RoHS RoHS-Compliant Induction Motors

W 9

15 W

25 W



Features

Optimal for Uni-Directional Continuous Operation

Induction motors are optimal for uni-directional continuous operation such as a conveyor system.

Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking		
UL 1004 UL 2111	UL	E64199 (1 W~6 W Type)			
CSA C22.2 No.100 CSA C22.2 No.77	UL	E64197 (15 W~150 W Type)			
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60664-1	60034-1 Conform to EN/IEC Standards				
GB 12350	CQC	2005010401150786 (Single-Phase 1 W, 3 W Type) 2003010401091525 (Single-Phase 6 W Type) 2003010401091527 (Three-Phase 6 W Type) 2003010401091522 (Single-Phase 15 W~90 W Type) 2003010401091520 (Three-Phase 25 W~90 W Type) 2005010401150785 (2-Pole, High-Speed Type, Single-Phase 40 W~150 W Type) 2005010401150788 (2-Pole, High-Speed Type, Three-Phase 60 W~150 W Type)			

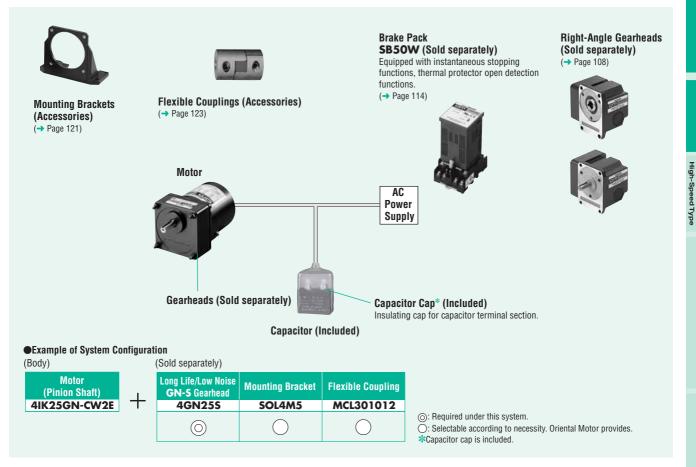
• When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

• The following products are not applicable to the table above

4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

SIKOUGE-UI4F, SIKO	0A-014F, 51K90G	2-014F, 51K70A-014F	
Standards	Certification Body	Standards File No.	CE Marking
EN 60950-1 EN 60034-1 EN 60034-5 IEC 60034-11	TÜV Rheinland	R50079501	Low Voltage Directives

System Configuration



• The system configuration shown above is an example. Other configurations are available.

Product Number Code

Motor

5 I K 40 GN - CW

(1) (2 3 4	(5) (6) (7) (8) (9)								
1	Motor Frame Size	0: 42 mm 2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm								
2	Motor Type	I: Induction Motor								
3	Series	K: K Series								
4	Output Power (W)	(Example) 40: 40 W								
5	Motor Shaft Type	GN: GN Type Pinion Shaft GE: GE Type Pinion Shaft A: Round Shaft								
6	Power Supply Voltage/ Number of Poles	AW: Single-Phase 100 VAC, 110/115 VAC 4-Pole BW: Single-Phase 100 VAC, 110/115 VAC 2-Pole CW: Single-Phase 200 VAC, 220/230 VAC 4-Pole DW: Single-Phase 200 VAC, 220/230 VAC 2-Pole SW: Three-Phase 200/220/230 VAC 4-Pole TW: Three-Phase 200/220/230 VAC 2-Pole U: Three-Phase 400 VAC 4-Pole SW: Three-Phase 200/220/230 VAC 4-Pole TW: Three-Phase 200/220/230 VAC 2-Pole								
7	2, 3: RoHS-Compliant									
8	T, T4, T4F: Terminal Bo	х Туре								
9	Included Capacitor	J: For Single-Phase 100 VAC, 200 VAC U: For Single-Phase 110/115 VAC E: For Single-Phase 220/230 VAC Blank: Three-Phase Type								

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(Example) Model: 5IK40GN-CW2E -> Motor nameplate and product approved under various safety standards: 5IK40GN-CW2

RH: Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant

Gearhead

4

GE Type Pinion

5	GN 50	5
1	2 3	<u>(4)</u>
1	Gearhead Frame Size	0: 42 mm 2: 60 mm 3: 70 mm 4: 80 mm 5: 90 mm
2	Type of Pinion	GN: GN Type Pinion GE: GE Type Pinion
3	Gear Ratio	(Example) 50: Gear Ratio of 1:50 10X denotes the decima
@	GN Type Pinion	S: Long Life/Low Noise GN-S Gearhead, RoHS-Compliant RH : Right-Angle/Hollow Shaft Gearhead, RoHS-Compliant

S: Long Life GE-S Gearhead

denotes the decimal gearhead of gear ratio 1:10 ad, RoHS-Compliant K: GN-K Gearhead RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant RA: Right-Angle/Solid Shaft Gearhead, RoHS-Compliant

* GN-K gearhead of frame size 42 mm complies to RoHS directive.

General Specifications of Motors

•1 W, 3 W Type

Item	Specifications
Insulation Resistance	100 M Ω or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.
Dielectric Strength	Sufficient to withstand 1.5 kV at 50 Hz or 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.
Temperature Rise	Temperature rise of windings are 75°C or less measured by the resistance change method after rated motor operation under normal ambient temperature and humidity, with connecting a gearhead or equivalent heat radiation plate ^{\$1} .
Insulation Class	UL/CSA standards: Class A (105°C), EN standards: Class E (120°C)
Overheat Protection	Impedance protected
Ambient Temperature	$-10^{\circ}C \rightarrow +40^{\circ}C$ (nonfreezing)
Ambient Humidity	85% or less (noncondensing)
Degree of Protection	IP20

●6 W~90 W Type, 2-Pole, High-Speed Type

Item	Specifications							
Insulation Resistance	100 M Ω or more when 500 VDC megger is applied between the windings and the frame after rated motor operation under normal ambient temperature and humidity.							
Dielectric Strength	Sufficient to withstand 1.5 kV (three-phase 400 VAC: 2 kV) at 50 Hz and 60 Hz applied between the windings and the frame for 1 minute after rated motor operation under normal ambient temperature and humidity.							
Temperature Rise	Femperature rise of windings are 80°C or less measured by the resistance change method under normal ambient temperature and humidity, after rated motor operation with connecting a gearhead or equivalent heat radiation plate*1. (Three-phase type: 70°C or less)							
Insulation Class*2	Class B (130°C)							
Overheat Protection	6 W type has impedance protection. All others have built-in thermal protector (automatic return type) Operating temperature; open: 130°C±5°C, close: 82°C±15°C							
Ambient Temperature	Single-phase 100 VAC, Single-phase 200 VAC, Three-phase 200 VAC: $-10^{\circ}C \sim +50^{\circ}C$ (nonfreezing) Other voltage: $-10^{\circ}C \sim +40^{\circ}C$ (nonfreezing)							
Ambient Humidity	85% or less (noncondensing)							
Degree of Protection	Lead Wire Type: IP20 IP65 (excluding the installation surface of the round shaft type) Terminal Box Type: 6 W Type IP65 (excluding the installation surface of the round shaft type) 25 W, 40 W, 60 W, 90 W Type (Poinon Shaft Type) IP54 25 W, 40 W, 60 W, 90 W Type (Round Shaft Type) IP40							

*1 Heat radiation plate (Material: Aluminum)

Motor Type	Size (mm)	Thickness (mm)			
1 W, 3 W Type	80×80				
6 W Туре	115×115				
15 W Type	125×125	5			
25 W Type (2-Pole, High-Speed 4IK40 Type, 4IK60 Type)	135×135				
40 W Type (2-Pole, High-Speed 5IK60 Type)	165×165				
60 W, 90 W, 150 W Type	200×200				

00 11, 00 11, 100

*2 The following products are recognized as class E (120°C). 4IK25GN-UT4, 4IK25A-UT4, 5IK40GN-UT4, 5IK40A-UT4, 5IK60GE-UT4F, 5IK60A-UT4F, 5IK90GE-UT4F, 5IK90A-UT4F

1 W / 3 W

RoHS Induction Motors 1 W / 3 W Frame Size: 42 mm



(Gearhead sold separately)

Specifications – Continuous Rating (RoHS)

Model Lead Wire Type		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	А	mN∙m	mN∙m	r/min	μF	
(ZP) OIK1GN-AW2J	0IK1A-AW2J	1	Single-Phase 100	50	0.107	8	9.5	1000	1.5	
UKIGN-AWZJ	VIK IA-AWZJ	1	Sillyle-Filase 100	60	0.102	0	8	1200	1.5	
(ZP) OIK1GN-AW3U	0IK1A-AW3U	1	Single-Phase 110	60	0.074	8	8	1200	1.0	
UKIGN-AW30	UIK IA-AW30		Single-Phase 115	00	0.078	0	0	1200	1.0	
(ZP) OIK1GN-CW2J	0IK1A-CW2J	0.8	Single-Phase 200	50	0.057	7	8	1000	0.35	
UKIGN-CW2J		1	Single-Fildse 200	60	0.055	1	0	1200	0.55	
(ZP) OIK3GN-BW2J	OIK3A-BW2J	3	Single-Phase 100	50	0.109	6	12	2400	1.8	
UKJGIN-BWZJ	UIKJA-DWZJ	3	Single-Fildse 100	60	0.123	0	10	3000	1.0	
(ZP) OIK3GN-BW3U	OIK3A-BW3U	3	Single-Phase 110	60	0.115	6	10	3000	1.5	
	UINJA-DWJU	3	Single-Phase 115	00	0.118	0	10	3000	1.0	
(ZP) OIK3GN-DW2J	0IK3A-DW2J	2.5	Single-Phase 200	50	0.057	- 5	9.5	2500	0.45	
ZP UKJGN-DWZJ	UIKJA-DWZJ	3	Single-Filase 200	60	0.064	3	9.0	3100	0.45	

• The J and U at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

ZP: Impedance protected

Product Line

Motor (RoHS)

Type	Model								
туре	Pinion Shaft Type	Round Shaft Type							
	0IK1GN-AW2J	0IK1A-AW2J							
	0IK1GN-AW3U	0IK1A-AW3U							
Lead Wire	0IK1GN-CW2J	OIK1A-CW2J							
Leau wire	OIK3GN-BW2J	OIK3A-BW2J							
	OIK3GN-BW3U	OIK3A-BW3U							
	0IK3GN-DW2J	OIK3A-DW2J							

Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Parallel Shaft	OGN⊡K	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (
) within the model name.

Accessories

Gearmotor – Torque Table

•Gearheads are sold separately. Decimal gearheads are not available.

•Enter the gear ratio in the box (\Box) within the model name.

A colored background _____ indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (4-pole type; 50 Hz: 1500 r/min, 60 Hz: 1800 r/min, 2-pole type; 50 Hz: 3000 r/min, 60 Hz: 3600 r/min) by the gear ratio. The actual speed is 2 - 33% less than the displayed value, depending on the size of the load.

