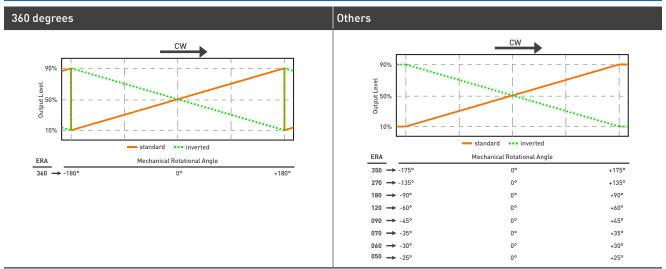
CONNECTION SCHEME			
PIN	European Pinout	American Pinout	
1	Ground	Power supply	
2	Power Supply	Ground	
3	Signal output	Signal output	

## **HRPM**

### Hall-Effect Rotary Position Sensor with integrated connector

HOW TO ORD	DER				
HRPM-Serie	HRPM-Series (two piece design / separate magnet)				
HRPM			_		
Series	Actuator	Electric rotational	Output Function	Voltage supply	Pinout
	M = Bare magnet A = Housed magnet	angle 050 060 070 090 120 180 270 350 350 360	S = standard (CW)   = inverted (CCW)	05 = 5V ±10% RE = 7V-32V	E = European A = American

### **OUTPUT FUNCTIONS**



Custom output functions on request.









Please always use the latest updated datasheets and 3D models published on our website.

Disclaimer:

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