⊘50 Hz																				Uni	it = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
0IK1GN-AW2J	Ó OGN⊡K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
0IK1GN-CW2J	/ OGN⊟K	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85
																				Uni	it = N•m
Model	Speed r/min	1000	833	600	500	400	333	240	200	166	120	100	83	60	50	40	33	30	25	20	16
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
OIK3GN-BW2J	/ OGN⊟K	0.029	0.035	0.049	0.058	0.073	0.087	0.11	0.13	0.16	0.2	0.24	0.29	0.4	0.48	0.53	0.64	0.71	0.85	1	1
0IK3GN-DW2J	/ OGN⊡K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1
⊘60 Hz																				Uni	it = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
0IK1GN-AW2J 0IK1GN-AW3U 0IK1GN-CW2J	OGN □K	0.019	0.023	0.032	0.039	0.049	0.058	0.073	0.088	0.11	0.13	0.16	0.19	0.26	0.32	0.35	0.42	0.47	0.57	0.71	0.85
																				Uni	it = N•m
Model	Speed r/min	1200	1000	720	600	480	400	288	240	200	144	120	100	72	60	48	40	36	30	24	20
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
OIK3GN-BW2J OIK3GN-BW3U		0.024	0.029	0.041	0.049	0.061	0.073	0.091	0.11	0.13	0.17	0.2	0.24	0.33	0.4	0.44	0.53	0.59	0.71	0.89	1
0IK3GN-DW2J	/ OGN⊡K	0.023	0.028	0.038	0.046	0.058	0.069	0.087	0.1	0.12	0.16	0.19	0.23	0.31	0.38	0.42	0.5	0.56	0.67	0.84	1

M 09

Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

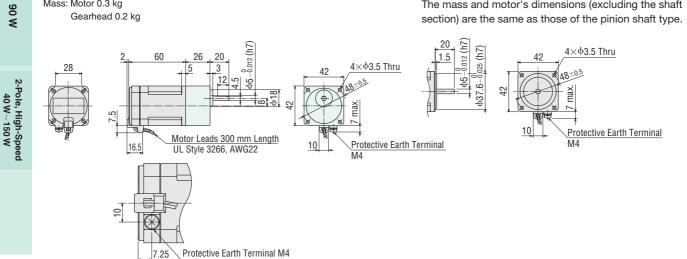
Permissible Load Inertia J for Gearhead

→ Page 107

Dimensions (Unit = mm)

Mounting screws are included with gearheads.

Mass: Motor 0.3 kg Gearhead 0.2 kg



♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft

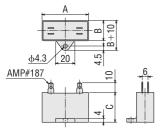
section) are the same as those of the pinion shaft type.

15 W

25 W

1 W / 3 W

♦ Capacitor (Included with the motors) ♦ Capacitor Dimensions (mm)

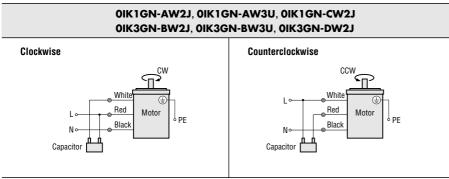


Ν	Capacitor	٨	В	С	Mass	Capacitor	
Pinion Shaft Type	Round Shaft Type	Model	A	D		(g)	Сар
0IK1GN-AW2J	OIK1A-AW2J	CH15FAUL	31	14.5	23.5	18	
0IK1GN-AW3U	OIK1A-AW3U	CH10FAUL	31	14.5	23.5	18	
0IK1GN-CW2J	OIK1A-CW2J	CH035BFAUL	31	17	27	24	Included
OIK3GN-BW2J	OIK3A-BW2J	CH18FAUL	31	14.5	14.5 23.5	18	Included
OIK3GN-BW3U	OIK3A-BW3U	CH15FAUL	31	14.5	23.5	18	
0IK3GN-DW2J	OIK3A-DW2J	CH045BFAUL	31	17	27	24	1

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

(RoHS)Induction Motors6 WFrame Size: □60 mm







(Gearhead sold separately)

Specifications – Continuous Rating (RoHS)



	•			•						
	Mode Upper Model Name: F Lower Model Name ():	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
	Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
(ZP)	2IK6GN-AW2J	2IK6GN-AW2TJ	6	Cingle Dhoos 100	50	0.199	45	49	1200	3.5
P	(2IK6A-AW2J)	(2IK6A-AW2TJ)	0	Single-Phase 100	60	0.217	40	41	1450	3.0
(ZP)	2IK6GN-AW2U	2IK6GN-AW2TU	6	Single-Phase 110	60	0.178	- 40	41	1450	2.5
P	(2IK6A-AW2U)	(2IK6A-AW2TU)	0	Single-Phase 115	00	0.182	40	41	1450	2.5
(ZP)	2IK6GN-CW2J 2IK6GN-CW2TJ		6	Single-Phase 200	50	0.100	45	49	1150	0.8
	(2IK6A-CW2J)	(2IK6A-CW2TJ)	0	Sillyle-Fliase 200	60	0.103	40	41	1450	0.0
				Single-Phase 220	50	0.103	38	49	1150	
ZP	2IK6GN-CW2E	2IK6GN-CW2TE	6	Sillyle-Filase 220	60	0.091	40	41	1450	0.6
	(2IK6A-CW2E)	(2IK6A-CW2TE)	0	Single-Phase 230	50	0.107	45	49	1200	0.0
				Single-Filase 250	60	0.094	40	41	1450	
				Three-Phase 200	50	0.081	49	49	1200	
(ZP)	2IK6GN-SW2	2IK6GN-SW2T	6	11166-11088 200	60	0.072	41	41	1400	
P	(2IK6A-SW2)	(2IK6A-SW2T)	6	Three-Phase 220	60	0.076	41	41	1500	_
				Three-Phase 230	60	0.079	41	41	1500	

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

2IK6A-SW2T

ZP: Impedance protected

Product Line

Motor (RoHS)

W 09

Model Туре Pinion Shaft Type Round Shaft Type 2IK6GN-AW2J 2IK6A-AW2J 2IK6A-AW2U 2IK6GN-AW2U 2IK6GN-CW2J 2IK6A-CW2J Lead Wire 2IK6GN-CW2E 2IK6A-CW2E 2IK6GN-SW2 2IK6A-SW2 2IK6GN-AW2TJ 2IK6A-AW2TJ 2IK6GN-AW2TU 2IK6A-AW2TU Terminal Box 2IK6GN-CW2TJ 2IK6A-CW2TJ 2IK6GN-CW2TE 2IK6A-CW2TE

2IK6GN-SW2T

Gearhead (Sold Separately) (RoHS)

Contract (cond coparately)											
Туре	Gearhead Model	Gear Ratio									
Long Life/Low Noise/ Parallel Shaft	2GN□S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180									
2GN10XS (Decimal gearhead)											

ullet Enter the gear ratio in the box () within the model name.

1 W / 3 W

8 W

15 W

Induction Motors 2-Pole,

Unit = N•m

Gearheads and decimal gearheads are sold separately.

•Enter the code that represents the terminal box type "**T**" in the box (**D**) within the model name.

•Enter the gear ratio in the box (\Box) within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

•To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 3 N·m.

⊘50 Hz

Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
21K6GN-AW2_J 21K6GN-CW2_J 21K6GN-CW2_E 21K6GN-SW2_	2GN□S	0.12	0.14	0.20	0.24	0.30	0.36	0.50	0.60	0.71	0.89	1.1	1.3	1.6	1.9	2.4	2.9	3	3	3	3

A 60 H-

																				Uni	t = N•m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
2IK6GN-AW2_J 2IK6GN-AW2_U 2IK6GN-CW2_J 2IK6GN-CW2_E 2IK6GN-SW2_	2GN⊡S	0.10	0.12	0.17	0.20	0.25	0.30	0.42	0.50	0.60	0.75	0.90	1.1	1.4	1.6	2.0	2.4	2.7	3	3	3

Permissible Overhung Load and Permissible Thrust Load

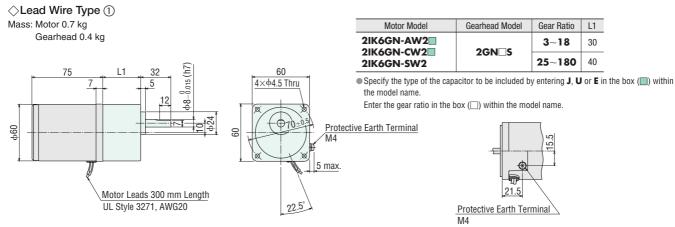
Motor (Round shaft type) → Page 107 Gearhead → Page 107

Permissible Load Inertia J for Gearhead

→ Page 107

Dimensions (Unit = mm)

Mounting screws are included with gearheads.



Detail Drawing of Protective Earth Terminal

Gear Ratio

3~18

25~180

L1

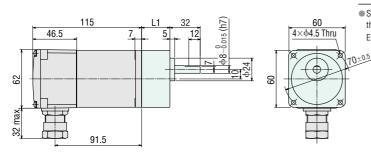
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Right-Angle Gearheads

Torque Motors

Mass: Motor 0.9 kg Gearhead 0.4 kg



Motor Model	Gearhead Model	Gear Ratio	L1
2IK6GN-AW2T 2IK6GN-CW2T	2GN⊟S	3~18	30
2IK6GN-SW2T	2GN_3	25~180	40

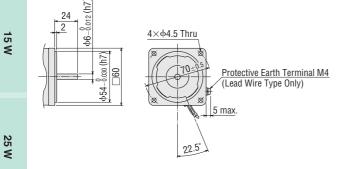
ullet Specify the type of the capacitor to be included by entering ${\bf J}, {\bf U}$ or ${\bf E}$ in the box ([]) within the model name.

Enter the gear ratio in the box (\Box) within the model name.

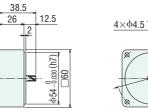
 \bullet Use cable with a diameter of $\varphi 8 \sim \varphi 12$ mm.

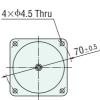
♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



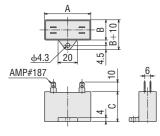
\bigcirc Decimal Gearhead Can be connected to **GN** pinion shaft type. 2GN10X5 Mass: 0.2 kg





♦Capacitor

(Included with single-phase motors)



Upper Model Name	del e: Pinion Shaft Type (): Round Shaft Type	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
2IK6GN-AW2J (2IK6A-AW2J)	2IK6GN-AW2TJ (2IK6A-AW2TJ)	CH35FAUL2	31	17	27	25	
2IK6GN-AW2U (2IK6A-AW2U)	2IK6GN-AW2TU (2IK6A-AW2TU)	CH25FAUL2	31	17	27	25	le cluded
2IK6GN-CW2J (2IK6A-CW2J)	2IK6GN-CW2TJ (2IK6A-CW2TJ)	CH08BFAUL	31	17	27	20	Included
2IK6GN-CW2E (2IK6A-CW2E)	2IK6GN-CW2TE (2IK6A-CW2TE)	CH06BFAUL	31	14.5	23.5	15	

W 9

40 W

00 W

M 06

2-Pole, High-Speed 40 W∼150 W

Induction Motors 2-Pole,

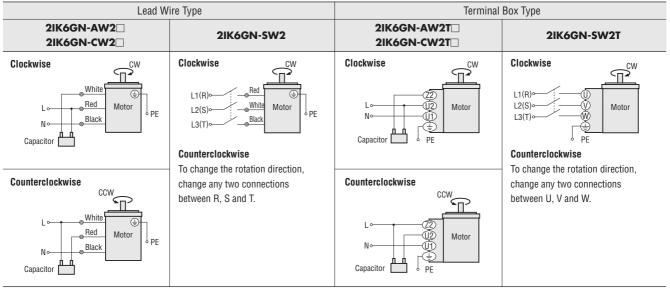
High-Speed Type

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

Accessories

1 W / 3 W

W 9

15 W

25 W

40 W

RoHS Induction Motors 15 W Frame Size: 70 mm



(Gearhead sold separately)

Specifications – Continuous Rating (RoHS)



-			-						
Model Lead Wire		Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor
Pinion Shaft Type	Round Shaft Type	W	VAC	Hz	A	mN∙m	mN∙m	r/min	μF
TP 3IK15GN-AW2J	3IK15GN-AW2J 3IK15A-AW2J		Single-Phase 100	50	0.36	80	125	1200	5.5
JIN I JOIN-AWZJ	JIK I JA-AWZJ	15	Single-Flidse 100	60	0.37	65	105	1450	5.5
TP) 3IK15GN-AW2U	3IK15A-AW2U	15	Single-Phase 110	60	0.33	- 65	105	1450	4.5
JIN I JOIN-AWZU	JIK I JA-AWZU	10	Single-Phase 115	00	0.34	05	105	1450	4.0
TP 3IK15GN-CW2J	3IK15A-CW2J	15	Single-Phase 200	50	0.18	80	125	1200	1.5
	JIK I JA-CWZJ	10	Single-Flidse 200	60	0.19	65	105	1450	1.5
			Single Dhase 220	50	0.19	70	125	1200	
TP 3IK15GN-CW2E	3IK15A-CW2E	15	Single-Phase 220	60	0.16	65	105	1450	1.0
JIN I JGN-CWZE	SIK I SA-CWZE	10	Cingle Dhose 020	50	0.19	75	125	1200	1.0
			Single-Phase 230	60	0.16	65	105	1450	

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate. When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

Product Line

Motor (RoHS)

Tuno	Model									
Туре	Pinion Shaft Type	Round Shaft Type								
	3IK15GN-AW2J	3IK15A-AW2J								
Lead Wire	3IK15GN-AW2U	3IK15A-AW2U								
	3IK15GN-CW2J	3IK15A-CW2J								
	3IK15GN-CW2E	3IK15A-CW2E								

Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio											
Long Life/Low Noise/ Parallel Shaft	3GN⊡S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180											
	3GN10XS (Decimal gearhead)												

• Enter the gear ratio in the box (
) within the model name.

M 06

Gearmotor – Torque Table

•Gearheads and decimal gearheads are sold separately.

•Enter the gear ratio in the box (\Box) within the model name.

•A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

•To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 5 N·m.

⊘50 Hz																				Uni	t = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-CW2J 3IK15GN-CW2E	∕ 3GN⊡S	0.30	0.36	0.51	0.61	0.76	0.91	1.3	1.5	1.8	2.3	2.7	3.3	4.1	5	5	5	5	5	5	5
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
3IK15GN-AW2J 3IK15GN-AW2U 3IK15GN-CW2J 3IK15GN-CW2E	/ 3GN⊡S	0.26	0.31	0.43	0.51	0.64	0.77	1.1	1.3	1.5	1.9	2.3	2.8	3.5	4.2	5	5	5	5	5	5

Permissible Overhung Load and Permissible Thrust Load

70 4×¢5.5 Thru

> .∞ ____5 max.

22.5

Motor (Round shaft type) → Page 107 Gearhead → Page 107

Permissible Load Inertia J for Gearhead

φ10-

Motor Leads 300 mm Length

UL Style 3271, AWG20

C

→ Page 107

604

Dimensions (Unit = mm)

Mounting screws are included with gearheads.



Mass: Motor 1.1 kg Gearhead 0.55 kg

80

Motor Model	Gearhead Model	Gear Ratio	L1
3IK15GN-AW2	3GN⊟S	3~18	32
3IK15GN-CW2	JGIN_3	25~180	42

• Specify the type of the capacitor to be included by entering **J**, **U** or **E** in the box (**(**) within the model name.

Enter the gear ratio in the box (\Box) within the model name.

Protective Earth Terminal M4



Detail Drawing of Protective Earth Terminal

Electromagnetic Brake Motors

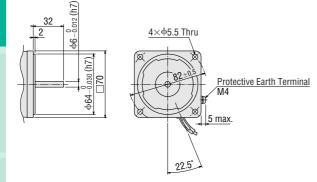
\diamond Key and Key Slot (The key is included with the gearhead) $25_{\pm 0.2}$ + 0.03 + 0.040 +

ed Type

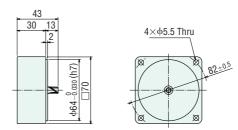
Reversible Motors

♦ Shaft Section of Round Shaft Type

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.

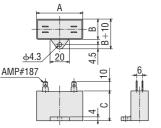


◇Decimal Gearhead Can be connected to GN pinion shaft type. 3GN10XS Mass: 0.3 kg



♦Capacitor

(Included with single-phase motors)



	mm)
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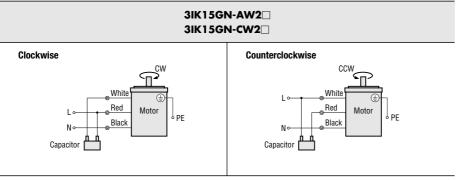
Mo	del	Capacitor	Α	P	C	Mass	Capacitor
Pinion Shaft Type	Round Shaft Type	Model		D	U	(g)	Сар
3IK15GN-AW2J	3IK15A-AW2J	CH55FAUL2	38	21	31	40	
3IK15GN-AW2U	3IK15A-AW2U	CH45FAUL2	37	18	27	30	Included
3IK15GN-CW2J	3IK15A-CW2J	CH15BFAUL	38	21	31	35	moluueu
3IK15GN-CW2E	3IK15A-CW2E	CH10BFAUL	37	18	27	30	

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.

■Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.



PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

15 W

W 9

25 W

High-Speed Type

Accessories

RoHS Induction Motors 25 W Frame Size: 80 mm



(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108



Specifications – Continuous Rating Rolls

Model Rated Torque Upper Model Name: Pinion Shaft Type Output Voltage Frequency Current Starting Torque Rated Capacitor Lower Model Name (): Round Shaft Type Power Speed Lead Wire Type Terminal Box Type W VAC Hz А mN⋅m mN•m r/min μF Dimension ① Dimension (2) 4IK25GN-AW2J 4IK25GN-AW2TJ 50 0.51 130 205 1200 Single-Phase 100 TP 25 8.0 (4IK25A-AW2J) (4IK25A-AW2TJ) 60 0.52 120 170 1450 4IK25GN-AW2U 4IK25GN-AW2TU Single-Phase 110 TP 25 60 0 46 120 170 1450 65 (4IK25A-AW2U) (4IK25A-AW2TU) Single-Phase 115 4IK25GN-CW2J 4IK25GN-CW2TJ 50 205 1200 TP 25 Single-Phase 200 0.26 120 2.0 (4IK25A-CW2J) (4IK25A-CW2TJ) 60 1450 170 0.27 1200 50 205 Single-Phase 220 110 4IK25GN-CW2E 4IK25GN-CW2TE 60 0.23 170 1450 25 1.5 TP (4IK25A-CW2E) (4IK25A-CW2TE) 205 1200 50 0.27 Single-Phase 230 120 60 0.23 170 1450 0.23 240 50 190 1300 Three-Phase 200 4IK25GN-SW2 4IK25GN-SW2T 60 0.21 160 160 1550 TP 25 (4IK25A-SW2) (4IK25A-SW2T) Three-Phase 220 60 0.21 160 160 1600 Three-Phase 230 60 0.22 160 160 1600 4IK25GN-UT4* TP 25 Three-Phase 400 50 0.12 240 190 1300 (4IK25A-UT4*)

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

* Conforms to EN/IEC standards only. Bears the CE Marking.

Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

Product Line

Motor Rolls

Tupo	Ma	del
Туре	Pinion Shaft Type	Round Shaft Type
	4IK25GN-AW2J	4IK25A-AW2J
	4IK25GN-AW2U	4IK25A-AW2U
Lead Wire	4IK25GN-CW2J	4IK25A-CW2J
	4IK25GN-CW2E	4IK25A-CW2E
	4IK25GN-SW2	4IK25A-SW2
	4IK25GN-AW2TJ	4IK25A-AW2TJ
	4IK25GN-AW2TU	4IK25A-AW2TU
Terminal Box	4IK25GN-CW2TJ	4IK25A-CW2TJ
Terminar Dux	4IK25GN-CW2TE	4IK25A-CW2TE
	4IK25GN-SW2T	4IK25A-SW2T
	4IK25GN-UT4	4IK25A-UT4

Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	4GN⊡S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	4GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	4GN⊡RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	4GN RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (\Box) within the model name.

Gearmotor – Torque Table

Gearheads and decimal gearheads are sold separately.

●Enter the code that represents the terminal box type "T" in the box (□) within the model name.

•Enter the gear ratio in the box (\Box) within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

•The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 8 N·m. When a gearhead of 1/25~1/36 is connected, the value for permissible torque is 6 N·m.

⊘50 Hz																				Unit	t = N∙m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2J 4IK25GN-CW2J 4IK25GN-CW2E	dgn⊡s	0.50	0.60	0.83	1.0	1.2	1.5	2.1	2.5	3.0	3.7	4.5	5.4	6.8	8	8	8	8	8	8	8
4IK25GN-SW2 4IK25GN-UT4	dGN⊡S	0.46	0.55	0.77	0.92	1.2	1.4	1.9	2.3	2.8	3.5	4.2	5.0	6.3	7.5	8	8	8	8	8	8
																				Unit	t = N•m

																				UIII	
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
4IK25GN-AW2_J 4IK25GN-AW2_U 4IK25GN-CW2_J 4IK25GN-CW2_E	dgn⊡s	0.41	0.50	0.69	0.83	1.0	1.2	1.7	2.1	2.5	3.1	3.7	4.5	5.6	6.7	8	8	8	8	8	8
4IK25GN-SW2	4GN□S	0.39	0.47	0.65	0.78	0.97	1.2	1.6	1.9	2.3	2.9	3.5	4.2	5.3	6.3	7.9	8	8	8	8	8

40 W

Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

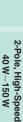
Permissible Load Inertia J for Gearhead

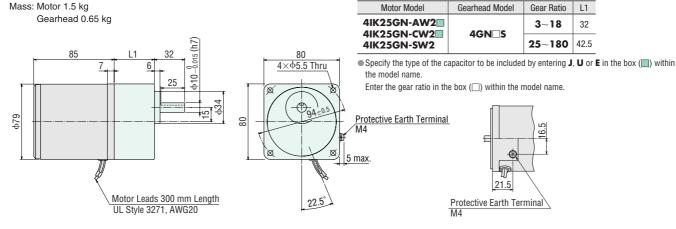
→ Page 107

♦ Lead Wire Type ① Mass: Motor 1.5 kg

Dimensions (Unit = mm)

Mounting screws are included with gearheads.





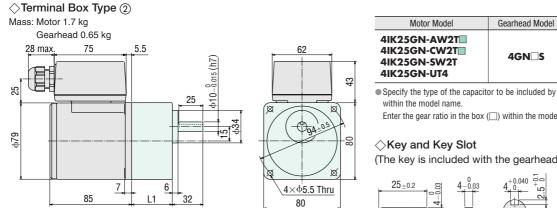
Detail Drawing of Protective Earth Terminal

1 W / 3 W

M9

15 W

World K Series



 \bullet Use cable with a diameter of $\varphi 6 \sim \varphi 12$ mm.

<u>φ</u>4.3 AMP#187

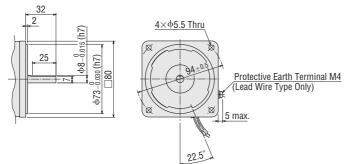
20

♦ Shaft Section of Round Shaft Type

(Included with single-phase motors)

9

The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



∧Capacitor Dimonsions (mm)

<	Capacitor Dimer	isions (mm)						
	Upper Model Name	del e: Pinion Shaft Type (): Round Shaft Type	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap
	Lead Wire Type	Terminal Box Type						
	4IK25GN-AW2J (4IK25A-AW2J)	4IK25GN-AW2TJ (4IK25A-AW2TJ)	CH80CFAUL2	48	21	31	45	
-	4IK25GN-AW2U (4IK25A-AW2U)	4IK25GN-AW2TU (4IK25A-AW2TU)	CH65CFAUL2	48	19	29	40	Included
-	4IK25GN-CW2J (4IK25A-CW2J)	4IK25GN-CW2TJ (4IK25A-CW2TJ)	CH20BFAUL	48	19	29	35	Included
-	4IK25GN-CW2E (4IK25A-CW2E)	4IK25GN-CW2TE (4IK25A-CW2TE)	CH15BFAUL	38	21	31	35	

Gear Ratio

L1

Enter the gear ratio in the box (\Box) within the model name.

(The key is included with the gearhead)



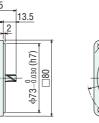
0.040 -0-1 ŝ сi

♦ Decimal Gearhead

Can be connected to GN pinion shaft type. 4GN10XS

Mass: 0.4 kg

45.5 32





Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

L	d Wire Type	Termina	I Вох Туре
4IK25GN-AW2□ 4IK25GN-CW2□	4IK25GN-SW2	4IK25GN-AW2T□ 4IK25GN-CW2T□	4IK25GN-SW2T 4IK25GN-UT4
Clockwise	PE L3(T) Black	Clockwise Clockwise CW CW CW CW CW CW CW CW CW CW	Clockwise L1(R) L2(S) L3(T) PE
Counterclockwise	Counterclockwise To change the rotation direction, change any two connections between R, S and T.	Counterclockwise	Counterclockwise To change the rotation direction, change any two connections between U, V and W.
LoweWhite Red NoweBlack Capacitor	PE	Lo 12 No Capacitor Capacitor	

PE: Protective Earth

Note:

 $Change \ the \ direction \ of \ single-phase \ motor \ rotation \ only \ after \ bringing \ the \ motor \ to \ a \ stop.$

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

15 W

World K Series

1 W / 3 W

High-Sp

eed Type

RoHS Induction Motors 40 W Frame Size: 90 mm

Lead Wire Type (Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108



Specifications – Continuous Rating (RoHS)

Model											
Mode Upper Model Name: I Lower Model Name ():	Pinion Shaft Type	Output Power	Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor		
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	w	VAC	Hz	A	mN∙m	mN∙m	r/min	μF		
TP 5IK40GN-AW2J	5IK40GN-AW2TJ	40	Single Dhose 100	50	0.76	200	315	1250	11		
(5IK40A-AW2J)	(5IK40A-AW2TJ)	40	Single-Phase 100	60	0.74	200	260	1500	11		
TP 5IK40GN-AW2U	5IK40GN-AW2TU	40	Single-Phase 110	60	0.68	200	260	1500	9.0		
(5IK40A-AW2U)	(5IK40A-AW2TU)	40	Single-Phase 115	00	0.67	200	260	1500	9.0		
TP 5IK40GN-CW2J	5IK40GN-CW2TJ	40	Cingle Dhoos 200	50	0.39	200	315	1250	3.0		
(5IK40A-CW2J)	(5IK40A-CW2TJ)	40	Single-Phase 200	60	0.40	200	260	1500	3.0		
-			Cinala Dhasa 000	50	0.39		315	1250			
5IK40GN-CW2E	5IK40GN-CW2TE	40	Single-Phase 220	60	0.35	200	260	1500	2.3		
(5IK40A-CW2E)	(5IK40A-CW2TE)	40	Cingle Dhoos 000	50	0.39	200	300	1300	2.3		
			Single-Phase 230	60	0.34	1	260	1500			
			Three Dhees 200	50	0.32	400	300	1300			
5IK40GN-SW2	5IK40GN-SW2T	40	Three-Phase 200	60	0.30	260	260	1550			
(5IK40A-SW2)	(5IK40A-SW2T)	40	Three-Phase 220	60	0.30	260	260	1600	—		
			Three-Phase 230	60	0.31	260	260	1600			
TP –	5IK40GN-UT4* (5IK40A-UT4*)	40	Three-Phase 400	50	0.16	500	315	1250	-		

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

* Conforms to EN/IEC standards only. Bears the CE Marking.

Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(D): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

Product Line

Motor Rolls

Type	Mo	del
туре	Pinion Shaft Type	Round Shaft Type
	5IK40GN-AW2J	5IK40A-AW2J
	5IK40GN-AW2U	5IK40A-AW2U
Lead Wire	5IK40GN-CW2J	5IK40A-CW2J
	5IK40GN-CW2E	5IK40A-CW2E
	5IK40GN-SW2	5IK40A-SW2
	5IK40GN-AW2TJ	5IK40A-AW2TJ
	5IK40GN-AW2TU	5IK40A-AW2TU
Terminal Box	5IK40GN-CW2TJ	5IK40A-CW2TJ
Terrininar Dux	5IK40GN-CW2TE	5IK40A-CW2TE
	5IK40GN-SW2T	5IK40A-SW2T
	5IK40GN-UT4	5IK40A-UT4

• Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/Low Noise/ Parallel Shaft	5GN [_] S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GN10XS (Decima	al gearhead)
Right-Angle/ Hollow Shaft	5GN□RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GN□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (\Box) within the model name.

Gearmotor – Torque Table

•Gearheads and decimal gearheads are sold separately.

●Enter the code that represents the terminal box type "T" in the box (□) within the model name.

•Enter the gear ratio in the box (\Box) within the model name.

•A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

•To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 10 N·m.

<>50 Hz																					
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2J 5IK40GN-CW2J 5IK40GN-CW2E (Single-phase 220 VAC)	5GN⊡S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
5IK40GN-CW2 (Single-phase 230 VAC) 5IK40GN-SW2	∫ 5GN⊡S	0.73	0.87	1.2	1.5	1.8	2.2	3.0	3.6	4.4	5.5	6.6	7.9	9.9	10	10	10	10	10	10	10
5IK40GN-UT4	/ 5GN□S	0.77	0.92	1.3	1.5	1.9	2.3	3.2	3.8	4.6	5.7	6.9	8.3	10	10	10	10	10	10	10	10
◇60 Hz																				Uni	it = N•m
Model	Speed	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10

Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK40GN-AW2UJ 5IK40GN-AW2U 5IK40GN-CW2UJ 5IK40GN-CW2E 5IK40GN-SW2	5GN⊡S	0.63	0.76	1.1	1.3	1.6	1.9	2.6	3.2	3.8	4.7	5.7	6.8	8.6	10	10	10	10	10	10	10

Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

Permissible Load Inertia J for Gearhead

→ Page 107

Dimensions (Unit = mm)

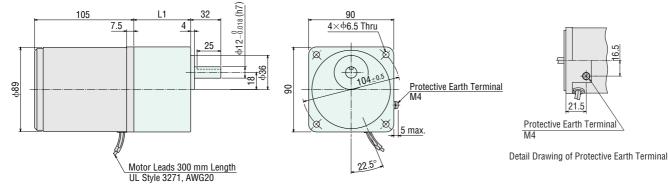
Mounting screws are included with gearheads.

◇Lead Wire Type ① Mass: Motor 2.5 kg Gearhead 1.5 kg

Motor Model	Gearhead Model	Gear Ratio	L1
5IK40GN-AW2 5IK40GN-CW2		3~18	42
5IK40GN-CW2	5GN_S	25~180	60

 \blacksquare Specify the type of the capacitor to be included by entering ${\bf J}, {\bf U}$ or ${\bf E}$ in the box ()) within the model name.

Enter the gear ratio in the box (\Box) within the model name.



15 W

1 W / 3 W

^

M 06

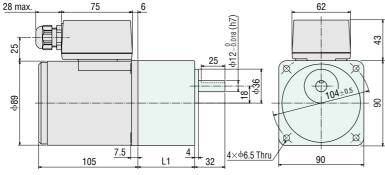
2-Pole, High-Speed

 $40 \text{ W} \sim 150 \text{ W}$

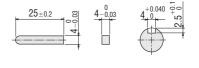
Motor Model	Gearhead Model	Gear Ratio	L1
5IK40GN-AW2T 5IK40GN-CW2T	5GN∏S	3~18	42
5IK40GN-SW2T 5IK40GN-UT4	SGN_5	25~180	60

 \bullet Specify the type of the capacitor to be included by entering ${\bf J}, {\bf U}$ or ${\bf E}$ in the box () within the model name.

Enter the gear ratio in the box (\Box) within the model name.



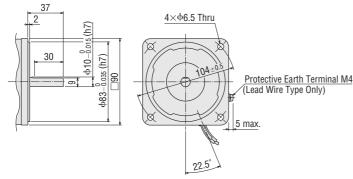
♦ Key and Key Slot (The key is included with the gearhead)



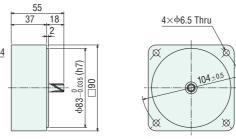
 \bullet Use cable with a diameter of $\varphi 6 \sim \varphi 12$ mm.

$\diamondsuit \mathsf{Shaft}$ Section of Round Shaft Type

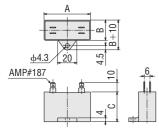
The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



◇Decimal Gearhead Can be connected to GN pinion shaft type. 5GN10XS Mass: 0.6 kg



(Included with single-phase motors)



Model Upper Model Name: Pinion Shaft Type Lower Model Name (): Round Shaft Type		Capacitor Model	A	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
5IK40GN-AW2J (5IK40A-AW2J)	5IK40GN-AW2TJ (5IK40A-AW2TJ)	CH110CFAUL2	58	21	31	50	
5IK40GN-AW2U (5IK40A-AW2U)	5IK40GN-AW2TU (5IK40A-AW2TU)	CH90CFAUL2	48	22.5	31.5	45	Included
5IK40GN-CW2J (5IK40A-CW2J)	5IK40GN-CW2TJ (5IK40A-CW2TJ)	CH30BFAUL	58	21	31	50	Included
5IK40GN-CW2E (5IK40A-CW2E)	5IK40GN-CW2TE (5IK40A-CW2TE)	CH23BFAUL	48	21	31	40	

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

L	ad Wire Type		Terminal Box Type
5IK40GN-AW2 5IK40GN-CW2	5IK40GN-SW2	2 5IK40GN-AW2 5IK40GN-CW2	
Clockwise	PE Clockwise	Clockwise Clockwise	Motor Clockwise CW L1(R) Motor L2(S) Motor L3(T) PE
Counterclockwise	Counterclockwise To change the rotation direc change any two connections R, S and T.		Counterclockwise To change the rotation direction, change any two connections bet U, V and W.
Low White Motor Now Black Motor	¢ PE	Lo- No- Capacitor PE	Motor

PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

World K Series

1 W / 3 W

W 9

High-Speed Type

Right-Angle Gearheads

Accessories

(RoHS) Induction Motors 60 W Frame Size: 90 mm





(Gearhead sold separately)

Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108



Specifications – Continuous Rating (RoHS)

Model Output Starting Torque Rated Torque Voltage Frequency Current Rated Capacitor Upper Model Name: Pinion Shaft Type Lower Model Name (): Round Shaft Type Power Speed Lead Wire Type Terminal Box Type W VAC Hz А mN∙m mN∙m r/min μF Dimension (1) Dimension (2) 5IK60GE-AW2J 5IK60GE-AW2TJ 50 1.20 490 1200 TP Single-Phase 100 60 320 20 (5IK60A-AW2J) (5IK60A-AW2TJ) 60 1.19 405 1450 5IK60GE-AW2U 5IK60GE-AW2TU Single-Phase 110 1.09 405 TP 60 60 320 1450 18 (5IK60A-AW2U) (5IK60A-AW2TU) Single-Phase 115 1.10 5IK60GE-CW2J 5IK60GE-CW2TJ 50 0.57 490 1200 Single-Phase 200 TP 60 320 5.0 (5IK60A-CW2J) (5IK60A-CW2TJ) 60 0.65 405 1450 0.55 490 1200 50 Single-Phase 220 0.54 5IK60GE-CW2E 5IK60GE-CW2TE 60 405 1450 TP 60 320 4.0 (5IK60A-CW2E) (5IK60A-CW2TE) 490 50 0.57 1200 Single-Phase 230 0 54 405 1450 60 50 0.50 600 450 1300 Three-Phase 200 5IK60GE-SW2 5IK60GE-SW2T 60 0.43 500 380 1550 TP 60 (5IK60A-SW2) (5IK60A-SW2T) Three-Phase 220 60 0.45 500 380 1600 Three-Phase 230 60 0.46 500 380 1600 5IK60GE-UT4F TP 60 Three-Phase 400 50 0.25 550 470 1250 (5IK60A-UT4F*)

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

* Conforms to EN/IEC standards only. Bears the CE Marking.

Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(TP: Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting.

Product Line

Motor (RoHS)

Type	Mo	del			
туре	Pinion Shaft Type	Round Shaft Type			
	5IK60GE-AW2J	5IK60A-AW2J			
	5IK60GE-AW2U	5IK60A-AW2U			
Lead Wire	5IK60GE-CW2J	5IK60A-CW2J			
	5IK60GE-CW2E	5IK60A-CW2E			
	5IK60GE-SW2	5IK60A-SW2			
	5IK60GE-AW2TJ	5IK60A-AW2TJ			
	5IK60GE-AW2TU	5IK60A-AW2TU			
Terminal Box	5IK60GE-CW2TJ	5IK60A-CW2TJ			
Terminal box	5IK60GE-CW2TE	5IK60A-CW2TE			
	5IK60GE-SW2T	5IK60A-SW2T			
	5IK60GE-UT4F	5IK60A-UT4F			

Gearhead/Right-Angle Gearhead (Sold Separately) (Rolls)

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE_S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE_RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE_RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

ullet Enter the gear ratio in the box (\Box) within the model name.

Gearmotor – Torque Table

Gearheads and decimal gearheads are sold separately.

●Enter the code that represents the terminal box type "T" in the box (□) within the model name.

•Enter the gear ratio in the box (\Box) within the model name.

•A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

•To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

⊘50 Hz																				Uni	it = N•m
Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2_J 5IK60GE-CW2_J 5IK60GE-CW2_E	5GE_S	1.2	1.4	2.0	2.4	3.0	3.6	4.5	5.4	6.4	8.1	9.7	11.6	16.2	19.4	20	20	20	20	20	20
5IK60GE-SW2	∕ 5GE⊡S	1.1	1.3	1.8	2.2	2.7	3.3	4.1	4.9	5.9	7.4	8.9	10.7	14.9	17.8	19.9	20	20	20	20	20
5IK60GE-UT4F	∕ 5GE⊡S	1.1	1.4	1.9	2.3	2.9	3.4	4.3	5.1	6.2	7.8	9.3	11	16	19	20	20	20	20	20	20
⊘60 Hz																				Uni	it = N∙m
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK60GE-AW2_J 5IK60GE-AW2_U 5IK60GE-CW2_J 5IK60GE-CW2_E	5GE	0.98	1.2	1.6	2.0	2.5	3.0	3.7	4.4	5.3	6.7	8.0	9.6	13.4	16.0	17.9	20	20	20	20	20

1.5 1.8 2.3 2.8 3.5 4.2 5.0 6.3 7.5 9.0 12.5 15.0 16.8

20 20 20 20 20

Permissible Overhung Load and Permissible Thrust Load

0.92 1.1

Motor (Round shaft type) → Page 107 Gearhead → Page 107

Permissible Load Inertia J for Gearhead

5GE S

→ Page 107

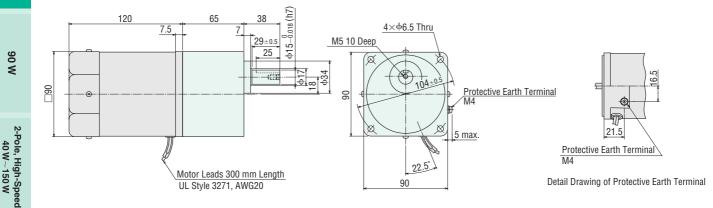
5IK60GE-SW2

Dimensions (Unit = mm)

Mounting screws are included with gearheads.

$\diamondsuit \mbox{Lead}$ Wire Type (1)

Mass: Motor 2.7 kg Gearhead 1.5 kg



1W/3W

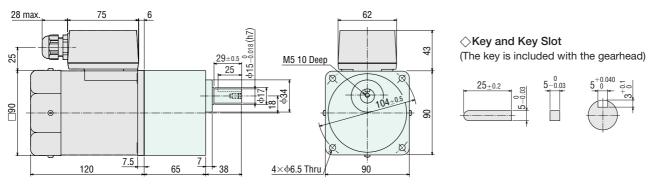
M9

15 W

25 W

40 W

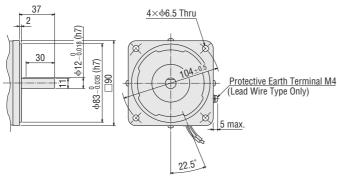
Orerminal Box Type ②
 Mass: Motor 2.8 kg
 Gearhead 1.5 kg



• Use cable with a diameter of $\phi 6 \sim \phi 12$ mm.

\diamondsuit Shaft Section of Round Shaft Type

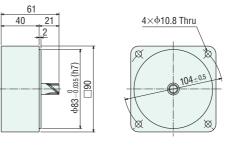
The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



◇Decimal Gearhead

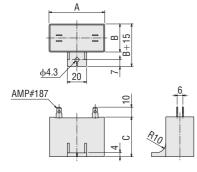
Can be connected to **GE** pinion shaft type. **5GE10XS**

Mass: 0.6 kg



◇Capacitor

(Included with single-phase motors)



Model Upper Model Name: Pinion Shaft Type Lower Model Name (): Round Shaft Type		Capacitor Model	A	В	С	Mass (g)	Capacitor Cap
Lead Wire Type	Terminal Box Type						
5IK60GE-AW2J (5IK60A-AW2J)	5IK60GE-AW2TJ (5IK60A-AW2TJ)	CH200CFAUL2	58	29	41	95	
5IK60GE-AW2U (5IK60A-AW2U)	5IK60GE-AW2TU (5IK60A-AW2TU)	CH180CFAUL2	58	29	41	95	la aludad
5IK60GE-CW2J (5IK60A-CW2J)	5IK60GE-CW2TJ (5IK60A-CW2TJ)	CH50BFAUL	58	29	41	85	Included
5IK60GE-CW2E (5IK60A-CW2E)	5IK60GE-CW2TE (5IK60A-CW2TE)	CH40BFAUL	58	23.5	37	70	

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

Lead W	ire Type	Terminal	Вох Туре		
5IK60GE-AW2 5IK60GE-CW2	5IK60GE-SW2	5IK60GE-AW2T 5IK60GE-CW2T	5IK60GE-SW2T 5IK60GE-UT4F		
Clockwise	Clockwise L1(R) L2(S) Black Motor PE	Clockwise	Clockwise L1(R) L2(S) L3(T) PE		
Counterclockwise	Counterclockwise To change the rotation direction, change any two connections between R, S and T.	Counterclockwise	Counterclockwise To change the rotation direction, change any two connections between U, V and W.		
Lo White Red Motor No Black Department Capacitor		Lo No Capacitor Capacitor			

PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

1 W / 3 W

High-Sp

eed Type

Right-Angle Gearheads

RoHS Induction Motors 90 W Frame Size: 90 mm



Right-angle gearheads (hollow shaft or solid shaft) can be combined. Right-Angle Gearheads → Page 108



Specifications – Continuous Rating (RoHS)

Upper Model Name:	Model Upper Model Name: Pinion Shaft Type Lower Model Name (): Round Shaft Type		Voltage	Frequency	Current	Starting Torque	Rated Torque	Rated Speed	Capacitor	
Lead Wire Type Dimension ①	Terminal Box Type Dimension ②	w	W VAC		A	mN∙m	mN∙m	r/min	μF	
TP 5IK90GE-AW2J	5IK60GE-AW2TJ	90	Single-Phase 100	50	1.64	450	700	1250	28	
(5IK90A-AW2J)	(5IK90A-AW2TJ)	90	Sillyle-Fliase 100	60	1.67	430	585	1500	20	
TP 5IK90GE-AW2U	5IK90GE-AW2TU	90	Single-Phase 110	60	1.45	450	585	1500	20	
(5IK90A-AW2U)	(5IK90A-AW2TU)	90	Single-Phase 115	60	1.44	400	202	1500	20	
TP 5IK90GE-CW2J	5IK90GE-CW2TJ	90 Single-Pha	Cingle Dhoos 200	50	0.80	450	730	1200	7.0	
(5IK90A-CW2J)	(5IK90A-CW2TJ)	90	90 Single-Phase 200	60	0.93	430	605	1450	7.0	
			Cingle Dhose 000	50	0.74		730	1200		
5IK90GE-CW2E	5IK90GE-CW2TE	00	90	Single-Phase 220	60	0.82	450	605	1450	6.0
(5IK90A-CW2E)	(5IK90A-CW2TE)	90		50	0.76	450	730	1200	0.0	
			Single-Phase 230	60	0.81		605	1450		
			Three Dhees 200	50	0.64	850	680	1300		
5IK90GE-SW2	5IK90GE-SW2T	90	Three-Phase 200	60	0.59	700	570	1550		
(5IK90A-SW2)	(5IK90A-SW2T)	90	Three-Phase 220	60	0.60	700	570	1600	-	
			Three-Phase 230	60	0.61	700	570	1600		
. –	5IK90GE-UT4F [*] (5IK90A-UT4F [*])	90	Three-Phase 400	50	0.35	850	700	1250	-	

• The J, U and E at the end of the model name indicate that the unit includes a capacitor. These letters are not listed on the motor nameplate.

When the motor is approved under various safety standards, the model name on the nameplate is the approved model name.

 $\ensuremath{\ast}$ Conforms to EN/IEC standards only. Bears the CE Marking.

Note:

A three-phase 400 VAC motor cannot be used with an inverter. Using them together may lead to deterioration of the motor wiring insulation and damage the products.

(P): Contains a built-in thermal protector. If a motor overheats for any reason, the thermal protector is opened and the motor stops.

When the motor temperature drops, the thermal protector closes and the motor restarts. Be sure to turn the motor off before inspecting,

Product Line

Motor (Rolls)

Type	Ma	del
туре	Pinion Shaft Type	Round Shaft Type
	5IK90GE-AW2J	5IK90A-AW2J
	5IK90GE-AW2U	5IK90A-AW2U
Lead Wire	5IK90GE-CW2J	5IK90A-CW2J
	5IK90GE-CW2E	5IK90A-CW2E
	5IK90GE-SW2	5IK90A-SW2
	5IK90GE-AW2TJ	5IK90A-AW2TJ
	5IK90GE-AW2TU	5IK90A-AW2TU
Terminal Box	5IK90GE-CW2TJ	5IK90A-CW2TJ
Terrininar Dux	5IK90GE-CW2TE	5IK90A-CW2TE
	5IK90GE-SW2T	5IK90A-SW2T
	5IK90GE-UT4F	5IK90A-UT4F

• Gearhead/Right-Angle Gearhead (Sold Separately) (RoHS)

Туре	Gearhead Model	Gear Ratio
Long Life/ Parallel Shaft	5GE S	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
	5GE10XS (Decima	l gearhead)
Right-Angle/ Hollow Shaft	5GE_RH	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180
Right-Angle/ Solid Shaft	5GE□RA	3, 3.6, 5, 6, 7.5, 9, 12.5, 15, 18, 25, 30, 36, 50, 60, 75, 90, 100, 120, 150, 180

• Enter the gear ratio in the box (
) within the model name.

Gearmotor – Torque Table

Gearheads and decimal gearheads are sold separately.

•Enter the code that represents the terminal box type "T" in the box (
) within the model name.

•Enter the gear ratio in the box (\Box) within the model name.

A colored background indicates gear shaft rotation in the same direction as the motor shaft, while the others rotate in the opposite direction.

•The speed is calculated by dividing the motor's synchronous speed (50 Hz: 1500 r/min, 60 Hz: 1800 r/min) by the gear ratio.

The actual speed is 2 - 20% less than the displayed value, depending on the size of the load.

To reduce the speed beyond the gear ratio in the table, attach a decimal gearhead (gear ratio: 10) between the gearhead and the motor. In that case, the permissible torque is 20 N·m.

Unit = N•m

♦ 50 Hz

Model	Speed r/min	500	416	300	250	200	166	120	100	83	60	50	41	30	25	20	16	15	12.5	10	8.3
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2_J	/ 5GE_S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	11.6	13.9	16.6	20	20	20	20	20	20	20	20
5IK90GE-CW2UJ 5IK90GE-CW2UE	SGE□S	1.8	2.1	3.0	3.5	4.4	5.3	6.7	8.0	9.6	12.0	14.5	17.3	20	20	20	20	20	20	20	20
5IK90GE-SW2	/ 5GE□S	1.7	2.0	2.8	3.3	4.1	5.0	6.2	7.4	8.9	11.2	13.5	16.2	20	20	20	20	20	20	20	20
5IK90GE-UT4F	/ 5GE□S	1.7	2.0	2.8	3.4	4.3	5.1	6.4	7.7	9.2	12	14	17	20	20	20	20	20	20	20	20
◇60 Hz																				Uni	it = N•m

<>60 Hz

*																					
Model	Speed r/min	600	500	360	300	240	200	144	120	100	72	60	50	36	30	24	20	18	15	12	10
Motor/ Gearhead	Gear Ratio	3	3.6	5	6	7.5	9	12.5	15	18	25	30	36	50	60	75	90	100	120	150	180
5IK90GE-AW2J 5IK90GE-AW2U	∕ 5GE⊡S	1.4	1.7	2.4	2.8	3.6	4.3	5.3	6.4	7.7	9.7	11.6	13.9	19.3	20	20	20	20	20	20	20
5IK90GE-CW2J 5IK90GE-CW2E	∕ 5GE⊡S	1.5	1.8	2.5	2.9	3.7	4.4	5.5	6.6	7.9	10.0	12.0	14.4	20	20	20	20	20	20	20	20
5IK90GE-SW2	∕ 5GE⊡S	1.4	1.7	2.3	2.8	3.5	4.2	5.2	6.2	7.5	9.4	11.3	13.5	18.8	20	20	20	20	20	20	20

40 W

00 W

Permissible Overhung Load and Permissible Thrust Load

Motor (Round shaft type) → Page 107 Gearhead → Page 107

Permissible Load Inertia J for Gearhead

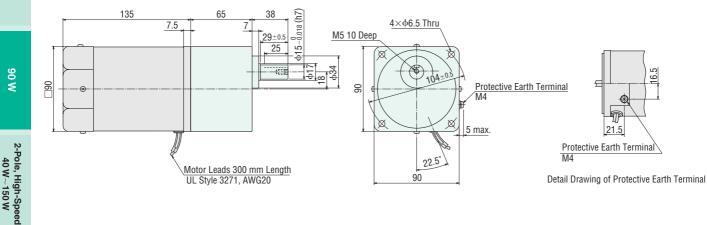
→ Page 107

Dimensions (Unit = mm)

Mounting screws are included with gearheads.

 \Diamond Lead Wire Type (1) Mass: Motor 3.2 kg

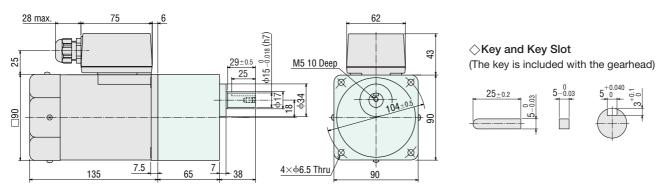
Gearhead 1.5 kg



1W/3W

M9

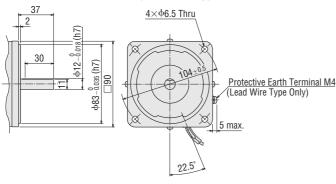
Cerrinal Box Type (2) Mass: Motor 3.3 kg Gearhead 1.5 kg



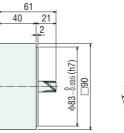
• Use cable with a diameter of $\phi 6 \sim \phi 12$ mm.

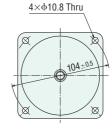
$\diamondsuit \mathsf{Shaft}$ Section of Round Shaft Type

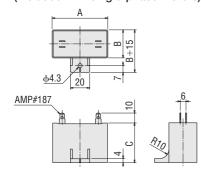
The mass and motor's dimensions (excluding the shaft section) are the same as those of the pinion shaft type.



◇Decimal Gearhead Can be connected to GE pinion shaft type. 5GE10XS Mass: 0.6 kg







Mc Upper Model Name Lower Model Name	Capacitor Model	A	В	С	Mass (g)	Capacitor Cap		
Lead Wire Type	Terminal Box Type							
5IK90GE-AW2J (5IK90A-AW2J)	5IK90GE-AW2TJ (5IK90A-AW2TJ)	CH280CFAUL2	58	35	50	140		
5IK90GE-AW2U (5IK90A-AW2U)	5IK90GE-AW2TU (5IK90A-AW2TU)	CH200CFAUL2	58	29	41	95	Included	
5IK90GE-CW2J (5IK90A-CW2J)	5IK90GE-CW2TJ (5IK90A-CW2TJ)	CH70BFAUL	58	35	50	130	Included	
5IK90GE-CW2E (5IK90A-CW2E)	5IK90GE-CW2TE (5IK90A-CW2TE)	CH60BFAUL	58	29	41	85		

Connection Diagrams

•The direction of motor rotation is as viewed from the shaft end of the motor. CW represents the clockwise direction, while CCW represents the counterclockwise direction.

•Connection diagrams are also valid for the equivalent round shaft type.

●Specify the type of the capacitor to be included by entering J, U or E in the box (□) within the model name.

Lead V	/ire Type	Terminal Box Type						
5IK90GE-AW2 5IK90GE-CW2	51K90GE-5W2	5IK90GE-AW2T□ 5IK90GE-CW2T□	5IK90GE-SW2T 5IK90GE-UT4F					
Clockwise White Ked No Capacitor	Clockwise L1(R) L2(S) L3(T) CW CW CW CW CW CW CW CW CW CW	Clockwise	Clockwise					
Counterclockwise	Counterclockwise - To change the rotation direction, change any two connections between R, S and T.	Counterclockwise	Counterclockwise To change the rotation direction, change any two connections between U, V and W.					
Low White Red Now Black Motor Capacitor		Lo 22 No UD Motor Capacitor PE						

PE: Protective Earth

Note:

Change the direction of single-phase motor rotation only after bringing the motor to a stop.

If an attempt is made to change the direction of rotation while the motor is rotating, motor may ignore reversing command or change its direction of rotation after some delay.

World K Series

1 W / 3 W

W 9

(RoHS) RoHS-Compliant Brake Pack for Standard AC Motors

SB50W

The **SB50W** provides instantaneous stop, forward/ reverse operation, electromagnetic brake control and thermal protector open detection functions integrated into one unit. These brake packs can sense when the thermal protector is opened, further ensuring the safety of your equipment.

Supports Motors with 1 to 90 W Output

The **SB50W** can be used with induction, reversible, electromagnetic brake and watertight, dust-resistant motors with an output range of 1 to 90 W.

Switchable Sink/Source Logic

Select the sink mode or source mode for the input/output circuit. You can change the setting at any time.

Features

Four Functions in One Integrated Unit

The **SB50W** provides instantaneous stop, forward/reverse operation, electromagnetic brake control and thermal protector open detection functions*.

* Thermal protector open detection function

(Available only when combined with a motor having a built-in thermal protector) When the motor's thermal protector (overheat protection device) is activated, the **SB50W** outputs an alarm signal and automatically cuts the power supply to the motor. The motor will not restart by itself, even after the temperature drops and the thermal protector recovers, until the power is cycled. Possible to reset the alarm through external signals.

Wide Voltage Range of 100 to 230 VAC

The **SB50W** covers a single-phase voltage range of 100 to 230 VAC \pm 10%, 50/60 Hz, accommodating all of the world's key voltage specifications.

Conforms to Safety Standards

This is the world first brake pack which conforms to safety standards. The CE marking is used in accordance with the EMC directives and low voltage directives.

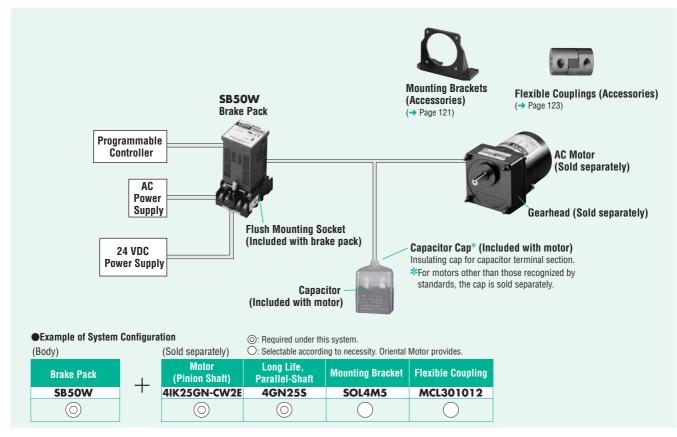
Safety Standards and CE Marking

Standards	Certification Body	Standards File No.	CE Marking		
UL 508	UL	E91291			
CSA C22.2 No.14	UL	E91291	Low Voltage Directives		
EN 50178	Conform to P	EMC Directives			
EN 60950-1	Comonin to I	Conform to EN Standards			

 The EMC value changes according to the wiring and layout. Therefore, the final EMC level must be checked with the brake pack incorporated in the user's equipment.



System Configuration



• The system configuration shown above is an example. Other configurations are available.

Specifications (RoHS)

Spe	Specifications (RoHS)									
Model	Power Supply Voltage	Frequency	Applicable Motor Output Voltage	Functions	Power Source for Control	Input Signals	Output Signals	Braking Current Duration		
SB50W	Single-phase 100-230 VAC ±10%	50/60 Hz	1 W~90 W	Instantaneous stop Forward/reverse operation Electromagnetic brake control (Electromagnetic brake motors) Thermal protector open detection (Alarm output) Sink/Source logic switch	24 VDC ±10%	CW, CCW, FREE/ALARM-RESET Input specifications Photocoupler input Input impedance 4.7 k Ω 24 VDC \pm 10%	ALARM Output specifications Open collector output External use conditions 26.4 VDC max. 10 mA min.	Approximately 0.2~0.4 seconds		

General Specifications

Item	Specifications		
Insulation Resistance	100 MΩ or more when measured by a 500 VDC megger between the power supply input terminal and the signal input terminal after rated motor operation under normal ambient temperature and humidity.		
Dielectric Strength Sufficient to withstand 3.0 kV at 50 Hz or 60 Hz applied between the power supply input terminal and the signal input terminal for 1 minute after rated moperation under normal ambient temperature and humidity.			
Ambient Temperature	$0^{\circ}C \sim + 40^{\circ}C$ (nonfreezing)		
Ambient Humidity	85% or less (noncondensing)		
Degree of Protection	IP10		

Applicable Products

World K Series 1 W∼90 W	Induction Motors* Reversible Motors Electromagnetic Brake Motors
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* Except for 2-pole type

Braking Current

When a motor is stopped suddenly, a large half-wave rectified current flows through the motor for approximately 0.2 to 0.4 seconds. When connecting a circuit breaker, fuse or transformer, refer to the table below for the braking current (peak value) and select its current capacity.

Males O. J. J. Dr	Braking Current	[A] (Peak Value)
Motor Output Power	100/110/115 VAC	200/220/230 VAC
1 W	1.0	0.3*
6 W	1.5	1.0
15 W	4.5	2.5
25 W	7.5	4.0
40 W	12	7.0
60 W	18	8.5
90 W	26	17

* Can be used only for 200 VAC.

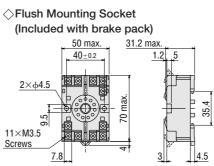
High-Speed Type

Accessories

World K Series

Dimensions (Unit = mm)

SB50W Mass: 0.1 kg

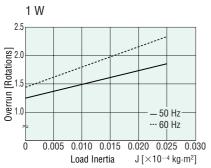


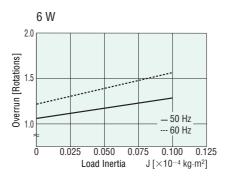
◇Flush Mounting Socket Panel Cut-Out 2×64.5 Mounting Holes

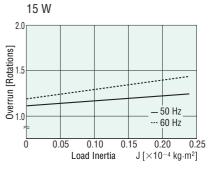


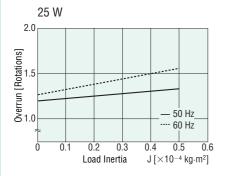
Braking Characteristics (Reference Values)

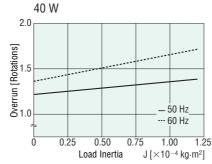
Induction Motors

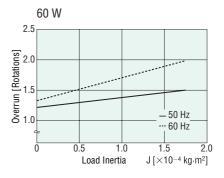


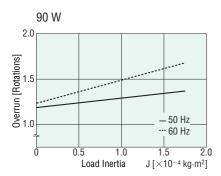


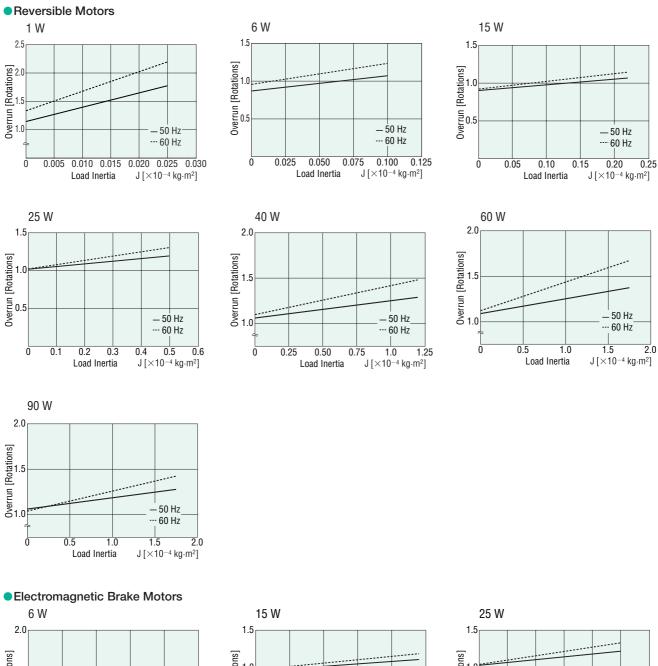


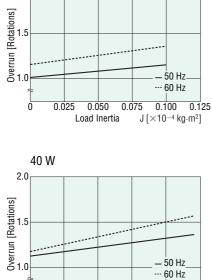












0

0.25

0.50

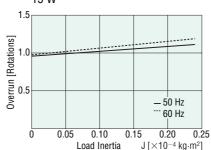
Load Inertia

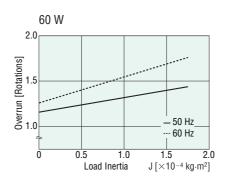
0.75

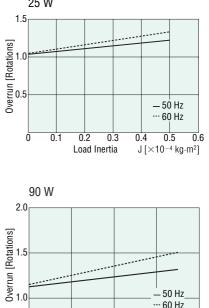
1.00

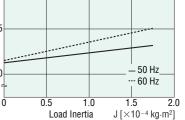
J [×10⁻⁴ kg·m²]

1.25









Accessories

World K Series

Induction Motors

2-Pole, High-Speed Type

Reversible Motors

Electromagnetic Brake Motors

Torque Motors

Right-Angle Gearheads

Brake Pack SB50W

Connection and Operation

Names and Functions of Brake Pack Parts



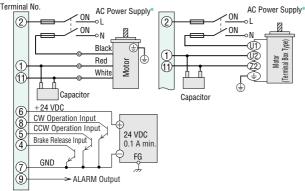
No.	Name	Factory Setting	Functions
1	POWER Indicator (Green)	-	Lit when 24 VDC is supplied.
2	ALARM Indicator (Red)	-	Lit when the ALARM output is "OFF."
3	Motor Output Select Switch	60-90 W	Used to set the motor output.
4	SINK/SOURCE Select Switch	SINK	Used to switch between Sink/Source for the control signal output.

Connection Diagrams

The wiring diagram is for when the SINK/SOURCE select switch is set to the "SINK" side.

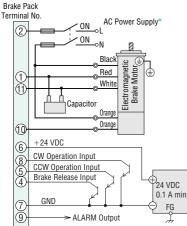
◇Induction Motors/Reversible Motors

Brake Pack



*Single-phase 100/110/115 VAC, single-phase 200/220/230 VAC

⇒Electromagnetic Brake Motors



*Single-phase 100/110/115 VAC, single-phase 200/220/230 VAC

Terminal Arrangement for Flush Mounting Socket

Terminal No.	Signal Name	Description
1	Motor/Capacitor	Connect the motor and capacitor.
2	AC Power Input (L)	Single-phase 100–115 VAC Single-phase 200–230 VAC
3	NC	Not used. Leave this terminal unconnected.
() *1	Brake Release Input ^{*2}	Not an instantaneous stop but a natural stop
4 ^{*1}	ALARM-RESET Input	Reset ALARM Output.
5	CCW Operation Input ^{#3}	Motor runs in the CCW direction during "ON."
6	DC Power Input	+24 VDC input
7	GND	GND
8	CW Operation Input	Motor runs in the CCW direction during "ON."
9	ALARM Output	Turns "OFF" when the motor's thermal protector is "open."
10	Electromagnetic Brake*4	Connect to the electromagnetic brake.
11	Motor/Capacitor	Connect the motor and capacitor.

*1 Functions as a brake release input during normal operation, and as an ALARM-RESET input when the ALARM output is OFF.

- *2 Releases the electromagnetic brake for electromagnetic brake motors.
- *3 Not used with an induction motor with four lead wires.

***4** Only for electromagnetic brake motors.

Notes:

• The input-signal voltage is 24 VDC±10% and 0.1 A or more.

Minimize the length of the motor cable and the input/output signal cable to reduce EMI.
 Ites a cable of AWC18 (0.75 mm²) or more in diameter for the mater cable and paid

 Use a cable of AWG18 (0.75 mm²) or more in diameter for the motor cable and power cable.

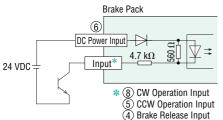
Be sure to connect the GND terminal to GND (negative side) of the external controller, or the unit will not operate.

I/O Signal Circuit

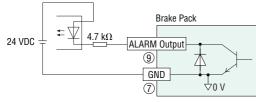
The I/O signal circuit can be switched between the sink mode and source mode using the sink/source select switch on the brake pack. The factory setting is the sink mode.

Sink Logic

Input Circuit

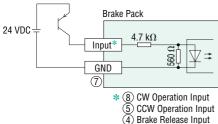


Output Circuit

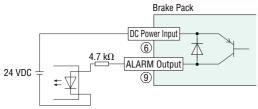


OSource Logic Contract Con

Input Circuit



Output Circuit



Timing Chart

-Natural Stop

1 y pe

- Braking _Braking Г ſ Stop Stop Operation Operation Operation AC Power Supply DC Power Supply ٥FI CW Operation Input* 01 CCW Operation Input* Brake Release Input Electromagnetic Brake Movement Holding Clock CW CW CW Moto Rotation Cou CCW CCW
- *1 Turn on CW operation input, CCW operation input, and brake release input after turning on AC power.
 - The motor does not operate if they are input ahead of AC power.
- The ALARM indicator will light and ALARM output will switch to "OFF."
- *2 The brake release input becomes ALARM-RESET input when the ALARM output is OFF.
- *3 Only for electromagnetic brake motors
- *4 The induction motor will not accommodate instantaneous forward/reverse switching.

◇CW Operation Input

Turning the CW operation signal to "ON" causes the motor's output shaft to turn in the CW direction. Turning it to "OFF" triggers an instantaneous stop.

♦ CCW Operation Input

Turning the CCW operation signal to "ON" causes the motor's output shaft to turn in the CCW direction. Turning it to "OFF" triggers an instantaneous stop.

If both the CW and CCW operation signals are simultaneously turned to "ON," the CW operation signal will take priority. Therefore, the wiring must be changed with an induction motor having four lead wires.

◇Brake Release Input [ALARM-RESET Input]

Functions as a brake release input during normal operation, and as an ALARM-RESET input when the ALARM output is OFF.

•When normal: [Brake Release Input]

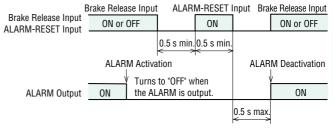
Turning the brake release signal to "ON" disables both the electronic brake and electromagnetic brake. When the CW and CCW operation signals are turned to "OFF," the motor operates via inertial force before coming to a natural stop. When the motor is stationary, the electromagnetic brake is not activated, so the motor's output shaft can be moved freely.

Turning the brake release signal to "OFF" (or leaving the signal unconnected) and turning both CW and CCW operation signals to "OFF" will activate the electronic brake and electromagnetic brake, bringing the motor to an instantaneous stop. Once the motor stops, the electronic brake will release automatically. However, the electromagnetic brake will continue to operate and hold the load.

•When ALARM output is OFF: [ALARM-RESET Input]

When ALARM output is turned OFF, turn all input signals "OFF" and input 0.5 seconds or more for ALARM-RESET input.

Wait at least 0.5 seconds after turning the ALARM-RESET input OFF before restarting operation.



It is also possible to deactivate the alarm by turning off the power and turning it on again. Turn off the DC or AC power, and turn all input signals "OFF" before turning on the power again.

◇ALARM Output (Thermal Protector Open Detection)

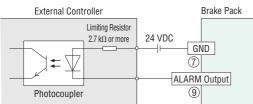
Since the **SB50W** ALARM output function detects the operations of the thermal protector, the current flowing in the motor is

- monitored. Operation occurs under the following conditions:When the thermal protector built-in to the motor is opened
- •When there is improper connection/disconnection of the power supply cable and motor cable
- •When the input signal is turned "ON" before the AC power is turned on
- •When the AC power is turned off while the motor is in operation or while it is stopped

In the above conditions, state of the **SB50W** ALARM output is "OFF," the ALARM indicator lamp (red) on the panel lights up, and power supply to the motor is stopped.

With electromagnetic brake motors, the brake is activated in order to hold the load in position.

* When the DC power is turned on, the alarm indication lamp lights up instantaneously, but this is not an abnormality.



Use a power source of 26.4 VDC or less, and limit the output current to 10 mA or less.

Operating/Braking Repetition Cycle

The repeated operation and braking of a motor will cause about a temperature increase in the motor and brake pack, thereby limiting the continuous operating time.

Observe the repetition cycle given in the table below for the operation and braking of the motor. The motor may generate heat depending on the conditions in which it is driven. Ensure that the temperature of the motor case does not exceed 90°C.

Motor Output Power	Repetition Cycle
1 W~25 W	2 seconds or more
$40 \text{ W}{\sim}90 \text{ W}$	4 seconds or more

(A repetition cycle of two seconds represents operation for one second and stopping for one second.)

Accessories

Motor/Gearhead Mounting Brackets (RoHS)

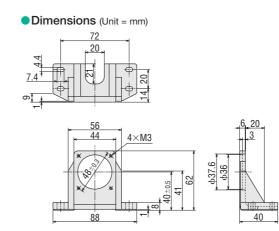
Mounting Brackets for attaching and securing a motor and gearhead. They are high-strength type, which can be used with high power motors/gearheads. These brackets come with tapped holes. To mount the motor and gearhead, simply fasten with the screws provided to the gearhead. To mount the motor alone, mounting screws must be provided separately.

Please note that these mounting brackets cannot be used with the following products. • Right-angle gearheads (RH type, RA type)

For Motor Frame Size: 42 mm

Model: SOLOM3 Mass: 85 g Material: Aluminum

OGN Gearhead Motor with the flame size of 242 mm

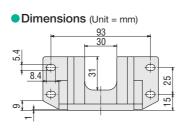


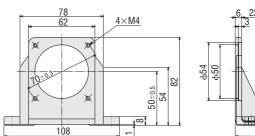
For Motor Frame Size: 60 mm

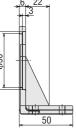
Model: SOL2M4

Mass: 135 g Material: Aluminum

2GN Gearhead Motor with the flame size of □60 mm







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eed Type

World K Series

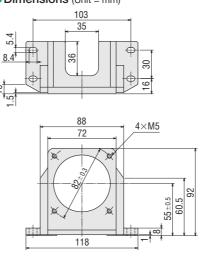
For Motor Frame Size: 70 mm

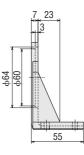
Model: SOL3M5

Mass: 175 g Material: Aluminum

3GN Gearhead Motor with the flame size of \Box 70 mm

Dimensions (Unit = mm)



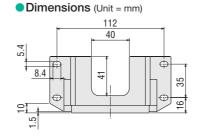


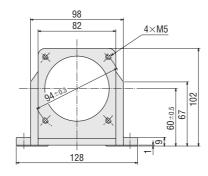
For Motor Frame Size: 80 mm

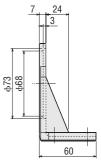
Model: SOL4M5

Mass: 210 g Material: Aluminum

4GN Gearhead Motor with the flame size of 280 mm





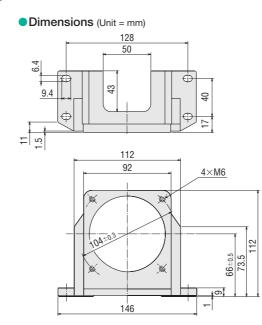


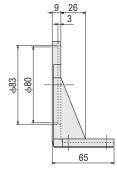
For Motor Frame Size: 90 mm

Model: SOL5M6

Mass: 270 g Material: Aluminum

5GN Gearhead 5GE Gearhead Motor with the flame size of
90 mm





Capacitor Cap (RoHS)

Insulating cap for capacitor terminal section.

(Example of use)

the capacitor.

be done.

Features

rotation.

by clamping.

UL File No. E56078

Material: Polyvinyl chloride

equipment to be connected.

Our capacitor caps are recognized by UL.

Flexible Couplings (RoHS)



Use a capacitor cap suitable for the external dimensions (A \times B) of

These products are the clamping type couplings to connect between the shaft of motor/gearhead and the shaft of the

Once the motor and gearhead are determined, the coupling can

Couplings come with shaft holes and have standardized

Characteristics are the same for clockwise and counterclockwise

The shaft being driven is not damaged, since shafts are joined

•Easy installation due to a separated hub and sleeve design.

combinations for different diameter shaft holes.

Oil-resistant and electrically insulated.Aluminum alloy construction.

Model	External Dimensions $A \times B$ (Unit = mm)	Applicable Capacitor Model
CHC5835AUL	58×35	CH400300A

Note:

Ten capacitor caps are included in one bag. Order capacitor caps in a multiple of one bag. World K Series

High-Speed Type

CR Circuit for Surge Suppression (RoHS) This product is used to protect the contacts of the relay and/ or switch used for controlling the reversal of direction and the electromagnetic brake.

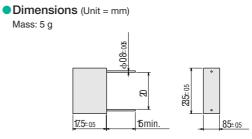
• Model: EPCR1201-2 250 VAC (120 Ω, 0.1 μF)

earhead Model	Coupling Type	
GN⊡K	MCL20	
	MCL20	-

Gearhead Model	Coupling Type	
0GN⊡K	MCL20	
2GN□S	MCL20 MCL30	
3GN□S	MCL30	
4GN_S	MCL30	
4GN⊡RA	MCL40	
5GN ^S	MCL30	
5GN RA	MCL40	
5GE S	MCL40	
5GE RA	MCL55	

* Type of coupling varies depending on condition of the load.





Oriental motor

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